

$$\|e_n\| \leq \sum_{j=0}^{n-1} C(\Delta t)^{k+1} = n C(\Delta t)^{k+1}$$

$$\leq C t_n (\Delta t)^k, \quad k > 0$$

$$\Rightarrow \|e_n\| \rightarrow 0 \text{ as } \Delta t \rightarrow 0 \text{ qed}$$

LAX EQUIVALENCE

Stability properties of Trapezoidal rule

$$A \dot{y} + B y = 0, \quad y(0) = y_0$$

$$F(\Delta t) = [A + \alpha \Delta t B]^{-1} [A - (1-\alpha) \Delta t B]$$

$$A = A^T, A > 0 \quad B = B^T, B > 0$$

$$\|y\|^2 = y^T A y \quad \dim y = N$$

Scalar case $\dot{y} + \lambda y = 0, \quad y(0) = y_0$

$$y_{n+1} = \mu(\Delta t) y_n, \quad \mu(\Delta t) = \frac{1 - (1-\alpha)\lambda \Delta t}{1 + \alpha \lambda \Delta t}$$

unconditional stability for $\alpha \geq 1/2$

conditional stability for $\alpha < \frac{1}{2}$, $\Delta t_c = \frac{\lambda^{-1}}{1-2\alpha}$

Reduce the grad case to scalar cases by a spectral (modal) decomposition.

$$\text{EVP: } (B - \lambda A) \varphi = 0; \quad \|\varphi\| = 1$$

\Rightarrow N solns (φ_r, λ_r) , $r = 1, \dots, N$

Props: 1) $\lambda_r > 0$ (from positive definiteness)

2) $\varphi_r^T A \varphi_s = \delta_{rs}$

3) $\{\varphi_r = 1, \dots, N\}$ forms a basis of \mathbb{R}^N

$$\Rightarrow \forall y \in \mathbb{R}^N \quad y = \sum_{r=1}^N y^r \varphi_r \quad \text{uniquely}$$

y^r : modal coordinates.

$$y^T A \varphi_s = \left(\sum_{r=1}^N y^r \varphi_r \right)^T A \varphi_s = y^s$$

Eigenprojections: $P_r = \varphi_r \otimes \varphi_r = \varphi_r \varphi_r^T$
 $\in \mathbb{R}^{N \times N}$

Props: 1) $P_r^T = P_r$

2) $P_r^2 = (q_r q_r^T)(q_r q_r^T) = q_r q_r^T = P_r$

3) $\sum_{r=1}^N P_r = I$

$$P_r y = q_r q_r^T \left(\sum_{s=1}^N y^s q_s \right) = q_r \sum_{s=1}^N y^s \delta_{rs}$$

$$= y^r q_r \quad (\text{no sum})$$

(modal components)

Eq. of evolution: $A y + B \dot{y} = 0$

$$A \left(\sum_{s=1}^N y^s q_s \right) + B \left(\sum_{s=1}^N \dot{y}^s q_s \right) = 0 \quad () q_r^T$$

$$\Rightarrow \boxed{\dot{y}^r + \lambda_r y^r = 0 \quad ; \quad r=1, \dots, N}$$

equations of evolution decouple mode by mode.

$$\|y\|^2 = y^T A y = \left(\sum_{r=1}^N y^r q_r \right)^T A \left(\sum_{s=1}^N y^s q_s \right)$$

$$\sum_{r=1}^N \sum_{s=1}^N y^r y^s \underbrace{q_r^T A q_s}_{\delta_{rs}}$$

$$\|y\|^2 = \sum_{r=1}^N |y^r|^2 \quad \text{energy norm decouples mode by mode.}$$

Trapezoidal rule also decouples mode by mode.

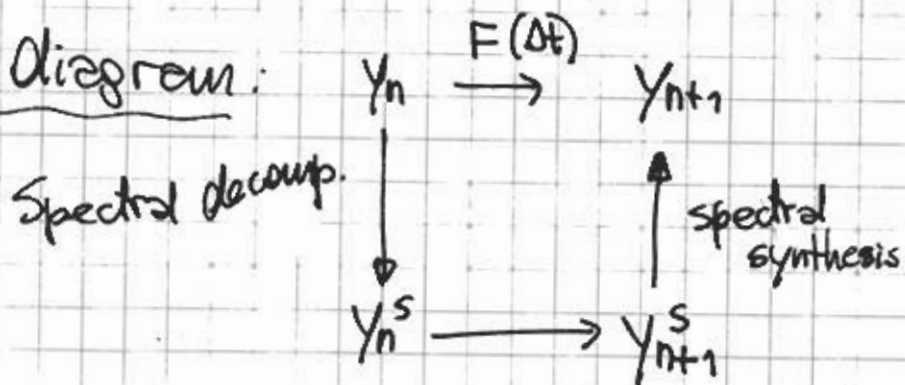
$$A \frac{y_{n+1} - y_n}{\Delta t} + B [(1-\alpha)y_n + \alpha y_{n+1}] = 0$$

