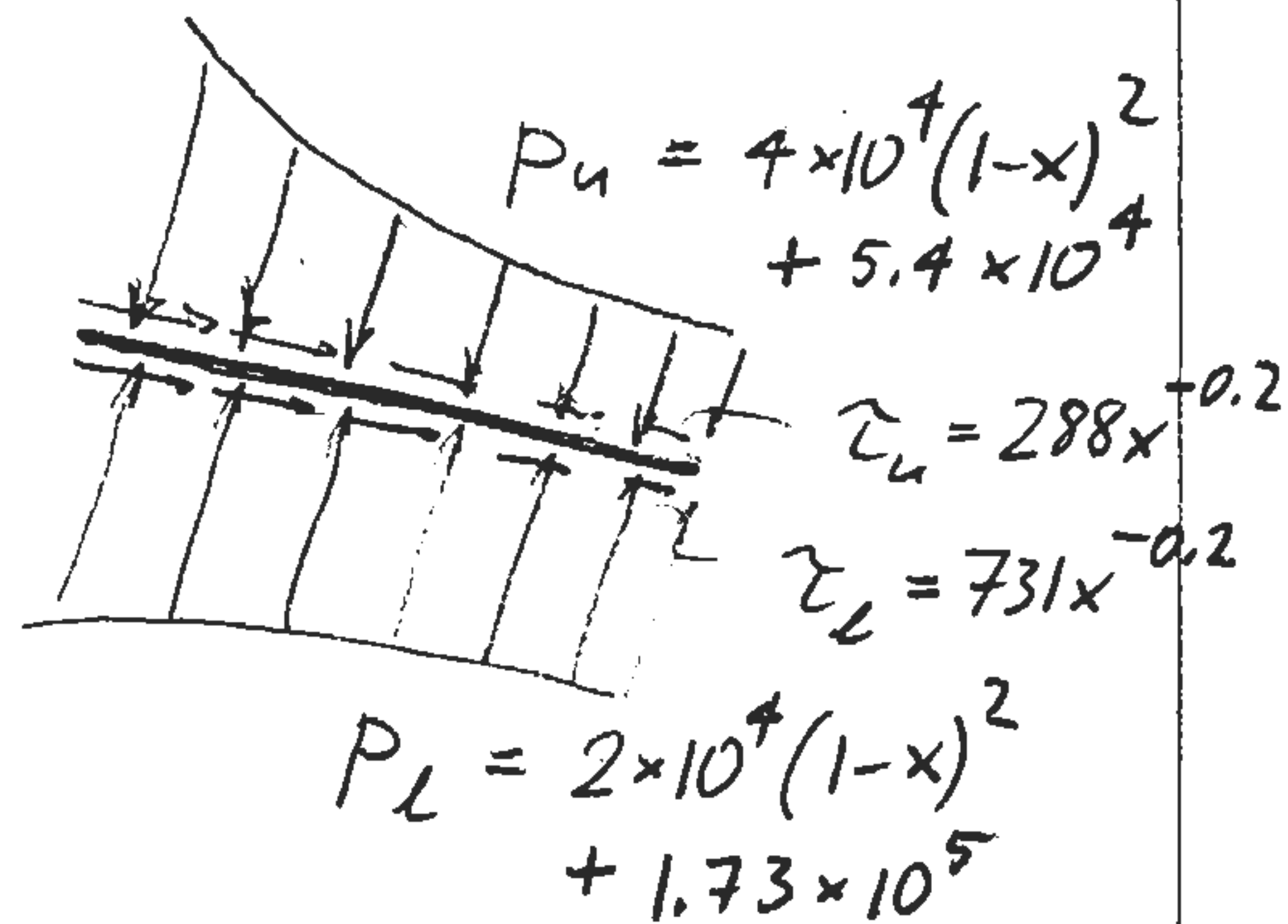


(Anderson 1.4)

Chord  $c = 1$  m

Because airfoil is a flat plate,  
only the net top & bottom forces matter.  
(less stuff to integrate).



$$P_L - P_u = 1.19 \times 10^5 - 2 \times 10^4 (1-x)^2 \text{ Pa}$$

$$\tau_L + \tau_u = 1019 x^{-0.2} \text{ Pa}$$

$$N' = \int_0^{1\text{m}} (P_L - P_u) dx = \left( 1.19 \times 10^5 x - \frac{2}{3} \times 10^4 (1-x)^3 \right) \Big|_0^1$$

$$N' = 1.19 \times 10^5 - 6.67 \times 10^3 = 1.123 \times 10^5 \text{ N/m}$$

$$A' = \int_0^{1\text{m}} (\tau_L + \tau_u) dx = \frac{1}{0.8} 1019 x^{0.8} \Big|_0^1 = 1.274 \times 10^3 \text{ N/m}$$

$$M'_{LE} = \int_0^{1\text{m}} -(P_L - P_u) x dx = \int_0^1 \left( -1.19 \times 10^5 x + 2 \times 10^4 (x - 2x^2 + x^3) \right) dx$$

$$= \left( -\frac{1}{2} 1.19 \times 10^5 x^2 + 2 \times 10^4 \left( \frac{1}{2} x^2 - \frac{2}{3} x^3 + \frac{1}{4} x^4 \right) \right) \Big|_0^1$$

$$= \left( -5.95 \times 10^4 + 2 \times 10^4 \left( \frac{1}{2} - \frac{2}{3} + \frac{1}{4} \right) \right)$$

$$M'_{LE} = -5.783 \times 10^4 \text{ N}$$

$$L' = N' \cos \alpha - A' \sin \alpha = 1.104 \times 10^5 \text{ N/m}$$

$$D' = N' \sin \alpha + A' \cos \alpha = 2.076 \times 10^3 \text{ N/m}$$

$$M'_{c/4} = M'_{LE} + \frac{1}{4} N' = -3.02 \times 10^4 \text{ N}$$

$$x_{cp} = -M'_{LE} / N' = 0.515 \text{ m}$$

Given:  $D = f(\alpha, \rho, V, \mu, b, c)$

or  $g(D, \alpha, \rho, V, \mu, b, c) = 0$

Parameter	Units
D	$mlt^{-2}$
$\alpha$	$m^{-3}$
$\rho$	$ml^{-3}$
V	$lt^{-1}$
$\mu$	$ml^{-1}t^{-1}$
b	l
c	l

$$N = 7$$

$$K = 3$$

$$\rightarrow 7 - 3 = 4 \text{ Pi products.}$$

$$\pi_1 = \frac{D}{\frac{1}{2}\rho V^2 bc} \equiv C_D$$

$$\pi_2 = \alpha \equiv \alpha$$

$$\pi_3 = \frac{\rho Vc}{\mu} \equiv Re$$

$$\pi_4 = \frac{b}{c} \equiv R \text{ (aspect ratio)}$$

$$\text{So } C_D = \bar{f}(\alpha, Re, R)$$

Alternative Pi products:

$$\pi_1 = \frac{D}{\frac{1}{2}\rho V^2 b^2} = \frac{C_D}{R}$$

$$\pi_3 = \frac{\rho Vb}{\mu} = Re \cdot R$$

$$\pi_4 = \frac{c}{b} = \frac{1}{R}$$

etc.

