

Abstract Interpretation and the Heap

Computer Science and Artificial Intelligence Laboratory
MIT

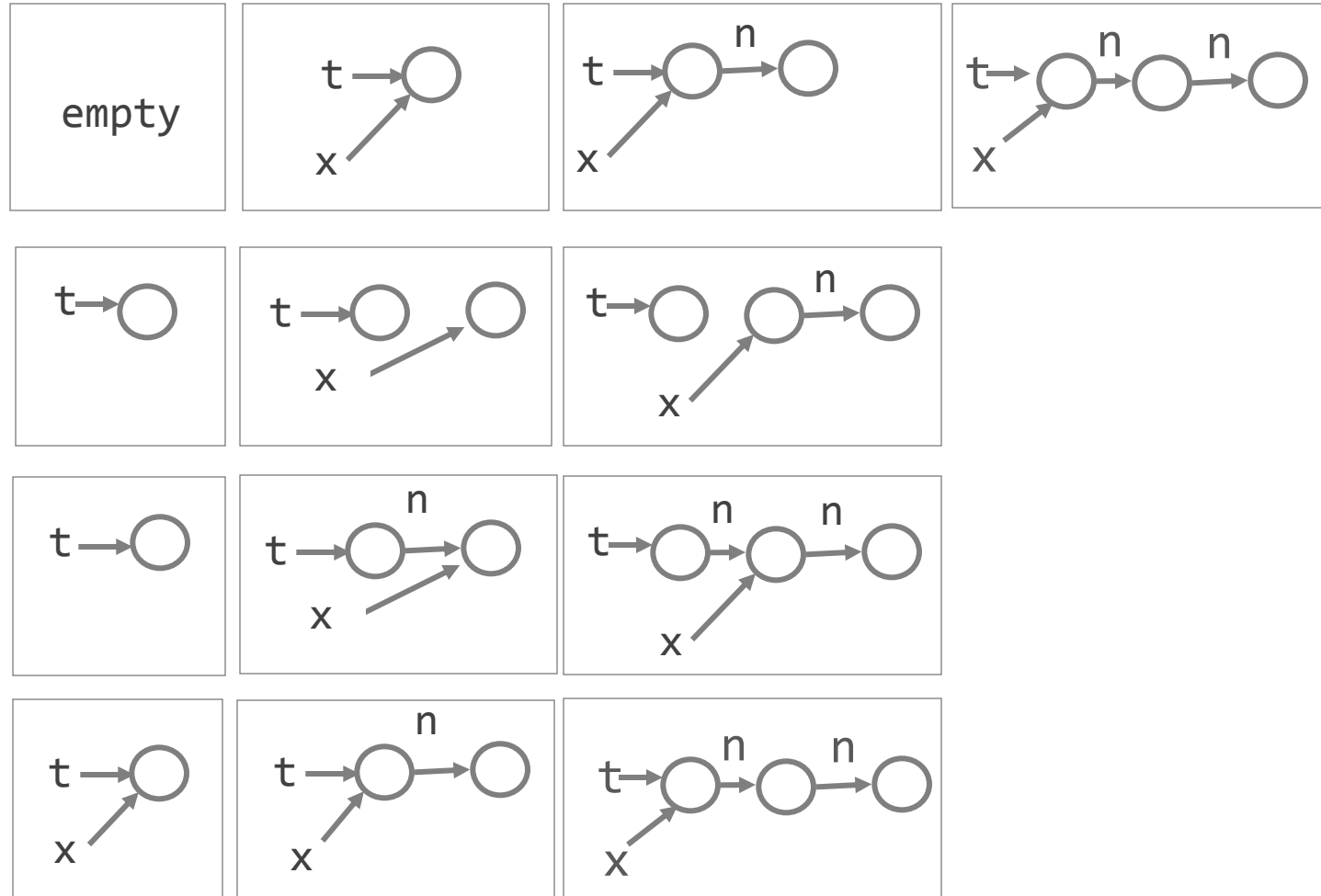
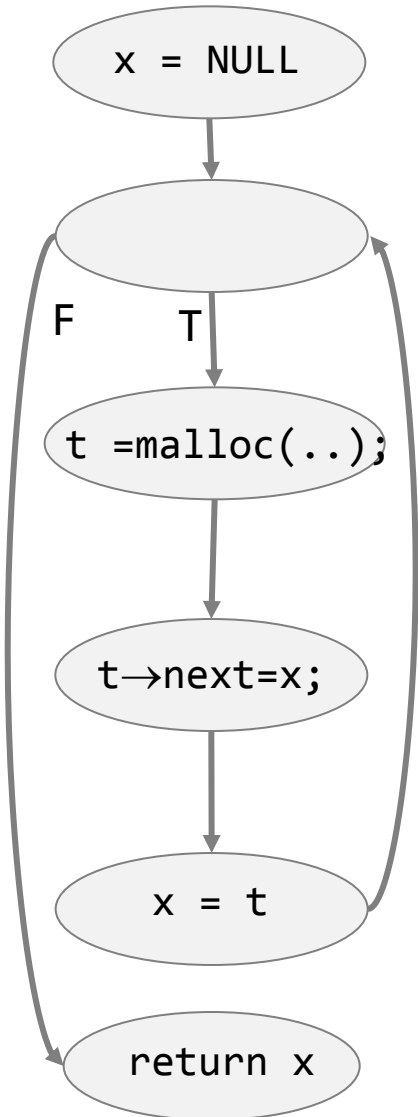
With slides and examples by Mooly Sagiv.
Used with permission.