$$\text{Let } y_{n+1} = \sum_{r=1}^N y_{n+1}^r q_r, \quad y_n = \sum_{r=1}^N y_n^r q_r$$

Insert and multiply through by q_s^T , orthogonality

$$\frac{y_{n+1}^s - y_n^s}{\Delta t} + \lambda_s [(1+\alpha)y_n^s + \alpha y_{n+1}^s] = 0$$

Commutative Diagram:



→ algorithm never mixes energy between different modes

Summary

IVP

EVP

$$\left. \begin{aligned} A\dot{y} + By &= 0 \\ y(0) &= y_0 \end{aligned} \right\}$$

$$\begin{aligned} (B - \lambda A) \varphi &= 0 \\ P_r &= \varphi_r \otimes \varphi_r \end{aligned}$$

Spectral decomposition: $y = \sum_{r=1}^N y^r \varphi_r$ (SD)

$$(i) \rightarrow A\dot{y} + By = 0 \xrightarrow{\text{SD}} \dot{y}^r + \lambda_r y^r = 0$$

$$\boxed{e^{-tA^{-1}B} P_r = P_r e^{-tA^{-1}B}}$$

propagator commutes with eigenprojections!

$$e^{tA^{-1}B} P_r y_0 = P_r e^{tA^{-1}B} y_0 = P_r y(t) \quad !!$$

$$(ii) A \frac{y_{n+1} - y_n}{\Delta t} + B y_{n+k} = 0 \xrightarrow{\text{SD}} \frac{y_n^r - y_{n+1}^r}{\Delta t} + \lambda_r y_{n+k}^r = 0$$

i.e. $F(\Delta t) P_r = P_r F(\Delta t)$

simplification matrix commutes with P_r

$$F(\Delta t) P_r y_n = P_r F(\Delta t) y_n$$

(iii) Energy norm: $\|y\|^2 = \sum_{r=1}^N |y_r|^2$

Stability condition $\|y_{n+1}\| < \|y_n\| \quad \forall y_n$

$$\Rightarrow \sum_{r=1}^N |y_{n+1}^r|^2 < \sum_{r=1}^N |y_n^r|^2 \quad \forall y_n$$

$$\Rightarrow |y_{n+1}^r| < |y_n^r|, \quad r=1, \dots, N$$

Since $y_{n+1}^r = \mu_r(\Delta t) y_n^r \Rightarrow |\mu_r(\Delta t)| < 1, \quad r=1, \dots, N$

$\alpha \geq \frac{1}{2} \Rightarrow$ unconditional stability

$\alpha < \frac{1}{2} \Rightarrow$ conditional stability \Rightarrow

$$\Delta t \leq \frac{2}{(1-\alpha)\lambda_r} \quad r=1, \dots, N$$

$$\Delta t \leq \Delta t_c = \frac{2}{(1-\alpha)\lambda_{\max}}$$

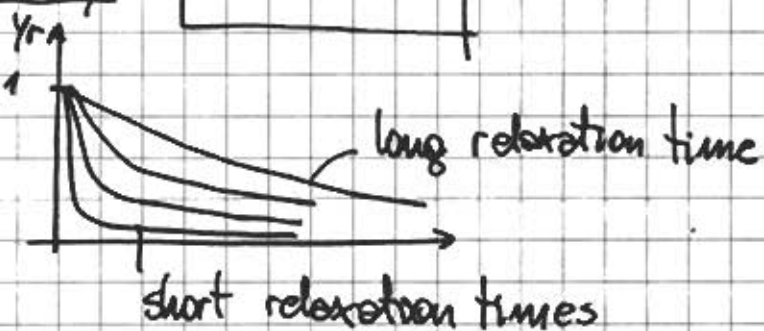
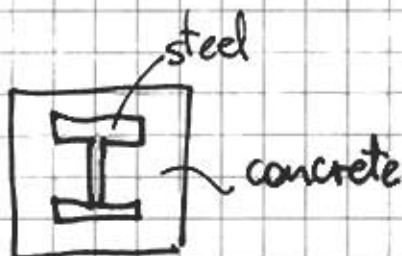
Stability governed
by λ_{\max} .