These are valid alternative parameters which determine  $C_D$ , although a bit unconventional

Given:  $\rho = 0.5 \rho_{SL}$   $l = 4 l_{SL}$  (characteristic length)  
 $a = 0.95 a_{SL}$  (span, chord, whatever)  
 $\mu = 0.95 \mu_{SL}$  → tunnel quantity

a) To match  $M_\infty$ , must have  $\frac{V}{a} = \frac{V_{SL}}{a_{SL}} \rightarrow V = 0.95 V_{SL}$

To also match  $Re$ , must have  $\frac{\rho V l}{\mu} \stackrel{?}{=} \frac{\rho_{SL} V_{SL} l_{SL}}{\mu_{SL}}$

or  $\frac{\rho}{\rho_{SL}} \frac{V}{V_{SL}} \frac{l}{l_{SL}} \stackrel{?}{=} \frac{\mu}{\mu_{SL}}$

$0.5 \cdot 0.95 \cdot 4 \stackrel{?}{=} 0.95$  ~~X~~ not possible

Cannot simultaneously match  $M_\infty$  and  $Re$  without being able to adjust another parameter (like  $\rho$ !)

b) Tunnel quantities:  $\rho_T a_T \mu_T V_T l_T$

Unknown:  $\rho_T$

Given:  $a_T = a_{SL} = \frac{1}{0.95} a$

$\mu_T = \mu_{SL} = \frac{1}{0.95} \mu$

$l_T = \frac{1}{4} l$

because  $T_T = T_{SL}$   
as given

Require  $M = M_T \rightarrow \frac{V}{a} = \frac{V_T}{a_T} \rightarrow V = 0.95 V_T$

Require  $Re = Re_T \rightarrow \frac{\rho V l}{\mu} = \frac{\rho_T V_T l_T}{\mu_T}$

$\rho_T = \rho \cdot \frac{V}{V_T} \frac{l}{l_T} \frac{\mu_T}{\mu} = \rho \cdot 0.95 \cdot 4 \cdot \frac{1}{0.95} = 4\rho$

or  $\rho_T = 2\rho_{SL}$

From equation of state:  $\rho_T = \rho_{SL} \left( \frac{\rho_T}{\rho_{SL}} \right) \left( \frac{T_T}{T_{SL}} \right) = 2\rho_{SL} = 2 \text{ atm.}$

1. The aircraft is flying at 120 knots.  
Therefore,

$$V_0 = 120 \text{ Kn} \times \frac{6080 \text{ ft}}{\text{NM}} \times \frac{1}{3600 \text{ s/hr}} \times 0.3048 \frac{\text{m}}{\text{ft}}$$

$$= 61.77 \text{ m/s}$$

Also,

$$g = 9.82 \text{ m/s}^2, \quad L_0/D_0 = 10$$

Therefore, the matrix  $A$  is given by

$$A = \begin{bmatrix} 0 & 0 & 61.77 \\ 0 & -0.03180 & -9.82 \\ 0 & 0.005147 & 0 \end{bmatrix}$$

The eigenvalues are the roots of

$$\det(sI - A) = 0$$

$$= s \left[ (s + 0.0318) s + (0.005147)(9.82) \right]$$

$$= s (s^2 + 0.03180 s + 0.05055)$$

The roots can be found using the quadratic formula. So

$$s_1 = 0, \quad s_2 = -0.01590 + 0.2243j$$

$$s_3 = -0.01590 - 0.2243j$$



The eigenvectors are found by solving

$$(s_i I - A) \underline{x}_i = \underline{0}$$

Do each in turn:

$$\underline{s_1 = 0}: \quad s_1 I - A = \begin{bmatrix} 0 & 0 & -61.77 \\ 0 & +0.03180 & +9.82 \\ 0 & -0.005147 & 0 \end{bmatrix}$$

Since the 1<sup>st</sup> column is all zeros, a solution is

$$\underline{x}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\underline{s_2 = -0.01590 + 0.2243j}:$$

$$s_2 I - A =$$

$$\begin{bmatrix} -0.01590 + 0.2243j & 0 & -61.77 \\ 0 & 0.01590 + 0.2243j & 9.82 \\ 0 & -0.005147 & -0.1590 + 0.2243j \end{bmatrix}$$

Row reduction proceeds as normal, but is messy. The result is

$$\begin{bmatrix} 1 & 0 & -19.43 - 274.1j \\ 0 & 1 & 3.0885 - 43.57j \\ 0 & 0 & 0 \end{bmatrix}$$

Note that one row is zero, as it should be, if  $\det(s_2 I - A) = 0!$

Arbitrarily take 3rd element of  $\underline{x}_2 = 1$ .

The

$$\underline{x}_2 = \begin{bmatrix} 19.43 + 274.1j \\ -3.0885 + 43.57j \\ 1 \end{bmatrix}$$

$$\underline{s}_3 = -0.0159 - 0.2243j;$$

Because  $s_3 = s_2^*$  (complex conjugate),

$$\underline{x}_3 = \underline{x}_2^* = \begin{bmatrix} 19.43 - 274.1j \\ -3.0885 - 43.57j \\ 1 \end{bmatrix}$$

2. The general solution is

$$\underline{x}(t) = a_1 \underline{x}_1 e^{s_1 t} + a_2 \underline{x}_2 e^{s_2 t} + a_3 \underline{x}_3 e^{s_3 t}$$

The initial condition is

$$\underline{x}(0) = a_1 \underline{x}_1 + a_2 \underline{x}_2 + a_3 \underline{x}_3$$

$$= \begin{bmatrix} \underline{x}_1 & \underline{x}_2 & \underline{x}_3 \end{bmatrix} \underline{a} \equiv V \underline{a}$$

$$= \begin{bmatrix} 0 \\ 0 \\ 0.1 \end{bmatrix}$$

Therefore,

$$\underline{a} = \begin{bmatrix} 3.885 + 0j \\ 0.05 - 0.003544j \\ 0.05 + 0.003544j \end{bmatrix}$$

I found this solution using Matlab, but it could easily be done with a calculator.