Nov 18, 2015

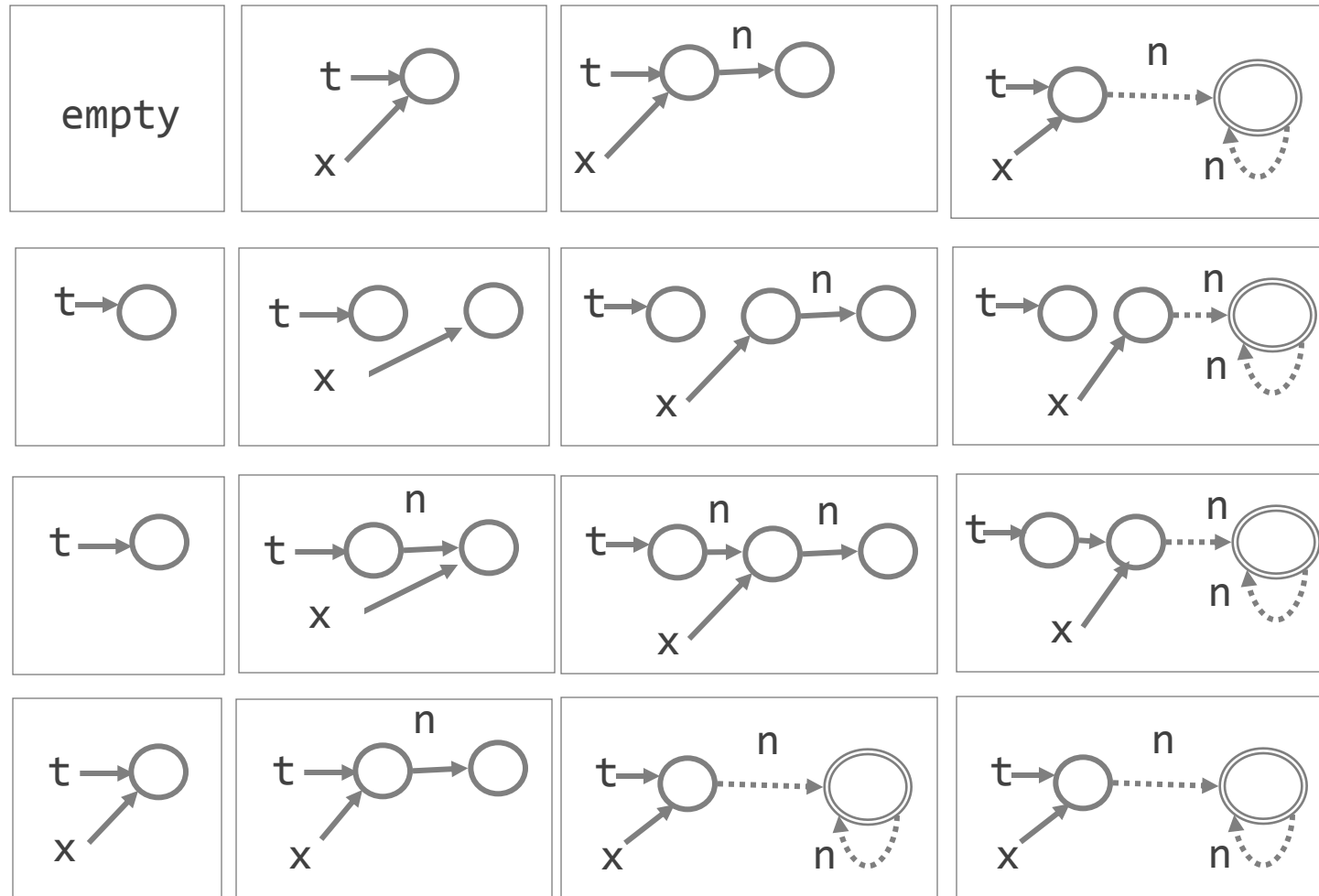
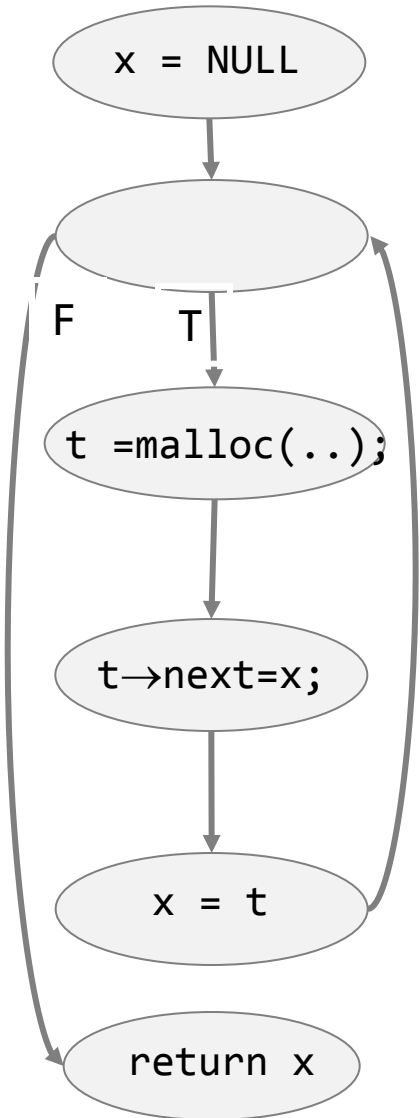
Recap: Collecting Semantics