Choice of Δt :

i) Conditional stability

$$\Delta t \leq \Delta t_c$$

ii) Stiff systems



Say one knows a priori that $y_r \approx 0 \quad r \geq m$

\Rightarrow implicit methods

choose Δt to resolve the smallest relevant relax.
time

$$\Delta t < \frac{2}{\lambda_m}$$

Stability of Newmark's Algorithm

$$\text{IVP } \left. \begin{aligned} M \ddot{x} + C \dot{x} + K x &= 0 \\ x(0) = x_0, \dot{x}(0) &= v_0 \end{aligned} \right\}$$

$$\text{EVP: } (K - \omega^2 M) q = 0 \quad \omega \equiv \text{eigenfrequencies.}$$

$$\text{Spectral dec } \quad x = \sum_{r=1}^N x^r q_r$$

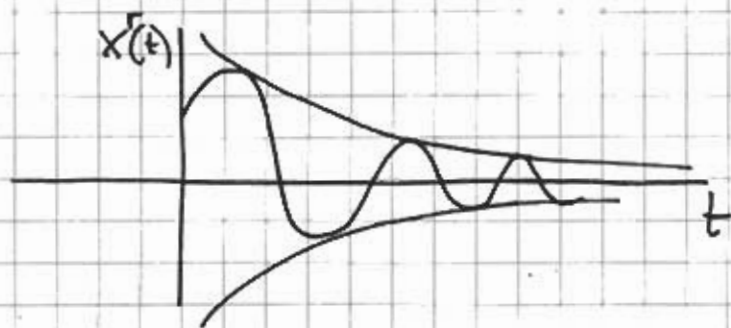
Assume c has same eigenvectors as K .

$$\ddot{x}^r + 2\zeta_r \omega_r \dot{x}^r + \omega_r^2 x^r = 0$$

→ eqns of evolution decouple mode by mode.

$$x^r(t) = e^{-\zeta_r \omega_r t} (A^r e^{i\omega_d^r t} + B^r e^{-i\omega_d^r t})$$

$$\omega_d^r = \omega_r \sqrt{1 - \zeta_r^2}$$



$$T = \frac{2\pi}{\omega_d} = \text{period}$$

(Hughes, 1983)

$$\left. \begin{aligned} x_{n+1} &= x_n + \Delta t v_n + \left[\left(\frac{1}{2} - \beta \right) a_n + \beta a_{n+1} \right] \Delta t^2 \\ v_{n+1} &= v_n + \Delta t \left[(1-\gamma) a_n + \gamma a_{n+1} \right] \\ M a_{n+1} + C v_{n+1} + K x_{n+1} &= 0 \end{aligned} \right\} \text{Newmark's Alg.}$$

SD \rightarrow

$$\left\{ \begin{aligned} x_{nr}^r &= x_n^r + \Delta t v_n^r + \left[\left(\frac{1}{2} - \beta \right) a_n^r + \beta a_{n+1}^r \right] \Delta t^2 \\ v_{nr}^r &= v_n^r + \Delta t \left[(1-\gamma) a_n^r + \gamma a_{n+1}^r \right] \\ \cancel{M a_{nr}^r} + \cancel{C v_{nr}^r} + 2\zeta_r \omega_r v_{nr}^r + \omega_r^2 x_{nr}^r &= 0 \end{aligned} \right.$$

$$r = 1, \dots, N$$

\rightarrow Newmark's eqs. decouple mode by mode!
Amplification matrix (drop "r")

$$\underbrace{\begin{pmatrix} 1 + \beta \Omega^2 & 2\beta \zeta \Omega^2 \\ \gamma \Omega & 1 + 2\gamma \zeta \Omega \end{pmatrix}^{-1}}_{F(\Delta t) \quad P^{-1}} \underbrace{\begin{pmatrix} 1 - \left(\frac{1}{2} - \beta \right) \Omega^2 & \Omega - 2 \left(\frac{1}{2} - \beta \right) \zeta \Omega^2 \\ -(1-\gamma) \Omega & 1 - 2(1-\gamma) \zeta \Omega \end{pmatrix}}_Q \quad \Omega = \omega \Delta t$$