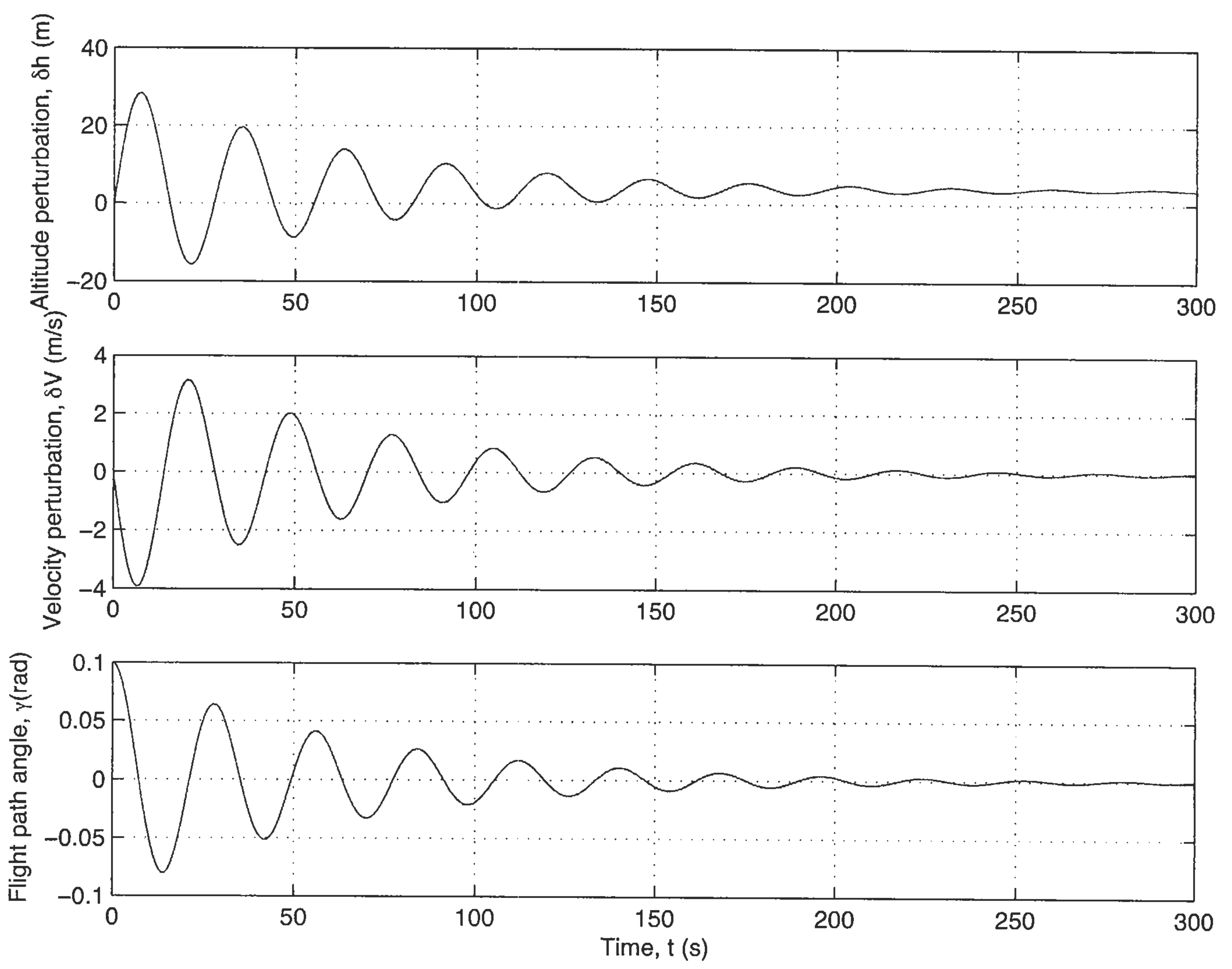
The result can now be plotted, since Matlab does complex exponentials.

```
s1 = 0;
s2 = -0.0159 + 0.2243j;
s3 = -0.0159 - 0.2243j;
X1 = [1;0;0];
X2 = [-19.43-274.1j;-3.0885+43.57j;1];
X3 = [-19.43+274.1j;-3.0885-43.57j;1];
a1 = 3.885;
a2 = 0.05-0.003544j;

a3 = 0.05+0.003544j;
t = 0:0.5:300;
x = a1*X1*exp(s1*t)+a2*X2*exp(s2*t)+a3*X3*exp(s3*t);

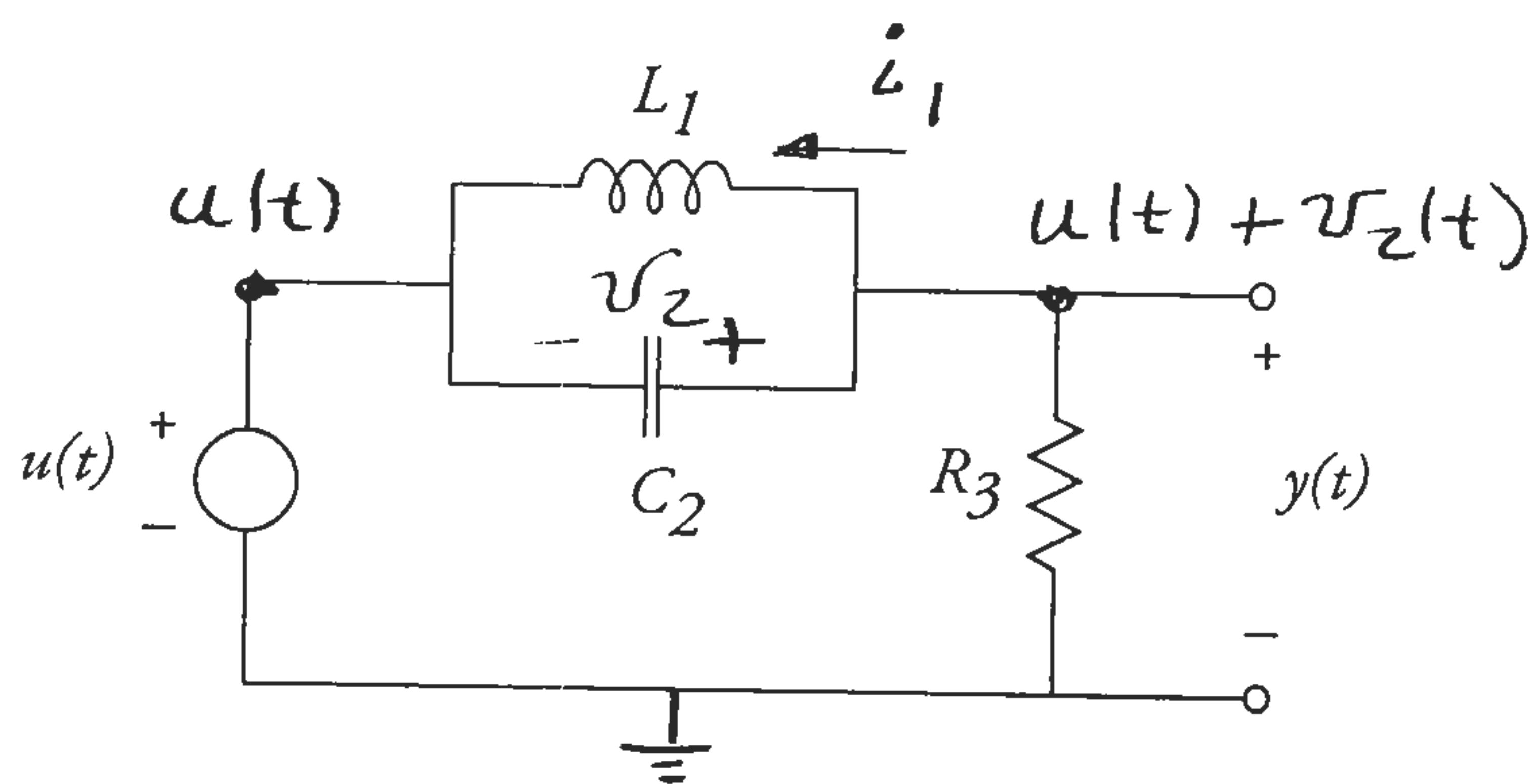
subplot(311)
plot(t,real(x(1,:)))
ylabel('Altitude perturbation, \delta{}h (m)')
grid
subplot(312)
plot(t,real(x(2,:)))
ylabel('Velocity perturbation, \delta{}V (m/s)')
grid
subplot(313)
plot(t,real(x(3,:)))
ylabel('Flight path angle, \gamma{}(rad)')
grid
xlabel('Time, t (s)')

print -depsc phugoid.eps
```





To solve the circuit, use the node method:



Note that there are no unknown nodes, which simplifies things!

