

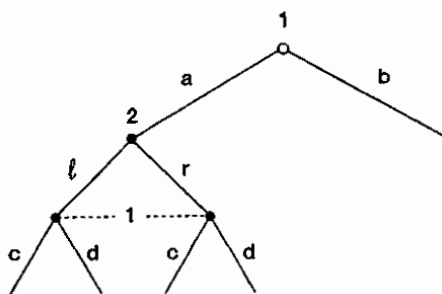
# Extensive Form Games

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# Extensive-Form Games

- ▶  $N$ : finite set of **players**; nature is player  $0 \in N$
- ▶ **tree**: order of moves
- ▶ **payoffs** for every player at the terminal nodes
- ▶ **information partition**
- ▶ **actions** available at every information set
- ▶ description of how actions lead to progress in the tree
- ▶ random moves by nature



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# Game Tree

- ▶  $(X, >)$ : **tree**
- ▶  $X$ : set of nodes
- ▶  $x > y$ : node  $x$  precedes node  $y$
- ▶  $\phi \in X$ : **initial** node,  $\phi > x, \forall x \in X \setminus \{\phi\}$
- ▶  $>$  transitive ( $x > y, y > z \Rightarrow x > z$ ) and asymmetric ( $x > y \Rightarrow y \not> x$ )
- ▶ every node  $x \in X \setminus \{\phi\}$  has one immediate predecessor:  $\exists x' > x$  s.t.  $x'' > x \ \& \ x'' \neq x' \Rightarrow x'' > x'$
- ▶  $Z = \{z \mid \nexists x, z > x\}$ : set of **terminal** nodes
- ▶  $z \in Z$  determines a unique path of moves through the tree, payoff  $u_i(z)$  for player  $i$

# Information Partition

- ▶ **information partition**: a partition of  $X \setminus Z$
- ▶ node  $x$  belongs to **information set**  $h(x)$
- ▶ player  $i(h) \in N$  moves at every node  $x$  in information set  $h$
- ▶  $i(h)$  knows that he is at some node of  $h$  but does not know which one
- ▶ same player moves at all  $x \in h$ , otherwise players might disagree on whose turn it is
- ▶  $i(x) := i(h(x))$

# Actions

- ▶  $A(x)$ : set of available **actions** at  $x \in X \setminus Z$  for player  $i(x)$
- ▶  $A(x) = A(x') =: A(h), \forall x' \in h(x)$  (otherwise  $i(h)$  might play an infeasible action)
- ▶ each node  $x \neq \phi$  associated with the last action taken to reach it
- ▶ every immediate successor of  $x$  labeled with a different  $a \in A(x)$  and vice versa
- ▶ move by nature at node  $x$ : probability distribution over  $A(x)$

# Strategies

- ▶  $H_i = \{h | i(h) = i\}$
- ▶  $S_i = \prod_{h \in H_i} A(h)$ : set of **pure strategies** for player  $i$
- ▶  $s_i(h)$ : action taken by player  $i$  at information set  $h \in H_i$  under  $s_i \in S_i$
- ▶  $S = \prod_{i \in N} S_i$ : **strategy profiles**
- ▶ A strategy is a complete **contingent plan** specifying the action to be taken at each information set.
- ▶ **Mixed strategies**:  $\sigma_i \in \Delta(S_i)$
- ▶ mixed strategy profile  $\sigma \in \prod_{i \in N} \Delta(S_i) \rightarrow$  probability distribution  $O(\sigma) \in \Delta(Z)$
- ▶  $u_i(\sigma) = \mathbb{E}_{O(\sigma)}(u_i(z))$

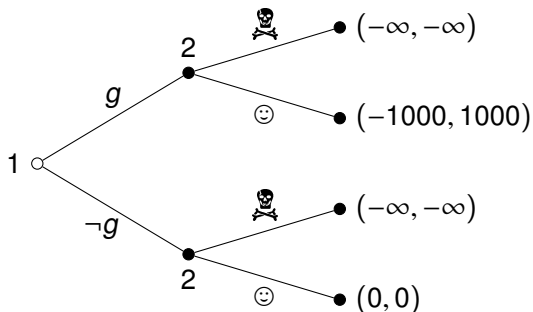
# Strategic Form

- ▶ The **strategic form representation** of the extensive form game is the normal form game defined by  $(N, S, u)$
- ▶ A mixed strategy profile is a **Nash equilibrium** of the extensive form game if it constitutes a Nash equilibrium of its strategic form.