$$\left\{ \begin{array}{l} \|F(\Delta t)\| < 1 \Rightarrow \text{eigenvalues } |\mu_{1,2}| < 1 \\ \mu_{1,2} = A_1 \pm \sqrt{A_1^2 - A_2} \\ A_1 = 1 - \left[\frac{1}{2} \left(\gamma + \frac{1}{2} \right) \Omega^2 + \xi \Omega \right] / D \\ A_2 = 1 - \left[\left(\gamma - \frac{1}{2} \right) \Omega^2 + 2\xi \Omega \right] / D \\ D = 1 + 2\xi \Omega + \beta \Omega^2 \end{array} \right.$$

Classification of regimes:

i) $A_1^2 < A_2 \Rightarrow \mu_{1,2}$ are complex conjugate

$$\text{Express } \mu_{1,2} = e^{-\bar{\xi} \bar{\omega} \Delta t} e^{\pm i \bar{\omega} \Delta t}$$

$$\Rightarrow y_n = e^{-\bar{\xi} \bar{\omega} t_n} (C_1 e^{i \bar{\omega} t_n} + C_2 e^{-i \bar{\omega} t_n})$$

which has the same form as $y(t_n)$ but errors in $\bar{\xi}, \bar{\omega}$.

$$\bar{\xi} = -\log A_2 / 2 \bar{\omega}$$

Say $\zeta = 0$ $\bar{\zeta} = \frac{1}{2} \left(\gamma - \frac{1}{2} \right) \Omega + O(\Omega^3)$

$\gamma > \frac{1}{2}$ numerical dissipation
damps more the higher modes.
(may be beneficial)

$\bar{T} = \frac{2\pi}{\omega_0} \neq T = \frac{2\pi}{\omega_0}$, Typically $\bar{T} > T$
(period elongation)

$\gamma > \frac{1}{2} \quad \beta > \frac{\gamma}{2} \Rightarrow$ unconditional stability

$\beta > \frac{1}{4} \left(\gamma + \frac{1}{2} \right)^2 \Rightarrow$ oscillatory solution

Otherwise

$$\Delta t_c = \frac{\zeta \left(\gamma - \frac{1}{2} \right) + \left[\frac{\gamma}{2} - \beta + \zeta^2 \left(\gamma - \frac{1}{2} \right)^2 \right]^{1/2}}{\left(\frac{\gamma}{2} - \beta \right)} \frac{1}{\omega_0}$$

Choice of time step

i) Explicit dynamics $\beta = 0 \quad \gamma = \frac{1}{2}$

$$\boxed{\Delta t \sim \Delta t_c}$$

ii) Stiff systems $x^r \sim 0$ for $r \geq m$
(structural dynamics)



→ Implicit dynamics

$$\Delta t \sim \frac{T_m}{20}$$

Ray's bounding principle

$$\omega_{\max}^2 = \max_{x \in \mathbb{R}^N} \frac{x^T K x}{x^T M x}$$



Consider extended

$$\bar{x} = \{x^e\}_{e=1}^E \text{ incompatible}$$



$$\bar{K} = \text{diag} \{K^e\}, \quad \bar{M} = \text{diag} \{M^e\}$$

$$\text{If } \bar{x} \text{ compatible} \Rightarrow \frac{\bar{x}^T \bar{K} \bar{x}}{\bar{x}^T \bar{M} \bar{x}} = \frac{x^T K x}{x^T M x}$$

$$\bar{\omega}_{\max}^2 = \max_{\bar{x}} \frac{\bar{x}^T \bar{K} \bar{x}}{\bar{x}^T \bar{M} \bar{x}} \geq \omega_{\max}^2$$

why? because \bar{x} are

a subset of x .

$$\Rightarrow \bar{\omega}_{\max}^2 = \max_{\bar{x}} \frac{\sum_e (x_e)^T K_e x_e}{\sum_e (x_e)^T M_e x_e}$$

$$\leq \max_e \left[\max_{x_e} \frac{(x_e)^T K_e x_e}{(x_e)^T M_e x_e} \right] = \max_e (\omega_{\max}^{e2})$$

$$\boxed{\bar{\omega}_{\max}^2 = \max_e (\omega_{\max}^{e2})}$$

max. eigenfrequency
of element e .