The states are

$$x_1 = \dot{i}_1$$

$$x_2 = v_2$$

To find  $\dot{x}_1 = di_1/dt$ , need  $v_1$ :

$$\begin{aligned} \dot{x}_1 &= \frac{di_1}{dt} = \frac{1}{L} v_1(t) \\ &= \frac{1}{L} \underbrace{[(u + v_2) - u]}_{\text{potential across } L} \\ &= \frac{1}{L} v_2 \end{aligned}$$

To find  $\dot{x}_2 = dv_2/dt$ , need  $i_2$ . To find  $i_2$ , apply KCL at  $u + v_2$  node:

$$\frac{u + v_2 - 0}{R} + i_1 + i_2 = 0$$

Therefore,

$$\dot{i}_2 = -i_1 - \frac{1}{R} v_2 - \frac{1}{R} u$$

and

$$\begin{aligned} \dot{x}_2 &= \frac{dv_2}{dt} = \frac{1}{C} \dot{i}_2 \\ &= -\frac{1}{C} i_1 - \frac{1}{RC} v_2 - \frac{1}{RC} u \end{aligned}$$

Therefore, the state equation is given by

$$\dot{\underline{x}} = \underbrace{\begin{bmatrix} 0 & 1/L \\ -1/C & -1/RC \end{bmatrix}}_A \underline{x} + \underbrace{\begin{bmatrix} 0 \\ -1/RC \end{bmatrix}}_B u$$

To find the measurement equation, note that

$$y(t) = v_2 + u = x_2 + u$$

Therefore,

$$y = \underbrace{[0 \quad 1]}_C \underline{x} + \underbrace{[1]}_D u$$

N.B.:

There are other possible labellings for  $v_2$  and  $i_1$ . If you used a different labelling, some of the signs may be different

In particular,

1) If  $v_2$  labelled opposite mine,

$$C = [0 \quad -1]$$

$$B = \begin{bmatrix} 0 \\ +1/RC \end{bmatrix}$$

2) If  $v_2$  or  $i_1$  labelled opposite mine (but not both),

$$A = \begin{bmatrix} 0 & -1/L \\ 1/C & -1/RC \end{bmatrix}$$

3) If both  $v_2$  and  $i_1$  labelled opposite mine,  $A$  remains the same.

1. From S13,

$$A = \begin{bmatrix} 0 & 1/L \\ -1/LC & -1/RC \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ -1/RC \end{bmatrix}$$

$$C = [0 \quad 1] \quad D = [1]$$

First find  $(sI - A)^{-1}$ :

$$sI - A = \begin{bmatrix} s & -1/L \\ 1/LC & s + 1/RC \end{bmatrix}$$

For any matrix  $M$ ,  $M^{-1} = \frac{\text{adj}(M)}{\det(M)}$ . For

$2 \times 2$  matrices, this gives:

$$(sI - A)^{-1} = \frac{1}{s^2 + \frac{s}{RC} + \frac{1}{LC}} \begin{bmatrix} s + 1/RC & + 1/L \\ -1/C & s \end{bmatrix}$$

Now find  $G(s) = C(sI - A)^{-1}B + D$ :

$$C(sI - A)^{-1} =$$

$$\frac{1}{s^2 + \frac{s}{RC} + \frac{1}{LC}} [0 \quad 1] \begin{bmatrix} s + 1/RC & 1/L \\ -1/C & s \end{bmatrix}$$

$$= \frac{1}{s^2 + \frac{s}{RC} + \frac{1}{LC}} [-1/C \quad s]$$

Then

$$C(sI - A)^{-1}B = \frac{1}{s^2 + \frac{s}{RC} + \frac{1}{LC}} \begin{bmatrix} -1/C & s \end{bmatrix} \begin{bmatrix} 0 \\ -1/RC \end{bmatrix}$$

$$= \frac{-s/RC}{s^2 + \frac{s}{RC} + \frac{1}{LC}}$$

Finally,

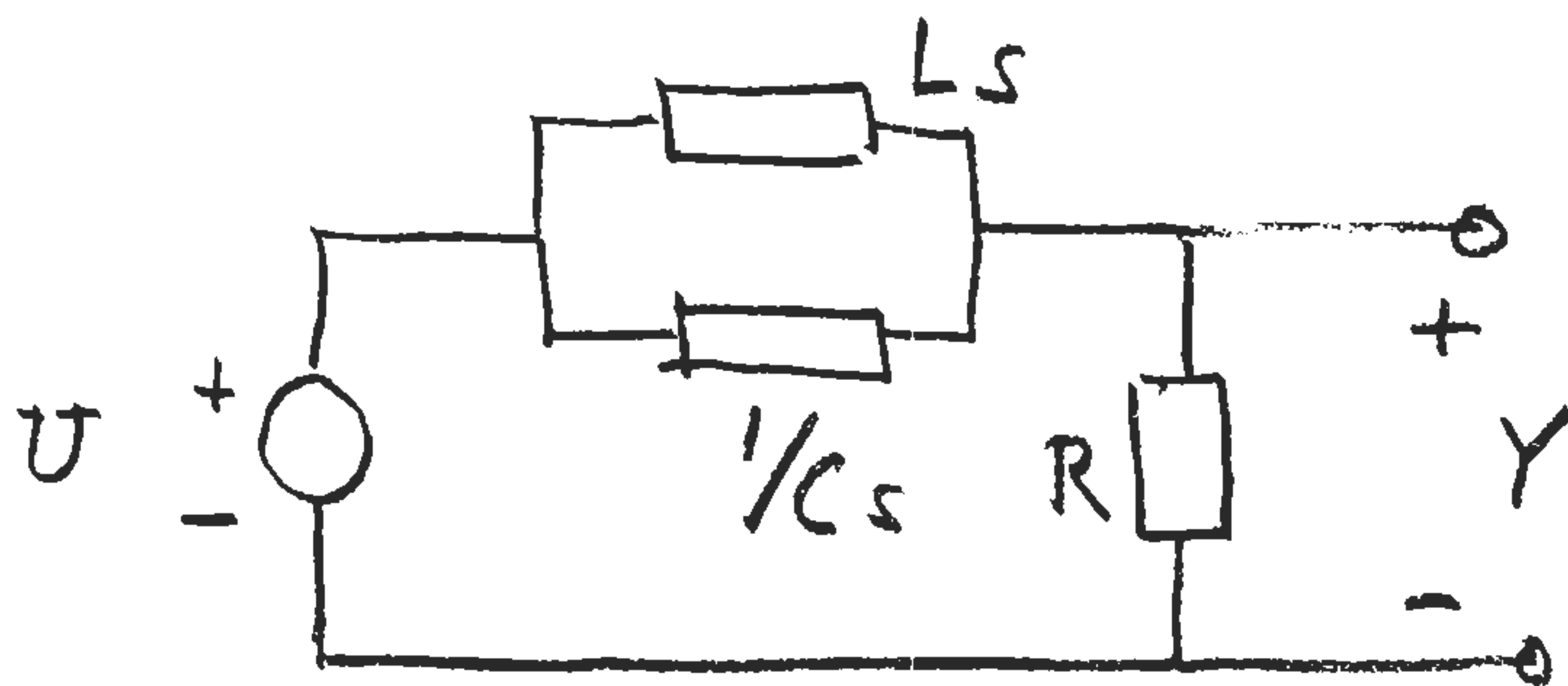
$$G(s) = C(sI - A)^{-1}B + D$$

$$= \frac{-s/RC}{s^2 + s/RC + 1/LC} + 1$$

$$= \frac{s^2 + 1/LC}{s^2 + s/RC + 1/LC}$$

$$G(s) = \frac{s^2 + 1/LC}{s^2 + s/RC + 1/LC}$$

2. We can also find  $G(s)$  by impedance methods. Redraw the circuit:





The inductor and capacitor are in parallel.  
The combined impedance is

$$Ls \parallel \frac{1}{Cs} = \frac{(Ls)(1/Cs)}{Ls + 1/Cs}$$


$$= \frac{Ls}{LCs^2 + 1}$$

With this impedance, the circuit becomes a voltage divider:

$$Y = \frac{R}{R + \frac{Ls}{LCs^2 + 1}} \cdot U$$

$$= \frac{RLCs^2 + R}{RLCs^2 + R + Ls} U$$

$$= \frac{s^2 + 1/LC}{s^2 + \frac{s}{RC} + \frac{1}{LC}} U$$

  
 $G(s)$

So we get the same  $G(s)$  as before.