# Grenade Threat Game

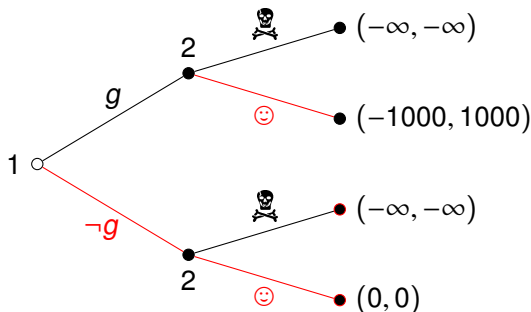
Player 2 threatens to explode a grenade if player 1 doesn't give him \$1000.

- ▶ Player 1 chooses between  $g$  and  $\neg g$ .
- ▶ Player 2 observes player 1's choice, then decides whether to explode a grenade that would kill both.





# Strategic Form Representation



$g$	$-\infty, -\infty$	$-\infty, -\infty$	$-1000, 1000^*$	$-1000, 1000$
$-g$	$-\infty, -\infty$	$0, 0^*$	$-\infty, -\infty$	$0, 0^*$

Three pure strategy Nash equilibria. Only  $(-g, \text{smiley}, \text{smiley})$  is **subgame perfect**.

is not a **credible** threat.

# Behavior Strategies

- ▶  $b_i(h) \in \Delta(A(h))$ : **behavior strategy** for player  $i(h)$  at information set  $h$
- ▶  $b_i(a|h)$ : probability of action  $a$  at information set  $h$
- ▶ behavior strategy  $b_i \in \prod_{h \in H_i} \Delta(A(h))$
- ▶ **independent mixing** at each information set
- ▶  $b_i$  outcome equivalent to the mixed strategy

$$\sigma_i(s_i) = \prod_{h \in H_i} b_i(s_i(h)|h) \quad (1)$$

- ▶ Is every mixed strategy equivalent to a behavior strategy?
- ▶ Yes, under **perfect recall**.

# Perfect Recall

No player forgets any information he once had or actions he previously chose.

- ▶ If  $x'' \in h(x')$ ,  $x > x'$ , and the same player  $i$  moves at both  $x$  and  $x'$  (and thus at  $x''$ ), then there exists  $\hat{x} \in h(x)$  (possibly  $\hat{x} = x$ ) s.t.  $\hat{x} > x''$  and the action taken at  $x$  along the path to  $x'$  is the same as the action taken at  $\hat{x}$  along the path to  $x''$ .
- ▶  $x'$  and  $x''$  distinguished by information  $i$  does not have, so he cannot have had it at  $h(x)$
- ▶  $x'$  and  $x''$  consistent with the same action at  $h(x)$  since  $i$  must remember his action there
- ▶ Equivalently, every node in  $h \in H_i$  must be reached via the same sequence of  $i$ 's actions.

# Equivalent Behavior Strategies

- ▶  $R_i(h) = \{s_i | h \text{ is on the path of } (s_i, s_{-i}) \text{ for some } s_{-i}\}$ : set of  $i$ 's pure strategies that do not preclude reaching information set  $h \in H_i$
- ▶ Under perfect recall, a mixed strategy  $\sigma_i$  is equivalent to a behavior strategy  $b_i$  defined by

$$b_i(a|h) = \frac{\sum_{\{s_i \in R_i(h) | s_i(h)=a\}} \sigma_i(s_i)}{\sum_{s_i \in R_i(h)} \sigma_i(s_i)} \quad (2)$$

when the denominator is positive.

## Theorem 1 (Kuhn 1953)

*In extensive form games with perfect recall, mixed and behavior strategies are outcome equivalent under the formulae (1) & (2).*