Compute for each program the true set of states that can occur at each point

Example: Collecting Interpretation



Example: Abstract Interpretation



Concrete Interpretation

A slightly different view of the state

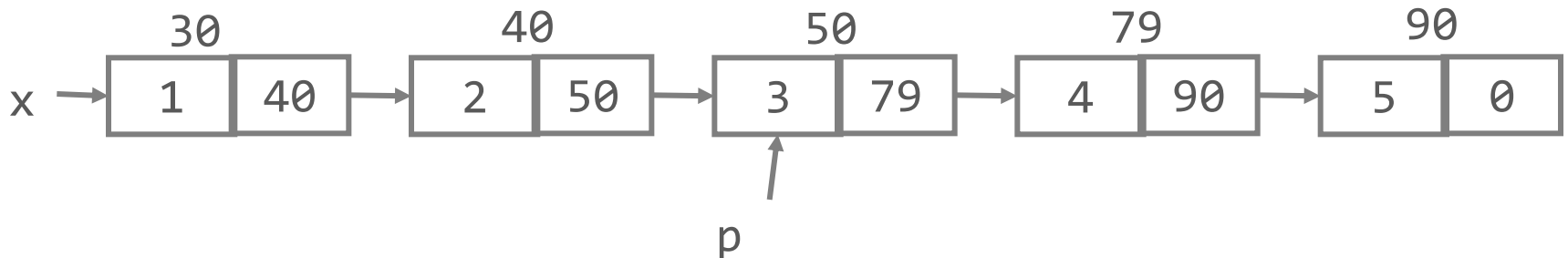
- Env: $Var \rightarrow Values$
- One map per field
- Field: $Loc \rightarrow Values$
- $Values = Loc \cup Atoms$

Example

- Env = $[x \rightarrow 30, p \rightarrow 79]$
- Fields:

next = $[30 \rightarrow 40, 40 \rightarrow 50, 50 \rightarrow 79, 79 \rightarrow 90]$

val = $[30 \rightarrow 1, 40 \rightarrow 2, 50 \rightarrow 3, 79 \rightarrow 4, 90 \rightarrow 5]$



The TVLA Approach

Represent the store with logical predicates

- Then do abstraction on these predicates
- An approach to building abstractions instead of a single one

