
Global Games

14.126 Game Theory
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Motivation

- Multiple equilibria exist in settings with strategic complementarities
 - Investment/Development
 - Search
 - Bank runs
 - Currency attacks
- Global Games: introducing a certain type of incomplete information leads to a unique equilibrium prediction.

A partnership game

| | Invest | Not-Invest |
|------------|------------------|-----------------|
| Invest | θ, θ | $\theta - 1, 0$ |
| Not-Invest | $0, \theta - 1$ | $0, 0$ |

θ is common knowledge

$$\theta < 0$$

| | Invest | Not-Invest |
|------------|------------------|-----------------|
| Invest | θ, θ | $\theta - 1, 0$ |
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θ is common knowledge

$$\theta > 1$$

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|-----------|------------------|-----------------|
| Invest | θ, θ | $\theta - 1, 0$ |
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θ is common knowledge

$$0 < \theta < 1$$

Multiple Equilibria

| | Invest | Not-Invest |
|------------|------------------|-----------------|
| Invest | θ, θ | $\theta - 1, 0$ |
| Not-Invest | $0, \theta - 1$ | $0, 0$ |

θ is common knowledge

Not-Invest

Multiple
Equilibria

Invest



θ is **not** common knowledge

- θ is uniformly distributed over a large interval
- Each player i gets a signal

$$x_i = \theta + \varepsilon \eta_i$$

- (η_1, η_2) is bounded
- Independent of θ
- iid with continuous F (common knowledge)
- $E[\eta_i] = 0$

Recall: Monotone supermodular games

- $G = (N, T, A, u, p)$
- $T = T_0 \times T_1 \times \dots \times T_n (\subseteq \mathbb{R}^M)$
- A_j compact sublattice of \mathbb{R}^K
- $u_j: A \times T \rightarrow \mathbb{R}$
 - $u_j(a, \cdot): T \rightarrow \mathbb{R}$ is measurable
 - $u_j(\cdot, t): A \rightarrow \mathbb{R}$ is continuous, “bounded”, supermodular in a_j , has increasing differences in a and in (a_j, t)
- $p(\cdot | t_j)$ is increasing function of t_j —in the sense of 1st-order stochastic dominance (e.g. p is affiliated).
- Theorem: There exist BNE s^* and s^{**} such that
 - For each BNE s , $s^* \geq s \geq s^{**}$.
 - Both s^* and s^{**} are isotone.

Conditional Beliefs given x_i

$$\theta =_d x_i - \varepsilon \eta_i$$

- i.e. $\Pr(\theta \leq \theta' | x_i) = 1 - F((x_i - \theta')/\varepsilon) := G(\theta' | x_i)$

$$x_j =_d x_i + \varepsilon(\eta_j - \eta_i)$$

- $\Pr(x_j \leq x_j' | x_i) = \Pr(\varepsilon(\eta_j - \eta_i) \leq x_j' - x_i)$
- $\Pr(\theta \leq \theta', x_j \leq x_j' | x_i) = \int 1_{\{\theta \leq \theta'\}} F((x_j' - \theta)/\varepsilon) dG(\theta | x_i)$ decreasing in x_i because integrand decreasing in θ and $G(\cdot | x_i)$ FOSD $G(\cdot | x_i')$ whenever $x_i \geq x_i'$
- $\mathbb{E}[\theta | x_i] = x_i$

Payoffs

| | Invest | Not-Inv |
|---------|----------|--------------|
| Invest | θ | $\theta - 1$ |
| Not-Inv | 0 | 0 |

- Invest $>$ Not-Invest
- $U_i(a_i, a_j, \theta, x)$ is supermodular.
- Monotone supermodular
- There exist greatest and smallest rationalizable strategies, which are
 - Bayesian Nash Equilibria
 - Monotone (isotone)

Monotone BNE

- Best response

Invest iff $x_i \geq \Pr(s_j = \text{Not-Invest}|x_i)$

- Assume $\text{supp}(\theta) = [a, b]$ where $a < 0 < 1 < b$.