# Proof

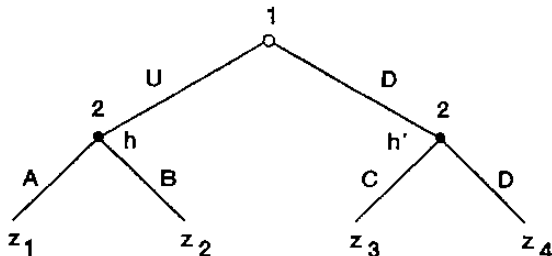
- ▶  $h_1, \dots, h_{\bar{k}}$ : player  $i$ 's information sets preceding  $h$  in the tree
- ▶ Under perfect recall, reaching any node in  $h$  requires  $i$  to take the same action  $a_k$  at each  $h_k$ ,

$$R_i(h) = \{s_i | s_i(h_k) = a_k, \forall k = \overline{1, \bar{k}}\}.$$

- ▶ Conditional on getting to  $h$ , the distribution of continuation play at  $h$  is given by the relative probabilities of the actions available at  $h$  under the restriction of  $\sigma_i$  to  $R_i(h)$ ,

$$b_i(a|h) = \frac{\sum_{\{s_i | s_i(h_k) = a_k, \forall k = \overline{1, \bar{k}} \text{ \& } s_i(h) = a\}} \sigma_i(s_i)}{\sum_{\{s_i | s_i(h_k) = a_k, \forall k = \overline{1, \bar{k}}\}} \sigma_i(s_i)}.$$

## Example

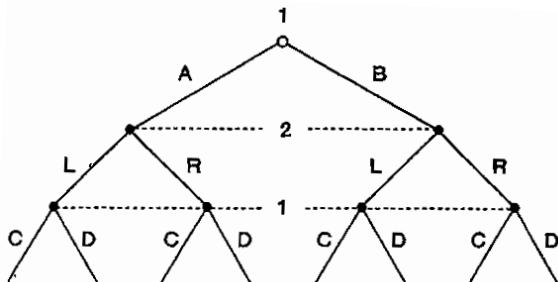


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**Figure:** Different mixed strategies can generate the same behavior strategy.

- ▶  $S_2 = \{(A, C), (A, D), (B, C), (B, D)\}$
- ▶ Both  $\sigma_2 = 1/4(A, C) + 1/4(A, D) + 1/4(B, C) + 1/4(B, D)$  and  $\sigma_2 = 1/2(A, C) + 1/2(B, D)$  generate—and are equivalent to—the behavior strategy  $b_2$  with  $b_2(A|h) = b_2(B|h) = 1/2$  and  $b_2(C|h') = b_2(D|h') = 1/2$ .

## Example with Imperfect Recall

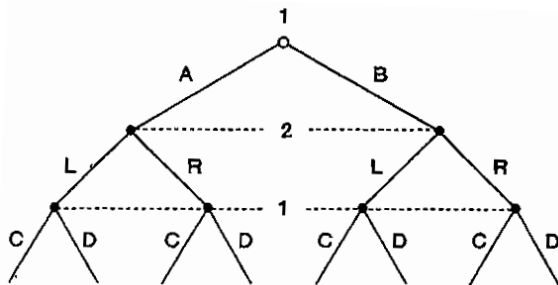


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Figure: Player 1 forgets what he did at the initial node.

- ▶  $S_1 = \{(A, C), (A, D), (B, C), (B, D)\}$
- ▶  $\sigma_1 = 1/2(A, C) + 1/2(B, D) \rightarrow b_1 = (1/2A + 1/2B, 1/2C + 1/2D)$
- ▶  $b_1$  **not** equivalent to  $\sigma_1$
- ▶  $(\sigma_1, L)$ : prob. 1/2 for paths  $(A, L, C)$  and  $(B, L, D)$
- ▶  $(b_1, L)$ : prob. 1/4 to paths  $(A, L, C), (A, L, D), (B, L, C), (B, L, D)$

# Imperfect Recall and Correlations



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- ▶ Since both  $A$  vs.  $B$  and  $C$  vs.  $D$  are choices made by player 1, the strategy  $\sigma_1$  under which player 1 makes all his decisions at once allows choices at different information sets to be correlated
- ▶ Behavior strategies cannot produce this correlation, because when it comes time to choose between  $C$  and  $D$ , player 1 has forgotten whether he chose  $A$  or  $B$ .



# Absent Minded Driver

Piccione and Rubinstein (1997)

- ▶ A drunk driver has to take the third out of five exits on the highway (exit 3 has payoff 1, other exits payoff 0).
- ▶ The driver cannot read the signs and forgets how many exits he has already passed.
- ▶ At each of the first four exits, he can choose  $C$  (continue) or  $E$  (exit). . . imperfect recall: choose same action.
- ▶  $C$  leads to exit 5, while  $E$  leads to exit 1.
- ▶ Optimal solution involves randomizing: probability  $p$  of choosing  $C$  maximizes  $p^2(1 - p)$ , so  $p = 2/3$ .
- ▶ “Beliefs” given  $p = 2/3$ :  $(27/65, 18/65, 12/65, 8/65)$
- ▶  $E$  has conditional “expected” payoff of  $12/65$ ,  $C$  has 0. Optimal strategy:  $E$  with probability 1, inconsistent.