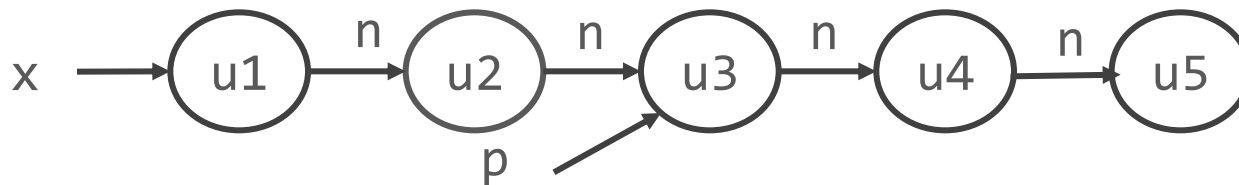
Locations \approx Individuals

Program variables \approx Unary predicates

Fields \approx Binary predicates

Example

- $U = \{u1, u2, u3, u4, u5\}$
- $x = \{u1\}, p = \{u3\}$
- $n = \{\langle u1, u2 \rangle, \langle u2, u3 \rangle, \langle u3, u4 \rangle, \langle u4, u5 \rangle\}$



Important notation

Transitive closure of a binary predicate $n(u, v)$

- $n^*(u, v) := u = v \vee (\exists w. n(u, w) \wedge n^*(w, v))$
- $n^+(u, v) := (\exists w. n(u, w) \wedge n^*(w, v))$

Concrete Interpretation

State:

- x : predicate for variable x .
- n : predicate for next field

Rules $\llbracket s \rrbracket(x, n) = (x', n')$

- $\llbracket x = \text{null} \rrbracket \quad n' = n \quad \forall v. x'(v) = 0$
- $\llbracket x = \text{malloc}() \rrbracket \quad n' = n \quad \forall v. x'(v) = \text{IsNew}(v)$
- $\llbracket x = y \rrbracket \quad n' = n \quad \forall v. x'(v) = y(v)$
- $\llbracket x = y.\text{next} \rrbracket \quad n' = n \quad \forall v. x'(v) = \exists w. y(w) \wedge n(w, v)$
- $\llbracket x.\text{next} = y \rrbracket \quad x' = x \quad \forall v w. n'(v, w) = (\neg x(v) \wedge n(v, w)) \vee (x(v) \wedge y(w))$

Stating program properties

x points to an acyclic list

$$- \forall v w. x(v) \wedge n^*(v, w) \rightarrow \neg n^+(w, v)$$

The heap n' reverses the list pointed at by x in n

$$- \forall v w r. x(v) \wedge n^*(v, w) \rightarrow (n(w, r) \leftrightarrow n'(r, w))$$

Canonical Abstraction

Convert logical structures of unbounded size into bounded size

Guarantees that number of logical structures in every program is finite

Every first-order formula can be conservatively interpreted

Same idea we explored last time, but revisited in Three Valued Logic

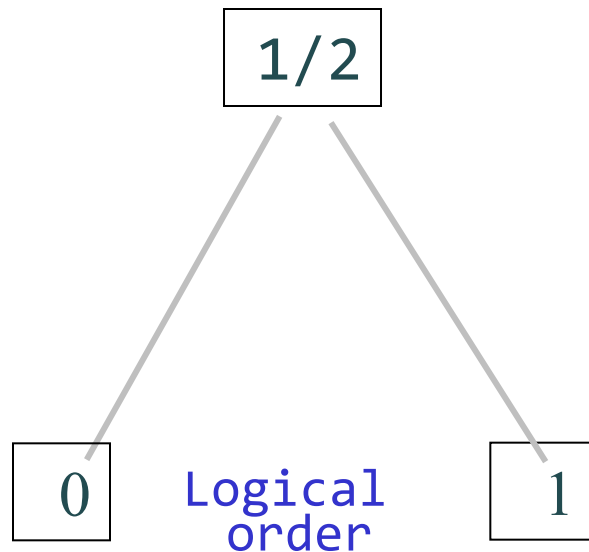
Kleene Three-Valued Logic

1: True

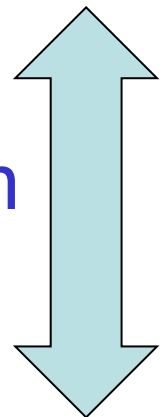
0: False

1/2: Unknown

A join semi-lattice: $0 \sqcup 1 = 1/2$



Information order



Boolean Connectives [Kleene]