- $x_i < 0 \Rightarrow s_i(x_i) = \text{Not Invest}$

- $x_i > 1 \Rightarrow s_i(x_i) = \text{Invest}$

- A cutoff x_i^* s.t.

- $x_i < x_i^* \Rightarrow s_i(x_i) = \text{Not Invest}; x_i > x_i^* \Rightarrow s_i(x_i) = \text{Invest}$

- Symmetry: $x_1^* = x_2^* = x^*$

- $x^* = \Pr(s_j = \text{Not-Invest}|x^*) = \Pr(x_j < x^* | x_i = x^*) = 1/2$

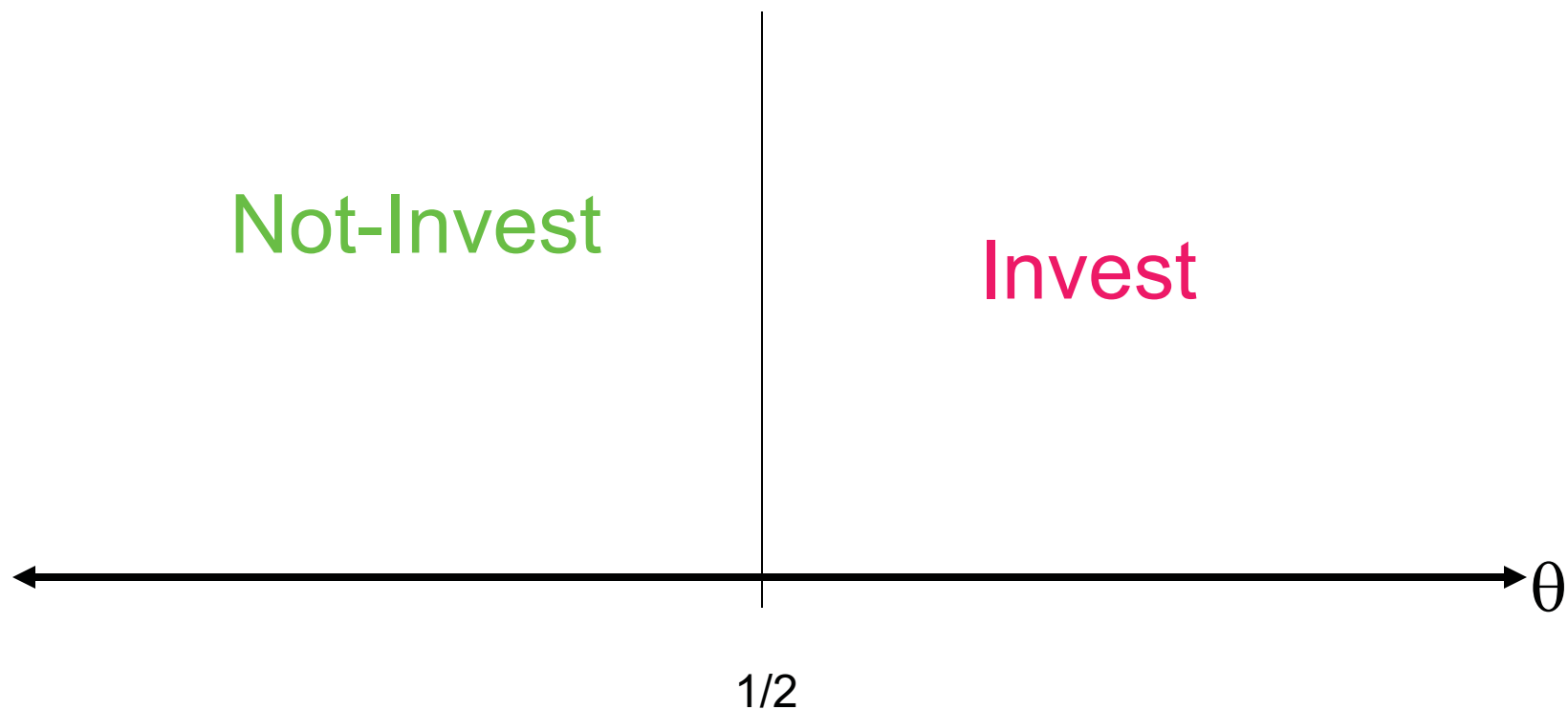
- “Unique” BNE

Questions

- What is the smallest BNE?
- What is the largest BNE?
- Which strategies are rationalizable?
- Compute directly.