# Conventions

- ▶ Restrict attention to games with perfect recall, so we can use mixed and behavior strategies interchangeably.
- ▶ Behavior strategies are more convenient.
- ▶ Drop notation  $b$  for behavior strategies and denote by  $\sigma_i(a|h)$  the probability with which player  $i$  chooses action  $a$  at information set  $h$ .

# Survivor

## THAI 21

- ▶ Two players face off in front of 21 flags.
- ▶ Players alternate in picking 1, 2, or 3 flags at a time.
- ▶ The player who successfully grabs the last flag wins.

Game of luck?

# Backward Induction

- ▶ An extensive form game has **perfect information** if all information sets are singletons.
- ▶ Can solve games with perfect information using **backward induction**.
- ▶ Finite game  $\rightarrow \exists$  penultimate nodes (successors are terminal nodes).
- ▶ The player moving at each penultimate node chooses an action that maximizes his payoff.
- ▶ Players at nodes whose successors are penultimate/terminal choose an optimal action given play at penultimate nodes.
- ▶ Work backwards to initial node. . .

## Theorem 2 (Zermelo 1913; Kuhn 1953)

*In a finite extensive form game of perfect information, the outcome(s) of backward induction constitutes a pure-strategy Nash equilibrium.*

# Market Entrance

- ▶ **Incumbent** firm 1 chooses a level of capital  $K_1$  (which is then fixed).
- ▶ A potential **entrant**, firm 2, observes  $K_1$  and chooses its capital  $K_2$ .
- ▶ The profit for firm  $i = 1, 2$  is  $K_i(1 - K_1 - K_2)$  (firm  $i$  produces output  $K_i$ , we use earlier demand function).
- ▶ Each firm dislikes capital accumulation by the other.
- ▶ A firm's *marginal* value of capital decreases with the other's.
- ▶ Capital levels are **strategic substitutes**.

# Stackelberg Competition

- ▶ Profit maximization by firm 2 requires

$$K_2 = \frac{1 - K_1}{2}.$$

- ▶ Firm 1 **anticipates** that firm 2 will act optimally, and therefore solves

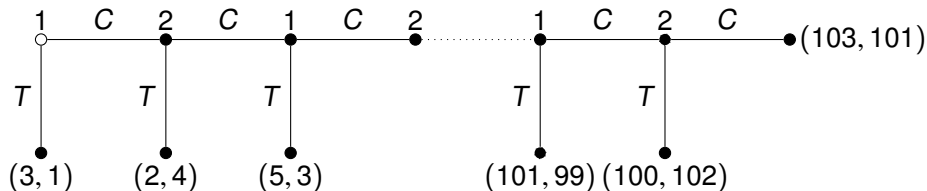
$$\max_{K_1} \left\{ K_1 \left( 1 - K_1 - \frac{1 - K_1}{2} \right) \right\}.$$

- ▶ Solution involves  $K_1 = 1/2$ ,  $K_2 = 1/4$ ,  $\pi_1 = 1/8$ , and  $\pi_2 = 1/16$ .
- ▶ Firm 1 has **first mover advantage**.
- ▶ In contrast, in the simultaneous move game,  $K_1 = 1/3$ ,  $K_2 = 1/3$ ,  $\pi_1 = 1/9$ , and  $\pi_2 = 1/9$ .

# Centipede Game

- ▶ Player 1 has two piles in front of her: one contains 3 coins, the other 1.
- ▶ Player 1 can either take the larger pile and give the smaller one to player 2 ( $T$ ) or push both piles across the table to player 2 ( $C$ ).
- ▶ Every time the piles pass across the table, one coin is added to each.
- ▶ Players alternate in choosing whether to take the larger pile ( $T$ ) or trust opponent with bigger piles ( $C$ ).
- ▶ The game lasts 100 rounds.

What's the backward induction solution?