\wedge	0	1/2	1
0	0	0	0
1/2	0	1/2	1/2
1	0	1/2	1

\vee	0	1/2	1
0	0	1/2	1
1/2	1/2	1/2	1
1	1	1	1

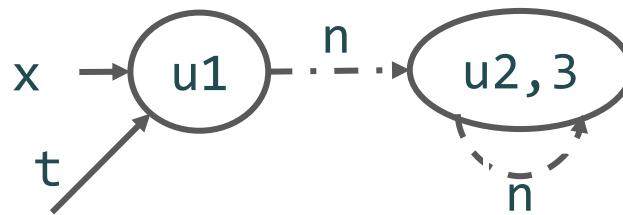
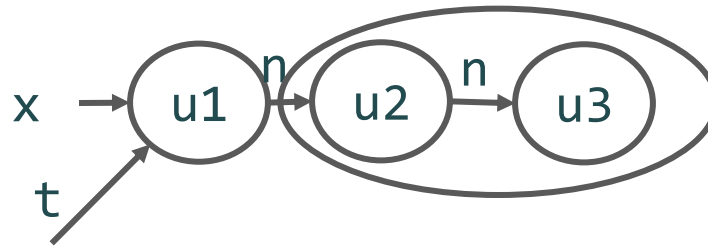
Key idea

Predicates describing program state are now predicates in 3-Valued Logic

- Let U be the set of individuals in the concrete domain (potentially infinite)
- Let U' be the set of individuals in the abstract domain (finite)
- Let $f: U \rightarrow U'$
- Then a predicate p^B over U can be abstracted to p^S over U' as follows
$$p^S(u'_1, \dots, u'_k) = \sqcup \{p^B(u_1, \dots, u_k) \mid f(u_1) = u'_1, \dots, f(u_k) = u'_k\}$$
- Since U' is bounded, p^S can be represented with a table

Canonical Abstraction

```
x = NULL;
while (...) do {
  t = malloc();
  t →next=x;
  x = t
}
```



$n(u1, u2)=1$
 $n(u1, u3)=0$
 $n(u2, u3)=1$
 $n(u3, u3)=0$

$ns(u1, u23)=1/2$
 $n(u23, u23)=1/2$

...

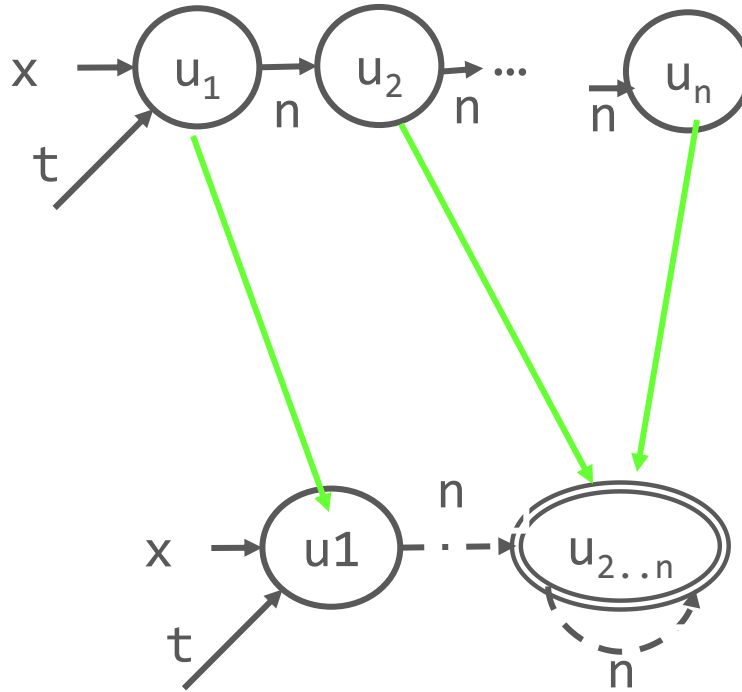
Big Idea

You can increase precision by tracking additional predicates

Cyclicity predicate

$$c[x]() = \exists v_1, v_2: x(v_1) \wedge n^*(v_1, v_2) \wedge n^+(v_2, v_2)$$

$$c[x]() = \emptyset$$



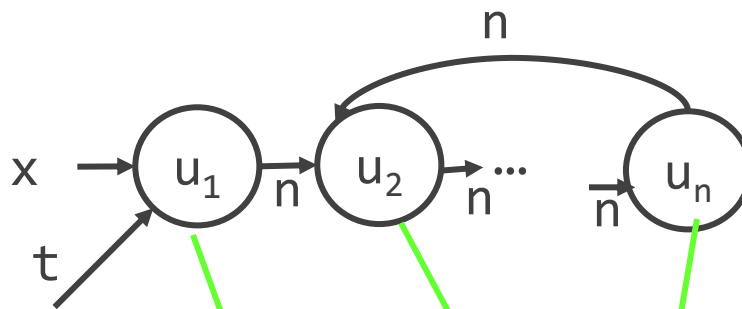
$$c[x]() = \emptyset$$

From the abstract graph alone we cannot tell there are no cycles, but the predicate tells us this is the case.