θ is **not** common knowledge
but the noise is very small

It is very likely that



Risk-dominance

- In a 2 x 2 symmetric game, a strategy is said to be “risk dominant” iff it is a best reply when the other player plays each strategy with equal probabilities.

| | Invest | Not-Invest |
|------------|------------------|-----------------|
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Invest is RD iff
 $0.5\theta + 0.5(\theta - 1) > 0$
 $\Leftrightarrow \theta > 1/2$

Players play according to risk dominance

Carlsson & van Damme

Risk Dominance

| | A | B |
|---|------------------|------------------|
| A | u_{11}, v_{11} | u_{12}, v_{12} |
| B | u_{21}, v_{21} | u_{22}, v_{22} |

| | A | B |
|---|----------------|----------------|
| A | g_1^a, g_2^a | 0,0 |
| B | 0,0 | g_1^b, g_2^b |

- Suppose that (A,A) and (B,B) are NE.
- (A,A) is risk dominant if
 - $(u_{11}-u_{21})(v_{11}-v_{12})$
 - $(u_{22}-u_{12})(v_{22}-v_{21})$
- Affine transformation: $g_1^a \dots$
- (A,A) risk dominant if
 - $g_1^a g_2^a > g_1^b g_2^b$
- i is indifferent against \underline{s}_j ; (A,A) risk dominant if
 - $\underline{s}_1 + \underline{s}_2 < 1$

Dominance, risk-dominance regions

- Dominance region

$$D_i^a = \{(u, v) \mid g_i^a > 0, g_i^b < 0\}$$

- Risk-dominance region

$$R^a = \{(u, v) \mid g_1^a > 0, g_2^a > 0; g_1^b, g_2^b > 0 \Rightarrow \underline{s}_1 + \underline{s}_2 < 1\}$$

Model

- $\Theta \subseteq \mathcal{R}^m$ is open; (u, v) are continuously differentiable functions of θ w/ bounded derivatives;
- prior on θ has a density h which is strictly positive, continuously differentiable, bounded.
- Each player i observes a signal

$$x_i = \theta + \varepsilon \eta_i$$

- (η_1, η_2) is bounded,
- Independent of θ ,
- Admits a continuous density

Theorem

- Suppose that
 - x is on a continuous curve $C \subseteq \Theta$
 - $(u(c), v(c)) \in R^a$ for each $c \in C$
 - $(u(c), v(c)) \in D^a$ for some $c \in C$.
- Then A is the only rationalizable action at x when ε is small.

“Public” Information

- $\theta \sim N(y, \tau^2)$ and $\varepsilon_i \sim N(0, \sigma^2)$

- Given x_i ,

$$\begin{aligned}\theta &\sim N(rx_i + (1-r)y, \sigma^2 r) \\ x_j &\sim N(rx_i + (1-r)y, \sigma^2(r+1)) \\ r &= \tau^2 / (\sigma^2 + \tau^2)\end{aligned}$$

- (Monotone supermodularity) monotone symmetric NE w/cutoff x^c :

$$rx^c + (1-r)y = \Pr(x_j \leq x^c \mid x_i = x^c) = \Phi\left(\frac{(1-r)(x^c - y)}{\sigma\sqrt{r+1}}\right)$$