# Chess Players and Backward Induction

Palacios-Huerta and Volij (2009)

- ▶ chess players and college students behave differently in the centipede game.
- ▶ Higher-ranked chess players end the game earlier.
- ▶ All Grandmasters in the experiment stopped at the first opportunity.
- ▶ Chess players are familiar with backward induction reasoning and need less learning to reach the equilibrium.
- ▶ Playing against non-chess-players, even chess players continue in the game longer.
- ▶ In long games, common knowledge of the ability to do complicated inductive reasoning becomes important for the prediction.



# Subgame Perfection

- ▶ Backward induction solution is more than a Nash equilibrium.
- ▶ Actions are optimal given others' play—and form an equilibrium—starting at *any* intermediate node: **subgame perfection**. . . rules out non-credible threats.
- ▶ Subgame perfection extends backward induction to imperfect information games.
- ▶ Replace “smallest” subgames with a Nash equilibrium and iterate on the reduced tree (if there are multiple Nash equilibria in a subgame, all players expect same play).

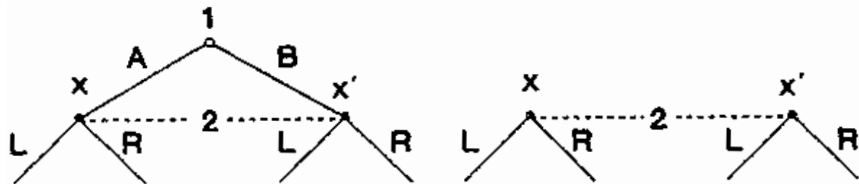
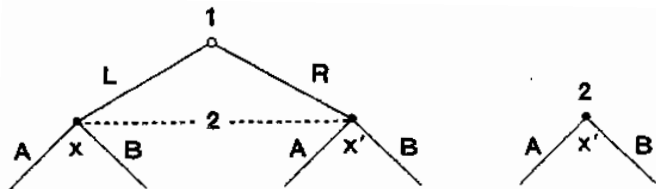
# Subgames

Subgame: part of a game that can be analyzed separately; strategically and informationally independent. . . information sets not “chopped up.”

## Definition 1

A **subgame**  $G$  of an extensive form game  $T$  consists of a single node  $x$  and *all* its successors in  $T$ , with the property that if  $x' \in G$  and  $x'' \in h(x')$  then  $x'' \in G$ . The information sets, actions and payoffs in the subgame are inherited from  $T$ .

# False Subgames



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# Subgame Perfect Equilibrium

$\sigma$ : behavior strategy in  $T$

- ▶  $\sigma|G$ : the strategy profile induced by  $\sigma$  in subgame  $G$  of  $T$  (start play at the initial node of  $G$ , follow actions specified by  $\sigma$ , obtain payoffs from  $T$  at terminal nodes)
- ▶ Is  $\sigma|G$  a Nash equilibrium of  $G$  for any subgame  $G$ ?

## Definition 2

A strategy profile  $\sigma$  in an extensive form game  $T$  is a **subgame perfect equilibrium** if  $\sigma|G$  is a Nash equilibrium of  $G$  for every subgame  $G$  of  $T$ .

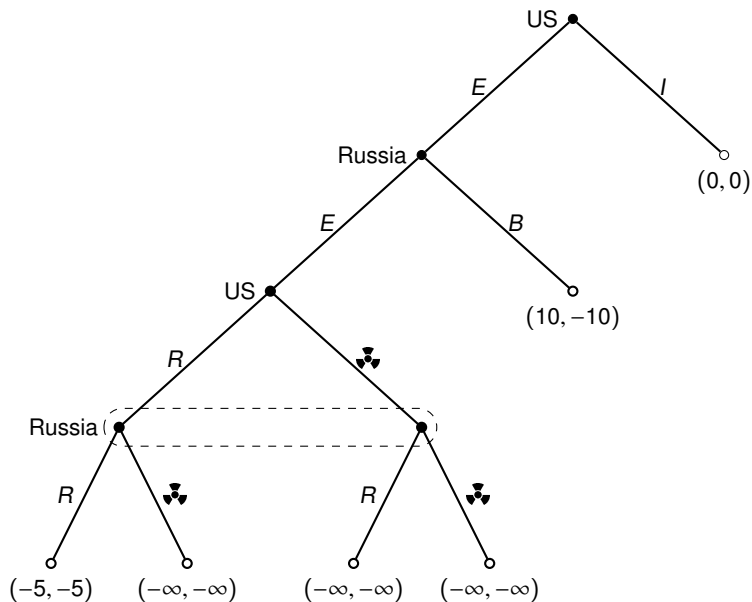
- ▶ Any game is a subgame of itself  $\rightarrow$  a subgame perfect equilibrium is a Nash equilibrium.
- ▶ Subgame perfection coincides with backward induction in games of perfect information.

