

16.06 Principles of Automatic Control

Recitation 9

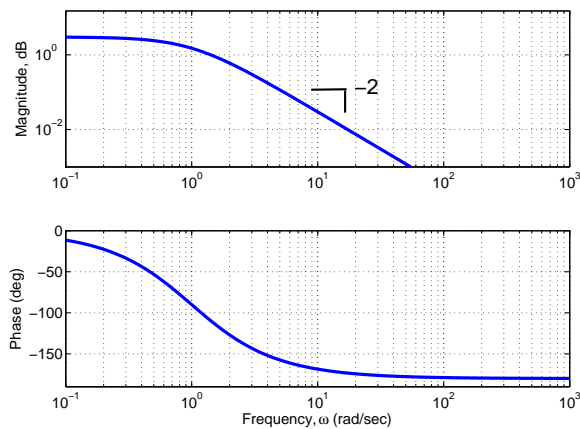
Design a lead compensator for $G(s) = \frac{3}{(s+1)^2}$ such that:

$$\omega_c = 50 \text{ rad/sec}$$

$$\text{PM} = 50^\circ$$

$$K(s) = K \frac{1+s/a}{1+s/b}$$

Bode Plot:



We want $\omega_c = 10 \text{ rad/sec}$ and $\text{PM} = 50^\circ$. Our lead compensator will add phase to the system, but we need to specify how much phase to add.

Current phase at ω_c is

$$-2 \tan^{-1}\left(\sqrt{\frac{b}{a}}\right) - 90^\circ = 38.6^\circ$$

$$\sqrt{\frac{b}{a}} = 2.08 \dots (1)$$

Strategically place pole and zero symmetrically about crossover (in log scale):

$$\omega_c = \sqrt{ab} = 10 \dots (2)$$

where \sqrt{ab} is the geometric mean.

Now solve (1) and (2) for a and b :

$$\begin{aligned} a &= 4.8 \\ b &= 20.8 \end{aligned}$$

Now, to find the gain, use the condition that $|K(j\omega_c)G(j\omega_c)| = 1$:

$$\frac{K \cdot 3 \sqrt{1^2 + \left(\frac{10}{4.8}\right)^2}}{\left(1^2 + 10^2\right) \sqrt{1^2 + \left(\frac{10}{20.8}\right)^2}} = 1$$

\hookrightarrow double pole

$$K \approx 16.1$$

$$K(s) = 16.1 \cdot \frac{\left(1 + \frac{s}{4.8}\right)}{\left(1 + \frac{s}{20.8}\right)}$$

Now, we add the requirement of having $K_p = 200$.

We need to design an additional lag compensator, but this will add about 6° phase lag at ω_c .

So we need to redesign our lead compensator to account for this 6° phase lag:

$$\phi_{\max} = 38.6^\circ + 6^\circ = 44.6^\circ = 2 \tan^{-1} \left(\sqrt{\frac{b}{a}} \right) - 90^\circ$$

$$\therefore \sqrt{\frac{b}{a}} = 2.39 \rightarrow \text{see equation (2) above: } \omega_c = \sqrt{ab} = 10.$$

$$b = 23.9$$

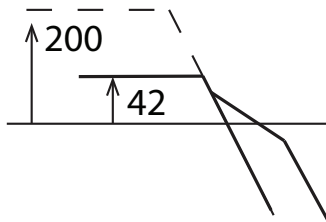
$$a = 4.18$$

and we find out new $K = 14.07$.

$$K_p = \lim_{s \rightarrow 0} \left(14.07 \frac{1 + \frac{s}{4.18}}{1 + \frac{s}{23.9}} \right) \cdot \frac{3}{(s+1)^2} = 42.2$$

Need our lag ratio to be

$$\frac{K_p \text{ desired}}{K_p \text{ current}} = \frac{200}{42.2} = 4.74$$



We can place the zero of the lag compensator $\sim 1^\circ$ below:

$$\omega_c = 10 \rightarrow \frac{s+1}{s+?} \rightarrow \text{set pole to satisfy the lag ratio of 4.74; i.e. at 0.21.}$$

$$\therefore K(s) = 14.07 \frac{1 + s/4.18}{1 + s/23.9} \cdot \frac{s+1}{s+0.21}$$

PM = 51.5°
 $\omega_c = 10.0$

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