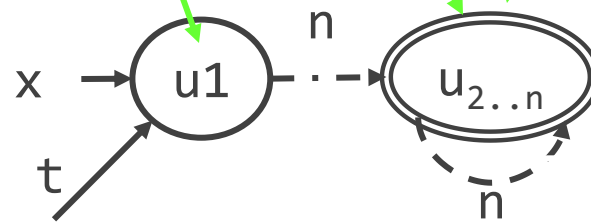
Cyclicity predicate

$$c[x]() = \exists v_1, v_2: x(v_1) \wedge n^*(v_1, v_2) \wedge n^+(v_2, v_2)$$

$c[x]()=1$



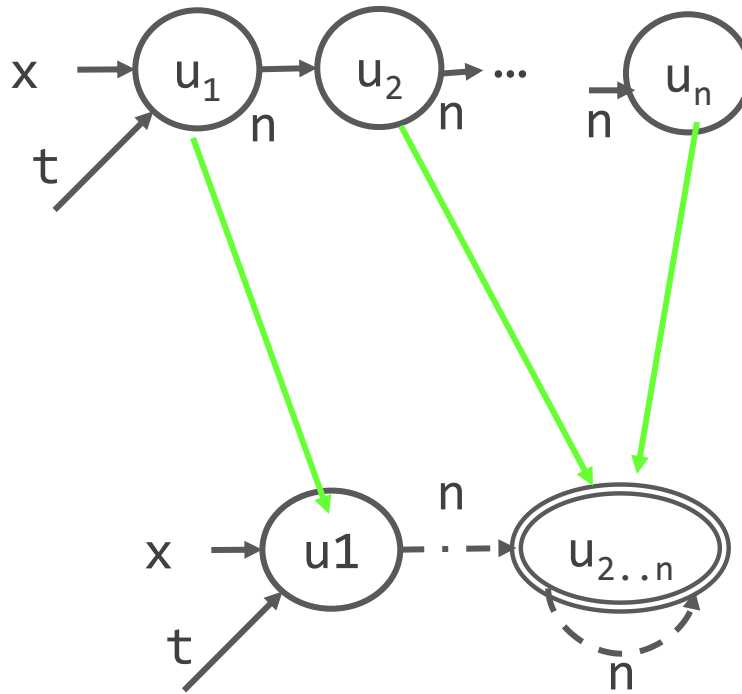
$c[x]()=1$



Heap Sharing predicate

$$is(v) = \exists v_1, v_2: n(v_1, v) \wedge n(v_2, v) \wedge v_1 \neq v_2$$

$is(v)=0$ $is(v)=0$ $is(v)=0$

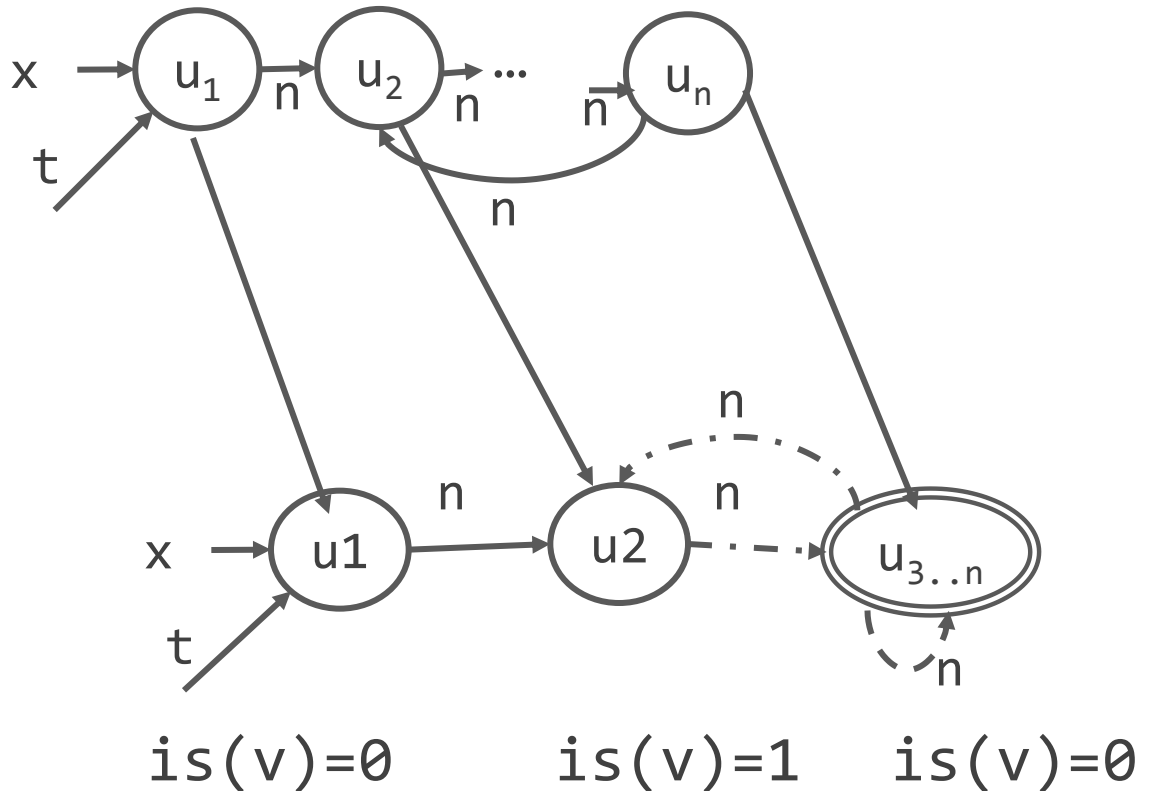


$is(v)=0$ $is(v)=0$

Heap Sharing predicate