# Nuclear Crisis

Russia provokes the US...



- ▶ The U.S. can choose to escalate ( $E$ ) or end the game by ignoring the provocation ( $I$ ).
- ▶ If the game escalates, Russia faces a similar choice: to back down ( $B$ ), but lose face, or escalate ( $E$ ).
- ▶ Escalation leads to nuclear crisis: a simultaneous move game where each nation chooses to either retreat ( $R$ ) and lose credibility or detonate ( $\blacklozenge$ ). Unless both countries retreat, retaliation to the first nuclear strike culminates in nuclear disaster, which is infinitely costly.

# The Extensive Form

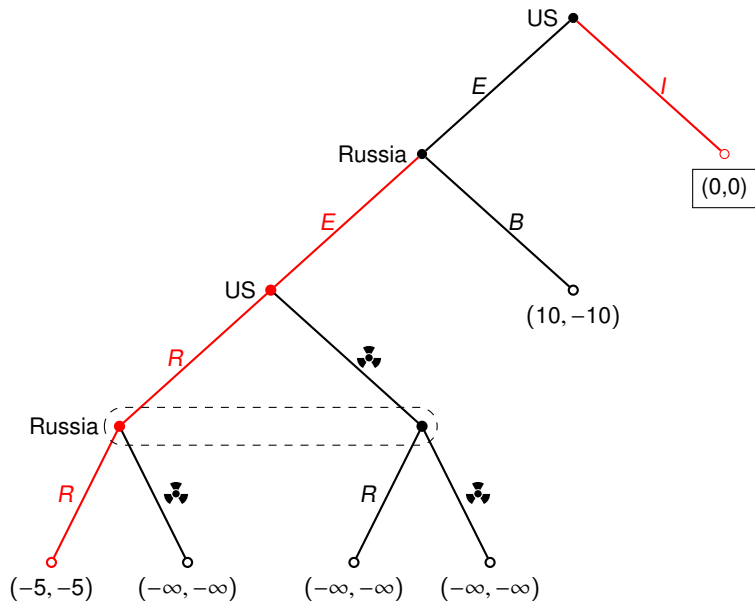


# Last Stage

The simultaneous-move game at the last stage has two Nash equilibria.

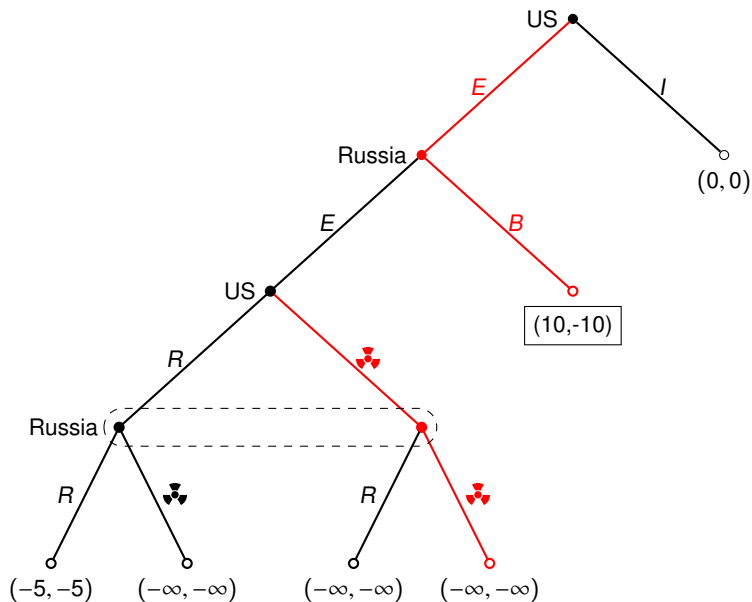
	R	
R	$-5, 5^*$	$-\infty, -\infty$
	$-\infty, -\infty$	$-\infty, -\infty^*$

# One Subgame Perfect Equilibrium





# Another Subgame Perfect Equilibrium



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