

Lecture 7

3) Thin Shear Layer Approximation

- 2) A) $Re \rightarrow \infty$ behavior
- B) Ordering
- C) TSL Approximation

96 - 99
 Sch - 145 - 148
 White - 218 - 219
 227 - 233.

Reading: White 218 - 219, 227 - 233
 Sch.

(see New ed.)

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A)
$$\frac{\partial u}{\partial t} + \underbrace{u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y}}_2 = \underbrace{-\frac{1}{\rho} \frac{\partial p}{\partial x}}_3 + \nu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \quad \text{--- x comp.}$$

$Re = \frac{U_\infty L}{\nu} \gg 1$

At A, ①, ②, and ③ balance
 B, ① & ② $\rightarrow 0$ ③ ~ 0 (④)

↑ do 1st
 * Using ρ, U_∞, ν, L as scales, the governing equations are:

$$\nabla \cdot \vec{u} = 0$$

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \cdot \nabla \vec{u} = -\nabla p + \frac{1}{Re} \nabla^2 \vec{u}$$

$$Re \equiv \frac{U_\infty L}{\nu}$$

B.C $\vec{u} = 0$ at wall (no slip)

Typical Re values are large

Example

Pigeon	—	50K
Sub, Concorde	—	5 mill.
747	—	100 mill.
Super tanker	—	5 bill

This suggests that $1/Re$ is a small parameter \rightarrow seek solutions as an asymptotic expansion in $\epsilon \in ((1/Re)^\epsilon)$.

$$\begin{aligned} \vec{u} &= \vec{u}_0 + \epsilon \vec{u}_1 + \epsilon^2 \vec{u}_2 + \dots \\ p &= p_0 + \epsilon p_1 + \epsilon^2 p_2 + \dots \end{aligned} \quad *$$

Look first at \vec{u}_0, p_0 : put (*) in N-S eqns. and B.C.s.

$$\begin{aligned} \nabla \cdot \vec{u}_0 &= 0 \\ \frac{\partial \vec{u}_0}{\partial t} + \vec{u}_0 \cdot \nabla \vec{u}_0 &= -\nabla p_0 \end{aligned}$$

$$\text{B.C.: } \vec{u}_0 = 0$$

Problem: Cannot satisfy both $u_0 = 0$ & $V_0 = 0$ at wall only $\vec{u}_0 \cdot \hat{n} = 0$

We lost highest-order term $\epsilon^2 \nabla^2 \vec{u}$

\rightarrow singular perturbation problem.

No slip B.C forces $\epsilon^2 \nabla^2 \vec{u}$ to be finite as $\epsilon \rightarrow 0$

The "fix" is to seek scales other than U_0, L near wall region

Example: In Rayleigh case, we had $\delta(t) = \sqrt{\nu t}$; $Y = y/\delta(t)$

In B-L case, look for $\delta(x)$ for scaling in limit of L for y

In the above problem we can switch the y coordinate

$$Y = y/\epsilon \quad \text{s.t.} \quad Y = O(1) \quad \text{as } \epsilon \rightarrow 0$$

Near the wall we can use

$$\begin{aligned} u &= u_1 + \epsilon u_2 + \dots \\ v &= \epsilon v_1 + \epsilon^2 v_2 + \dots \\ p &= p_0 + \epsilon p_1 + \dots \end{aligned}$$

$$x \text{ comp} \Rightarrow u_1 \frac{\partial u_1}{\partial x} + v_1 \frac{\partial u_1}{\partial Y} = -\frac{\partial p}{\partial x} + \frac{1}{\epsilon^2 Re} \frac{\partial^2 u_1}{\partial Y^2}$$

$$\rightarrow \epsilon = \frac{1}{\sqrt{Re}}$$

* Simple linear ODE illustration ① loss of highest derivative

② choice of length scale near a wall.

$$\epsilon \frac{d^2 f}{dx^2} + \frac{df}{dx} = a \quad f(0) = 0, \quad f(1) = 1$$