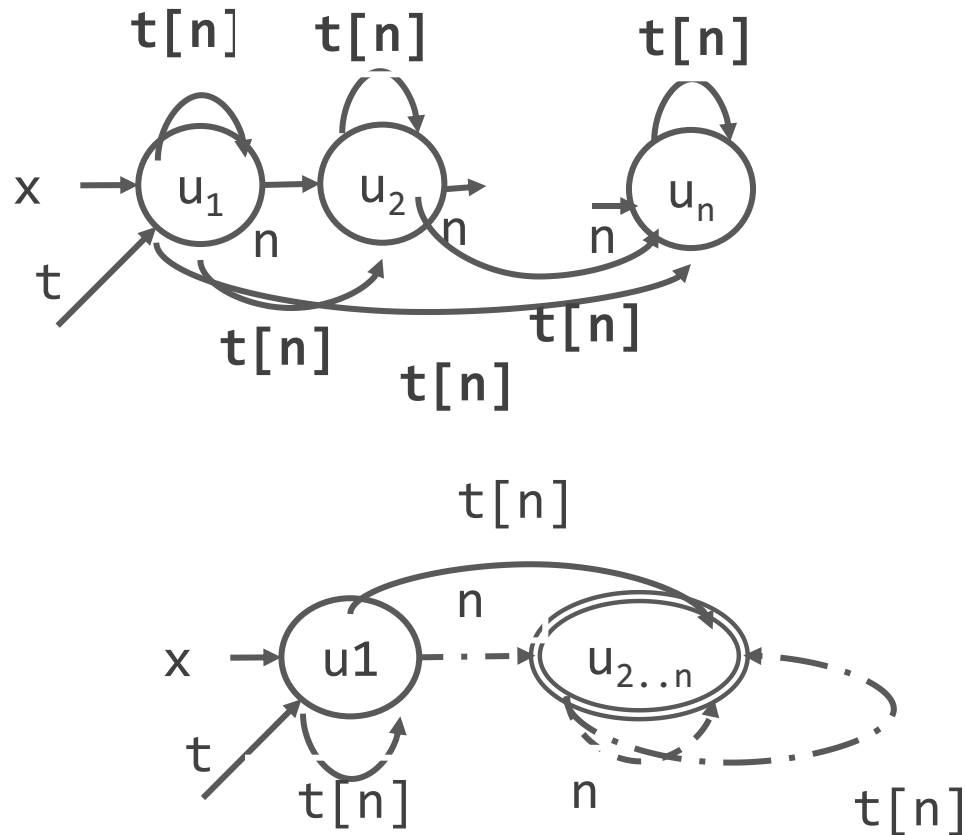
$$is(v) = \exists v_1, v_2: n(v_1, v) \wedge n(v_2, v) \wedge v_1 \neq v_2$$

$is(v)=0$ $is(v)=1$ $is(v)=0$



Reachability predicate

$$t[n](v1, v2) = n^*(v1, v2)$$



Additional Instrumentation predicates

reachable-from-variable- $x(v)$

$$c_{fb}(v) = \forall v_1: f(v, v_1) \stackrel{\Omega}{=} b(v_1, v)$$

tree(v)

dag(v)

inOrder(v) =

$$\forall v_1: n(v, v_1) \rightarrow dle(v, v_1)$$

Instrumentation (Summary)