3. For  $L = 1\text{H}$ ,  $C = 0.25\text{F}$ ,  $R = 10\Omega$ , the transfer function is

$$G(s) = \frac{s^2 + 4}{s^2 + 0.4s + 4}$$

For sinusoidal input, we can write

$$u(t) = \cos \omega t = \text{Real} [e^{j\omega t}]$$

Thus,  $U = 1$   
 $s = j\omega$

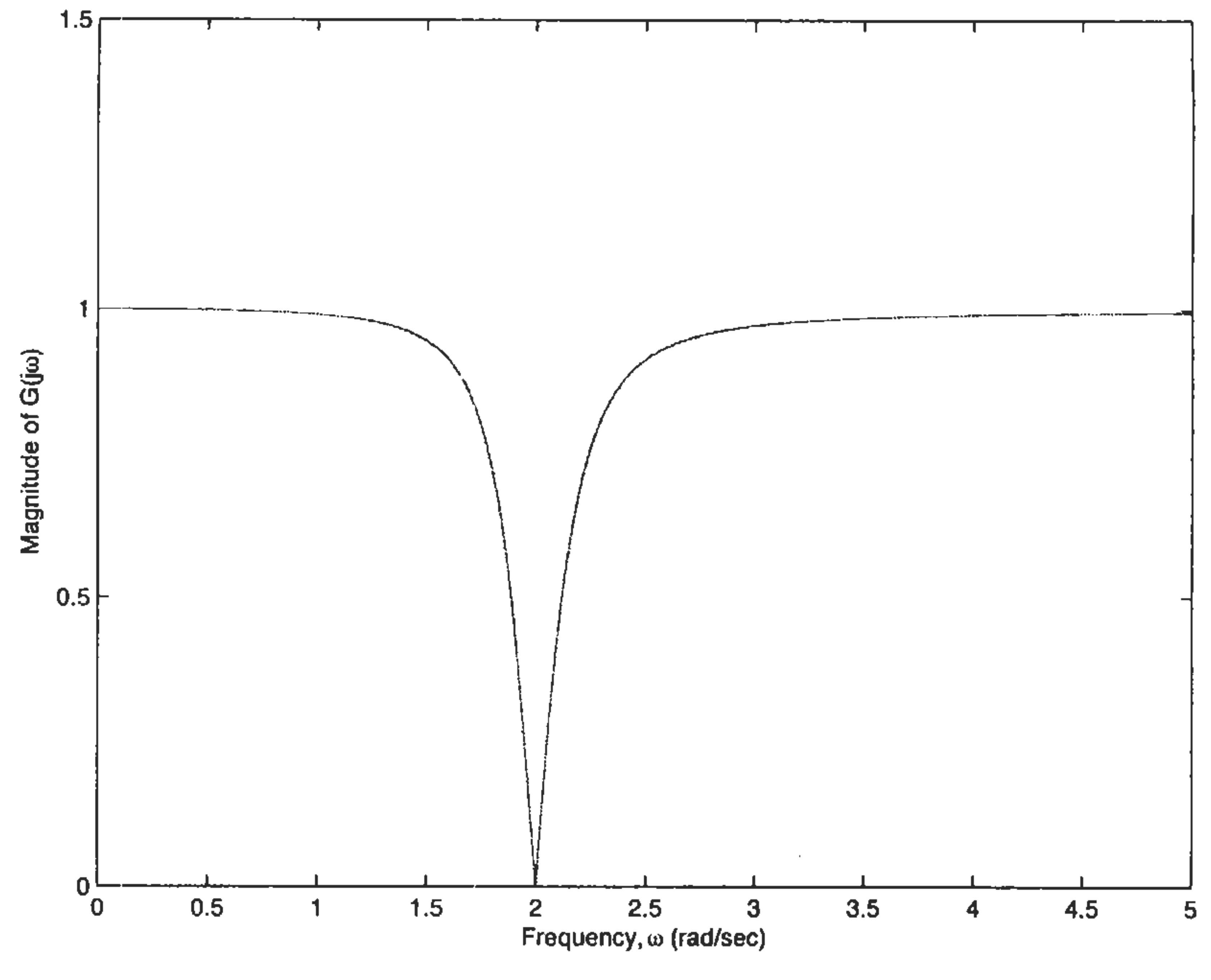
So the ratio of output to input amplitudes is

$$|G(j\omega)| = \left| \frac{-\omega^2 + 4}{-\omega^2 + 0.4j\omega + 4} \right|$$

This transfer function magnitude can be plotted by hand, or by using, say, Matlab. My Matlab code is below:

```
>> w = 0:.001:5;
>> G = (-w.^2+4)./(-w.^2+0.4j*w+4);
>> plot(w,abs(G))
>> axis([0 5 0 1.5]); ylabel('Magnitude of G(j\omega)'); xlabel('Frequency, \omega (rad/sec)');
>> print -depsc notch.eps
```

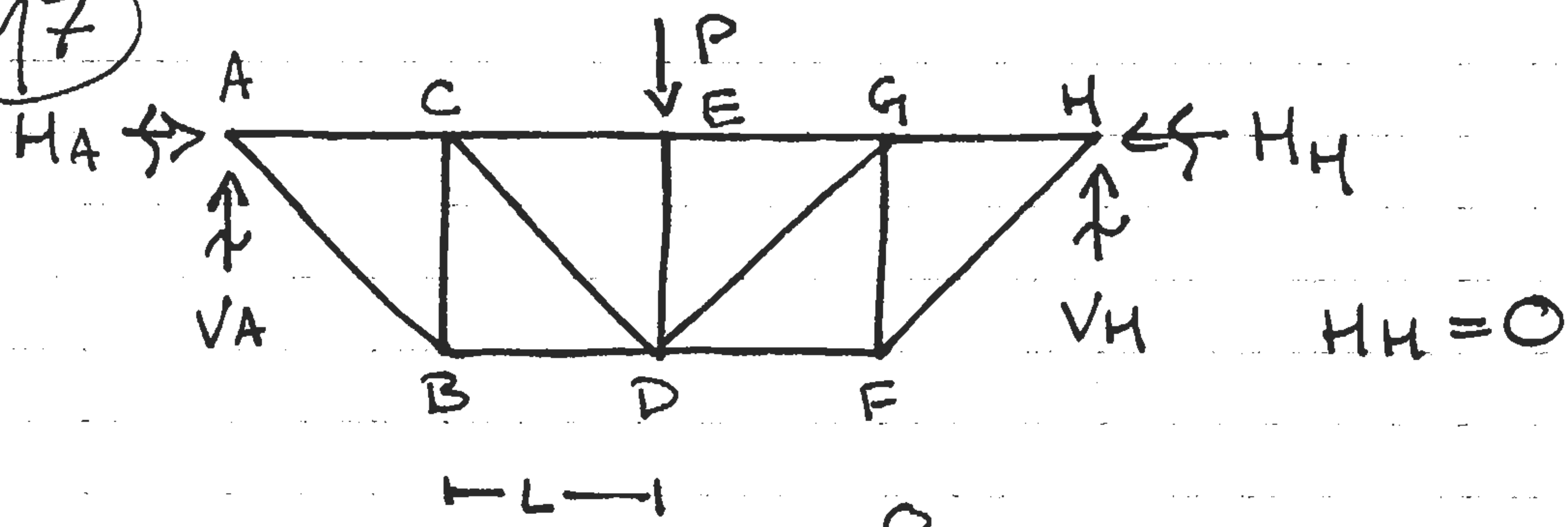
The resulting plot is on the next page. You can see why it is called a notch filter — the plot has a notch at the resonant frequency.