Exact solution:

$$f(x; \epsilon) = (1-a) \left(\frac{1 - e^{-x/\epsilon}}{1 - e^{-1/\epsilon}} \right) + ax$$

First setting $\epsilon = 0$ gives

$$\frac{df}{dx} = a$$

which can only satisfy one boundary condition unless $a = 1$

$$f(x; \epsilon) \sim (1-a) + ax \quad (\text{result of dropping highest derivative})$$

as $\epsilon \rightarrow 0$

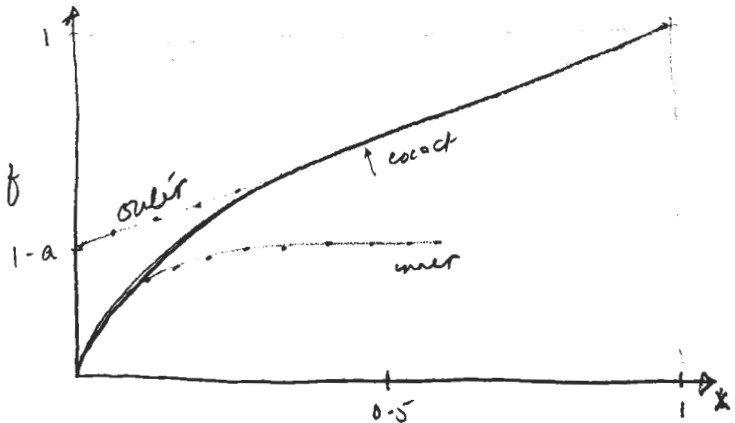
Choose a different scale when x is small or close to the wall

$$X = x/\epsilon \rightarrow F(X; \epsilon)$$

Substituting gives

$$\frac{d^2 F}{dX^2} + \frac{dF}{dX} = a\epsilon \quad F(0) = 0, \quad F(1/\epsilon) = 1$$

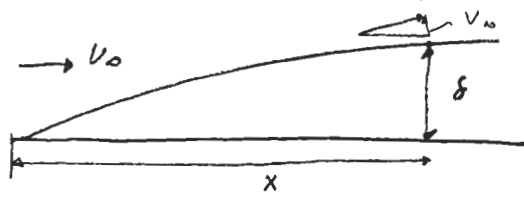
$$\Rightarrow f(x; \epsilon) \sim (1-a)(1 - e^{-x/\epsilon}) \quad \text{as } \epsilon \rightarrow 0 \text{ but } X \sim O(1)$$



Ref: Van Dyke
Pert. Methods in
Fluid Dynamics

0) Ordinary

(4)



Examine the order of magnitude of each term in governing eqns.

1) Continuity:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$O \left\{ \frac{U_\infty}{x} \quad \frac{U_\infty}{\delta} \right\} \rightarrow \frac{\delta}{x} = O \left(\frac{U_\infty}{U_\infty} \right)$$

$$O \left\{ 1 \quad 1 \right\} \quad x = O(1)$$

2) X-momentum:

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left[\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right]$$

$$O \left\{ \begin{array}{ll} U_\infty \cdot \frac{U_\infty}{x} & U_\infty \left(\frac{\delta}{x} \right) \frac{U_\infty}{\delta} \\ \frac{U_\infty^2}{x} & \frac{U_\infty^2}{x} \end{array} \right. \quad \frac{\nu^2}{x} \quad \delta^2 \left[\frac{U_\infty}{x^2} \quad \frac{U_\infty}{\delta^2} \right]$$

$$\delta^2 \left[\frac{U_\infty}{x^2} \quad \frac{U_\infty}{\delta^2} \right]$$

$$1 \quad 1/\delta^2$$

Also $\frac{\nu^2}{x} = O \left(\frac{\nu U_\infty}{\delta^2} \right) \Rightarrow \frac{\delta}{x} = O \left(\sqrt{\frac{\nu}{U_\infty x}} \right)$

$$\frac{\partial^2 u}{\partial x^2} \sim O(\delta^2)$$

3) Y-momentum:

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial y} + \nu \left[\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right]$$

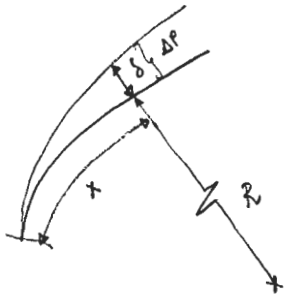
$$O \left\{ \begin{array}{ll} U_\infty \cdot \frac{U_\infty}{x} \frac{\delta}{x} & U_\infty \frac{\delta}{x} \cdot U_\infty \frac{\delta}{x} \frac{1}{\delta} \\ \frac{U_\infty^2}{x} & \frac{U_\infty^2}{x} \end{array} \right. \quad \delta^2 \left[\frac{U_\infty}{x^2} \frac{\delta}{x} \quad \frac{U_\infty}{\delta^2} \cdot \frac{\delta}{x} \right]$$

$$\delta \quad \delta \quad \delta^3 \quad \delta$$

This suggests

$$\frac{1}{\rho} \frac{\partial p}{\partial y} = O\left(\frac{u_{\infty}^2}{x^2} \cdot \delta\right) \approx O(\delta)$$

Curved wall



$$\Rightarrow \frac{1}{\rho} \frac{\partial p}{\partial y} = O\left(\frac{u_{\infty}^2}{R}\right)$$

Change in pressure across B.L

$$p(\delta) - p(0) = \Delta p \approx \frac{\partial p}{\partial y} \delta = O(\rho u^2 \left(\frac{\delta}{x}\right)^2) \approx O(\delta^2)$$

$$\approx O(\rho u^2 (\delta/R)) \approx O(\delta/R)$$

which is bigger in most cases.

In summary,

Keeping terms of $O(1)$ in x -momentum, and $\frac{\partial p}{\partial y} \approx 0$ in y -momentum gives us TBL Equations

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$
$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \frac{\partial^2 u}{\partial y^2}$$
$$\frac{\partial p}{\partial y} = 0$$

Neglects streamwise diffusion

$$\nu \frac{\partial^2 u}{\partial x^2} \approx 0$$

Neglects normal momentum

$$\frac{\partial p}{\partial y} \approx 0$$

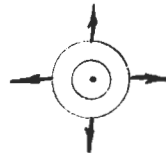
* assumption weakest at airfoil t.e and shocks, for example

THIN SHEAR LAYER APPROXIMATION

Viscous flows contain 3 basic momentum transport mechanisms:



CONVECTION



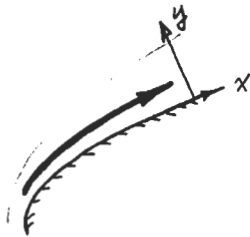
PRESSURE



DIFFUSION

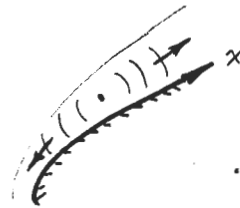
$$\vec{u} \cdot \nabla \vec{u} = -\frac{\nabla p}{\rho} + \nu \nabla^2 \vec{u}$$

These mechanisms become directionally biased in a thin shear layer:



CONVECTION

(unchanged)



PRESSURE

(transverse component suppressed)



DIFFUSION

(transverse component accentuated)

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} \approx -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \frac{\partial^2 u}{\partial y^2}$$

$$0 \approx -\frac{1}{\rho} \frac{\partial p}{\partial y}$$

- 1) Transverse velocity v is governed primarily by kinematic (continuity) requirements: $\partial v / \partial y = -\partial u / \partial x$, not by dynamic (y -momentum) requirements. The y -momentum equation decouples and is neglected.
- 2) Streamwise diffusion is negligible compared to transverse diffusion.

In real situations, assumption 1) is weaker than 2).