Refines the abstraction

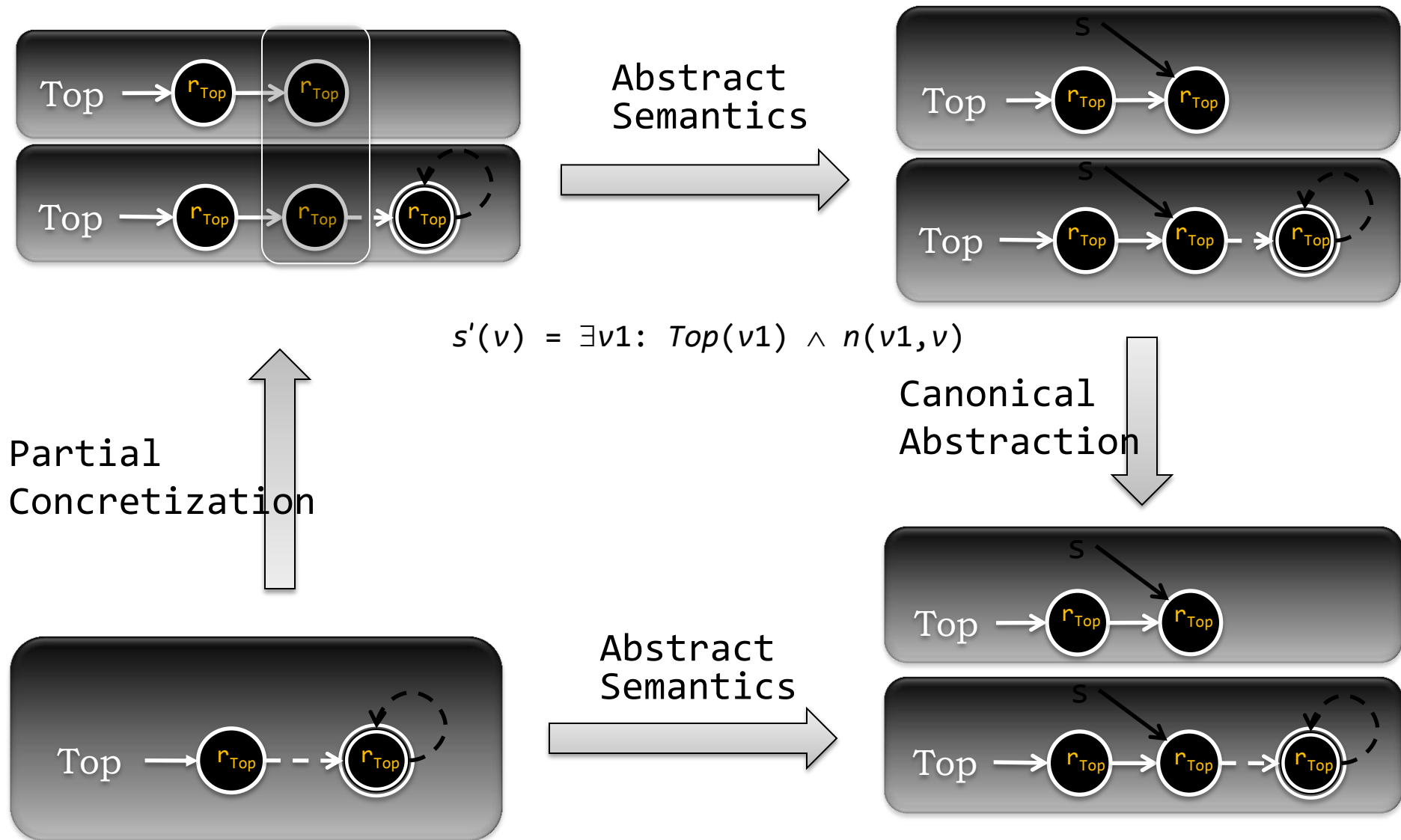
Adds global invariants

But requires update-formulas
(generated automatically in TVLA2)

Partial Concretization (focus)

Helpful in making transfer functions more precise
Expand an abstract heap into a collection of more concrete

Partial Concretization Based on Transformer ($s = Top \rightarrow n$)



MIT OpenCourseWare
<http://ocw.mit.edu>

6.820 Fundamentals of Program Analysis
Fall 2015

For information about citing these materials or our Terms of Use, visit: <http://ocw.mit.edu/terms>.