- Unique monotone NE (and rationalizable strategy) if

$$rx^c + (1-r)y - \Pr(x_j \leq x^c \mid x_i = x^c)$$

is increasing in x^c whenever zero, i.e.,

$$\sigma^2 < 2\pi\tau^4(r+1)$$

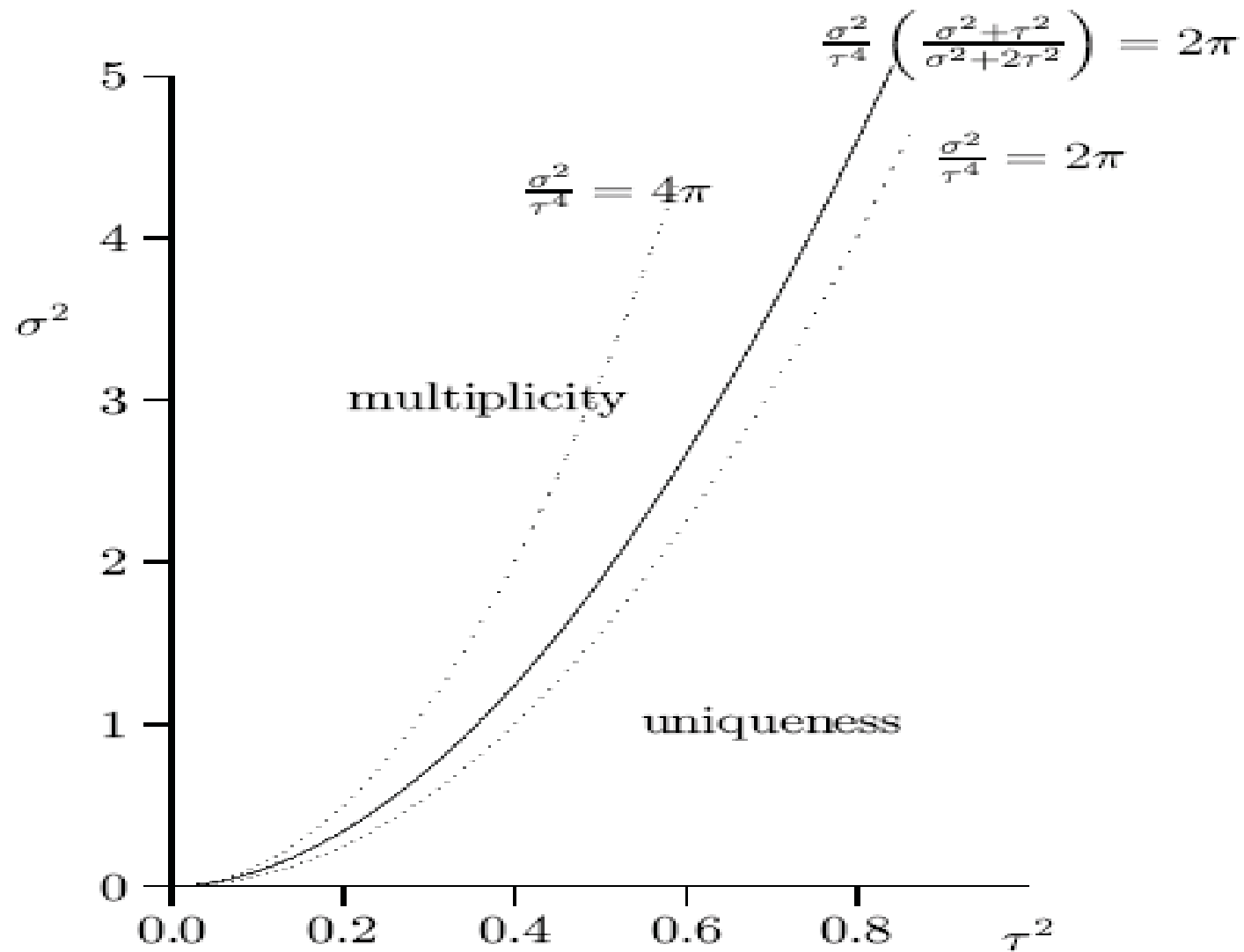


Figure 3.1: Parameter Range for Unique Equilibrium

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