No. 5505  
Engineer's Computation Pad

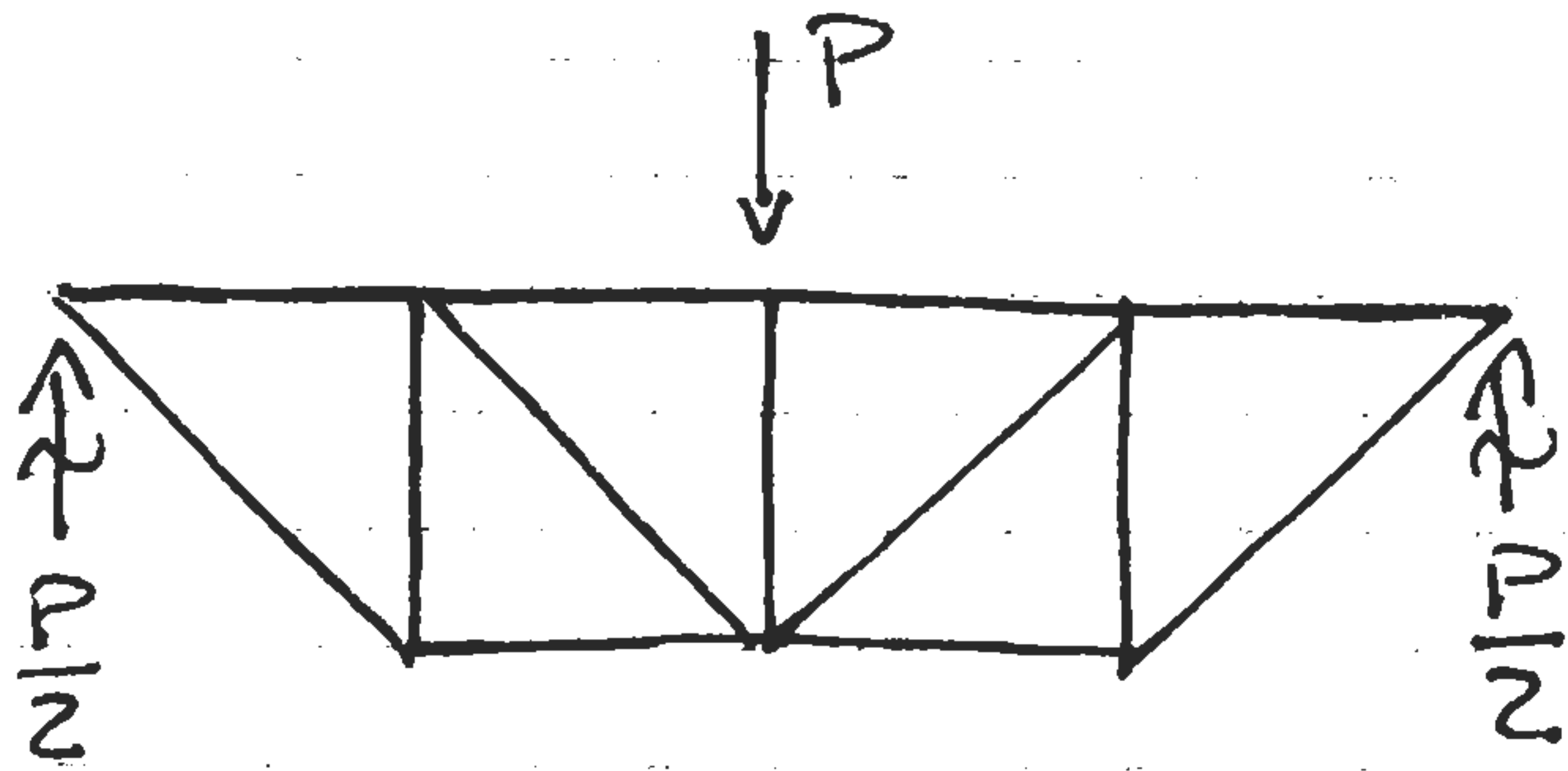


M7

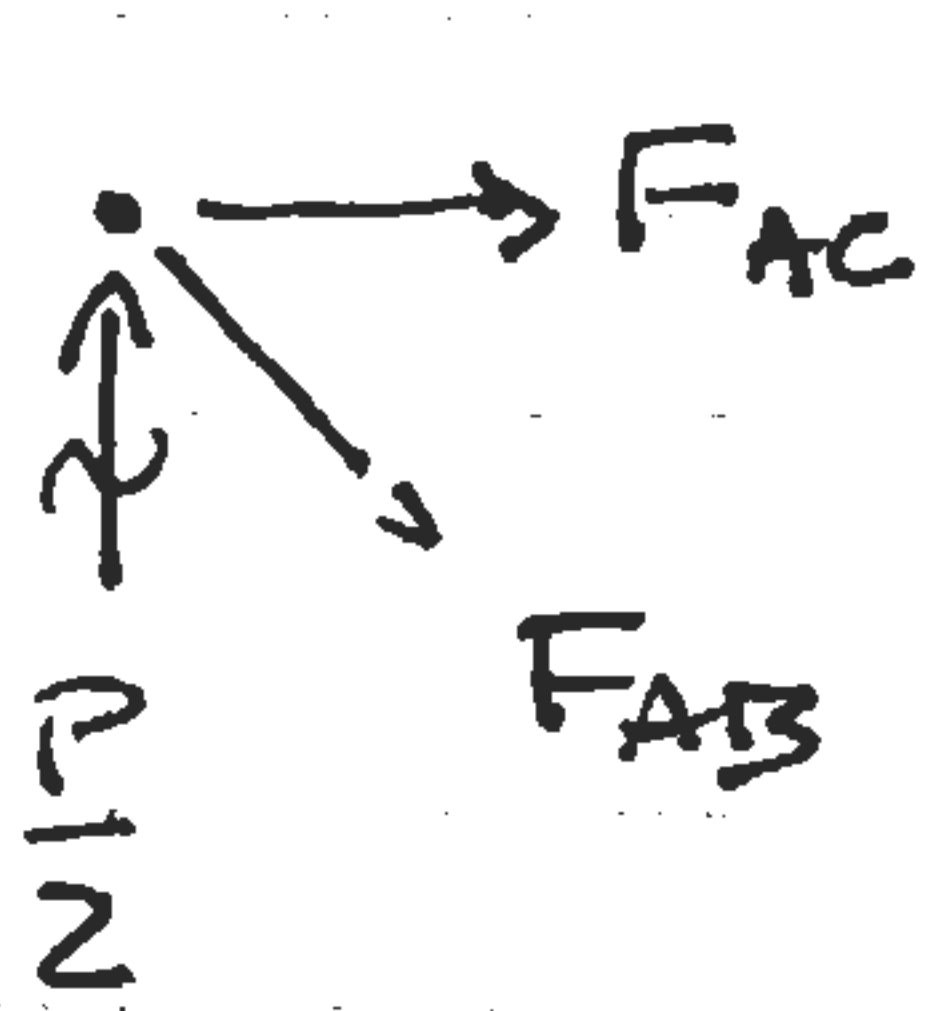


$$\begin{aligned} \sum \vec{F}_x = 0 & \quad H_A + H_H = 0 \quad H_A = 0 \\ \sum \vec{F}_y = 0 & \quad V_A + V_H - P = 0 \\ (\sum M_A = 0) & \quad V_H(4L) - P(2L) = 0 \\ & \quad V_H = \frac{P}{2} \quad + \quad V_A = \frac{P}{2} \end{aligned}$$

(also from symmetry)



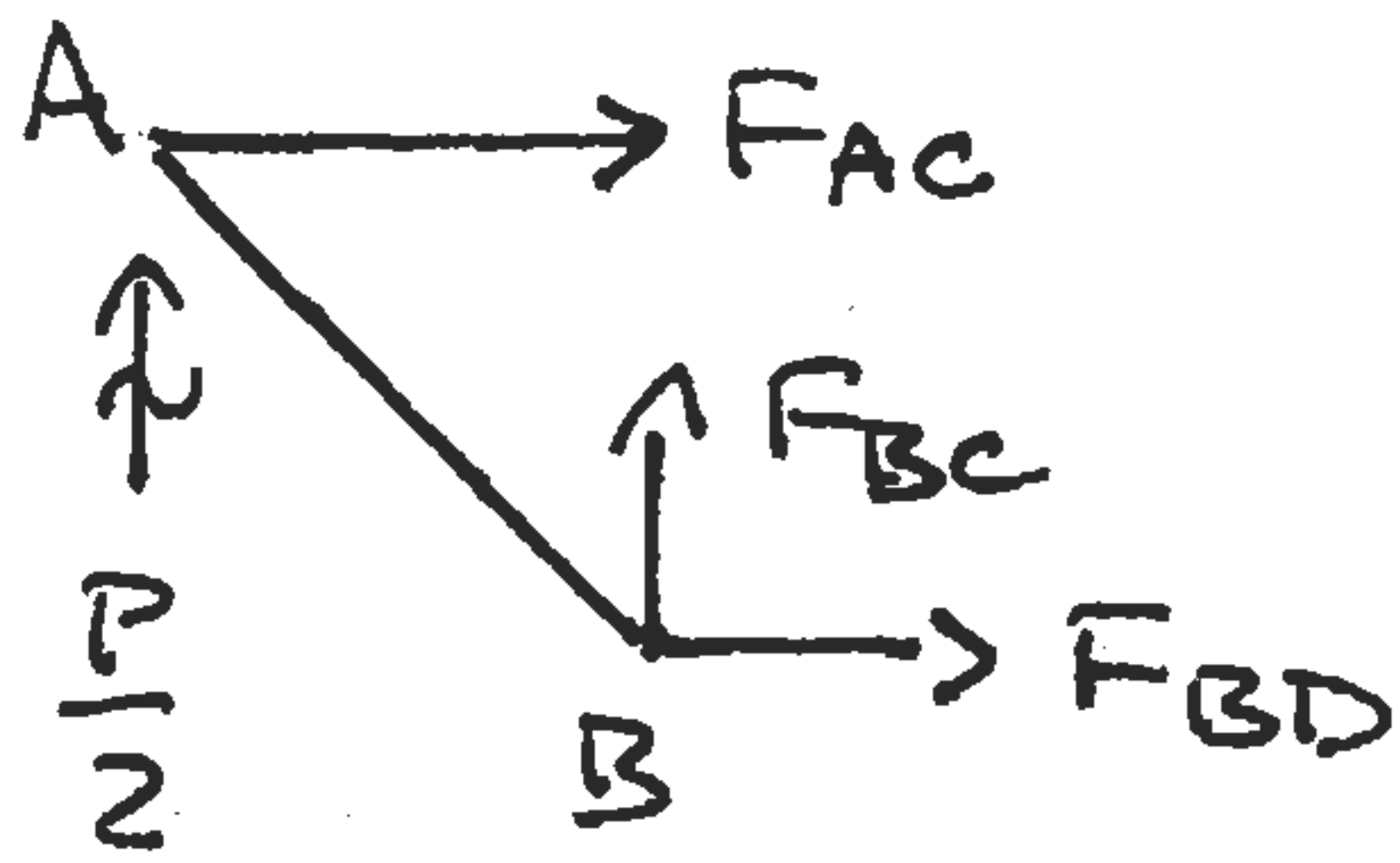
Using the method of joints @ A:



$$\begin{aligned} \sum F_y \uparrow = 0 & \\ \frac{P}{2} - F_{AB} \cos 45^\circ = 0 & \\ F_{AB} = \frac{\sqrt{2}P}{2} & \\ \sum F_x \rightarrow = 0 & \\ F_{AC} + \frac{\sqrt{2}P}{2} \cos 45^\circ = 0 & \\ F_{AC} = -\frac{P}{2} & \end{aligned}$$



Method of Sections :



$$\sum F_y \uparrow = 0$$

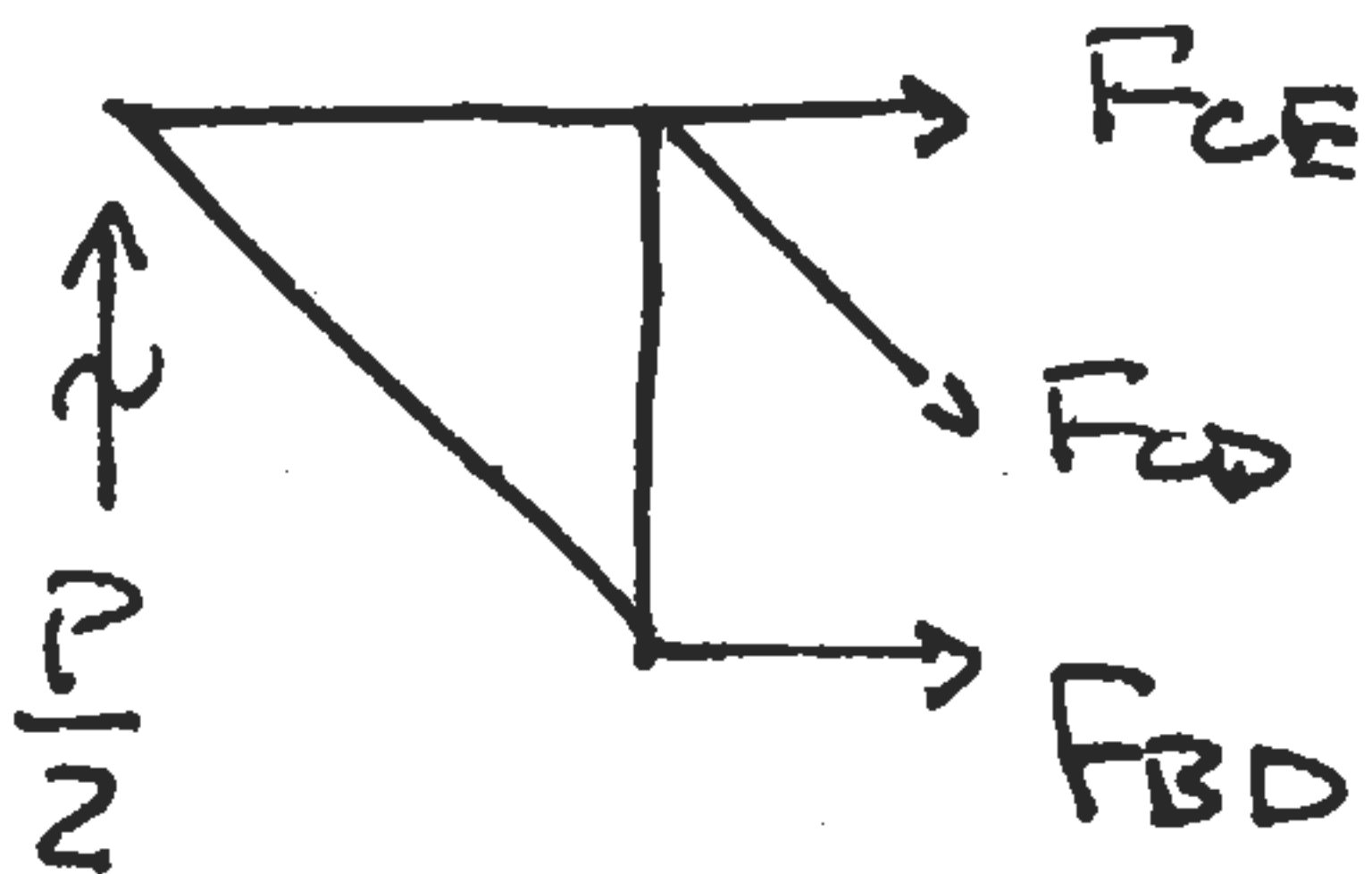
$$F_{BC} + \frac{P}{2} = 0$$

$$F_{BC} = -\frac{P}{2}$$

Method of Sections :  $\left( \sum M_c = 0 \right)$

$$-\frac{P}{2}(L) + F_{BD}(L) = 0$$

$$F_{BD} = \frac{P}{2}$$



$$\sum F_y \uparrow = 0 \quad \frac{P}{2} - F_{CD} \sin 45^\circ = 0$$

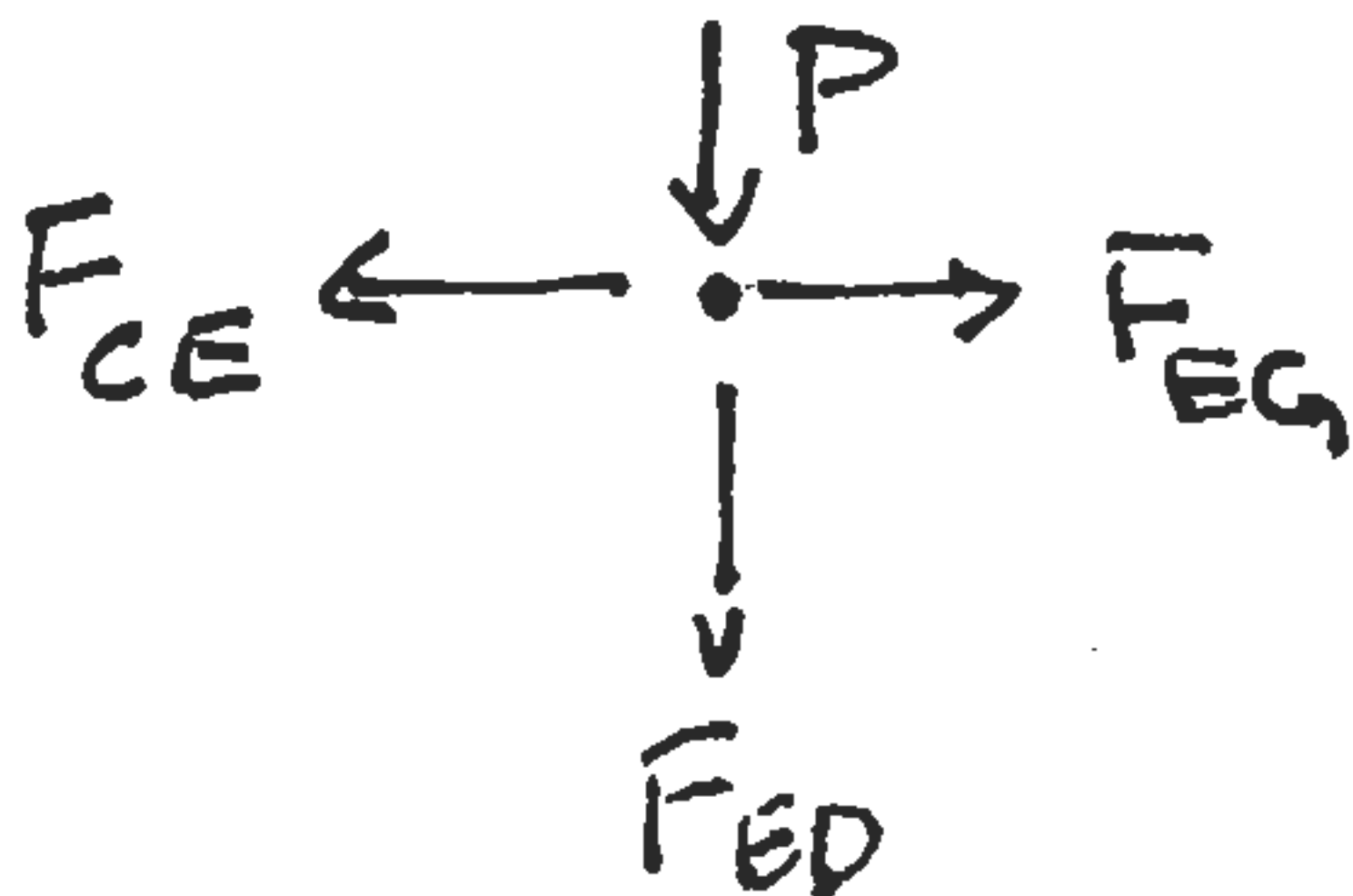
$$F_{CD} = \frac{P}{2} \sqrt{2} = \frac{\sqrt{2}P}{2}$$

$$\left( \sum M_D = 0 \right)$$

$$-\frac{P}{2}(2L) - F_{CE}(L) = 0$$

$$F_{CE} = -P$$

Method of Joints @ E :



$$\sum F_y \uparrow = 0$$

$$-P - F_{ED} = 0$$

$$F_{ED} = -P$$

By symmetry all other bar forces are the same on the right hand side.





<u>Bar</u>	<u>Force</u>
AB	$\frac{\sqrt{2}}{2} P$
AC	$-P/2$
BC	$-P/2$
CE	$-P$
CD	$\frac{\sqrt{2}}{2} P$
BD	$P/2$
ED	$-P$
EG	$-P$
DG	$\frac{\sqrt{2}}{2} P$
DF	$P/2$
GF	$-P/2$
GH	$-P/2$
FH	$\sqrt{2} P/2$