



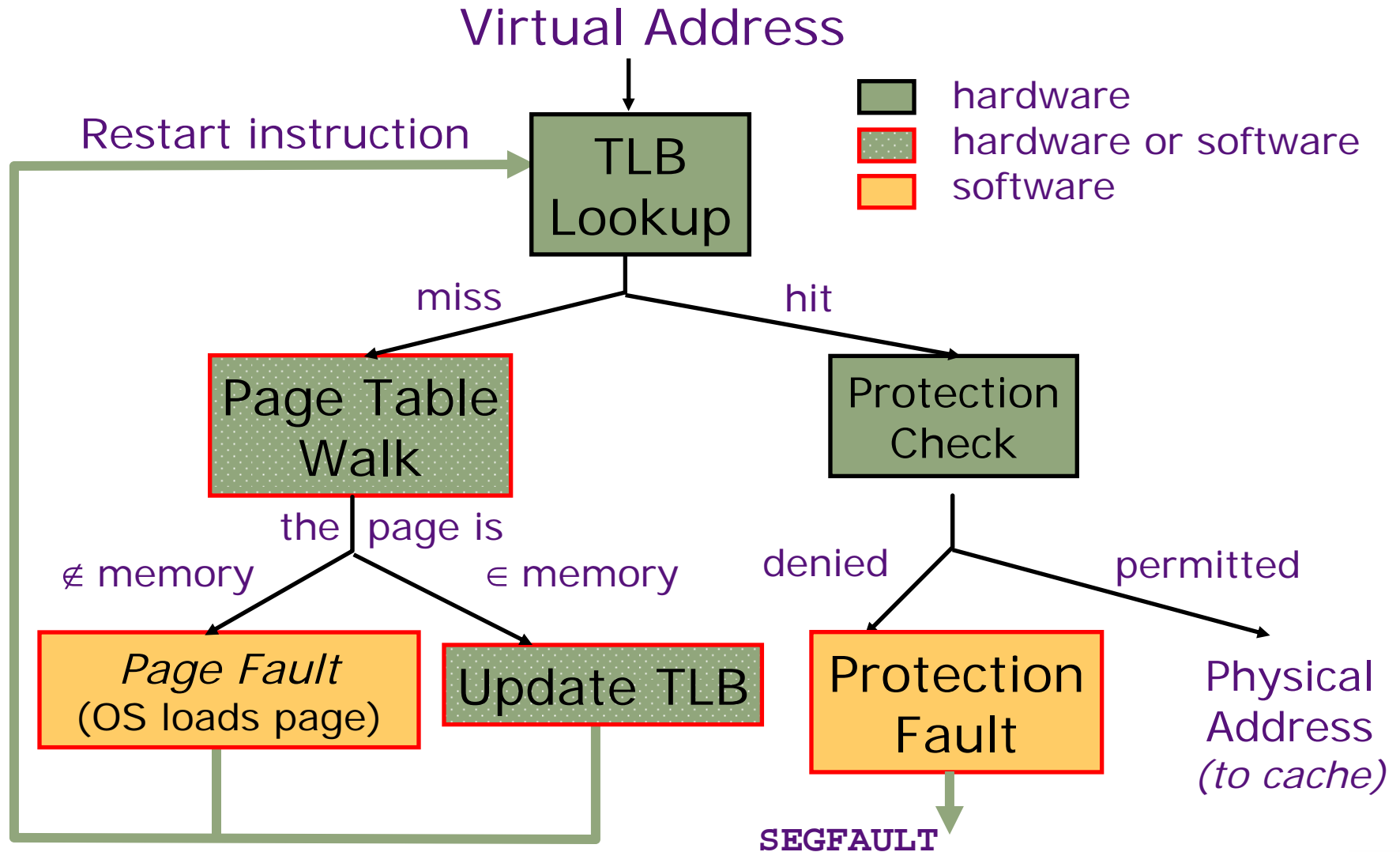
# Modern Virtual Memory Systems

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*Based on the material prepared by  
Arvind and Krste Asanovic*

# Address Translation: *putting it all together*



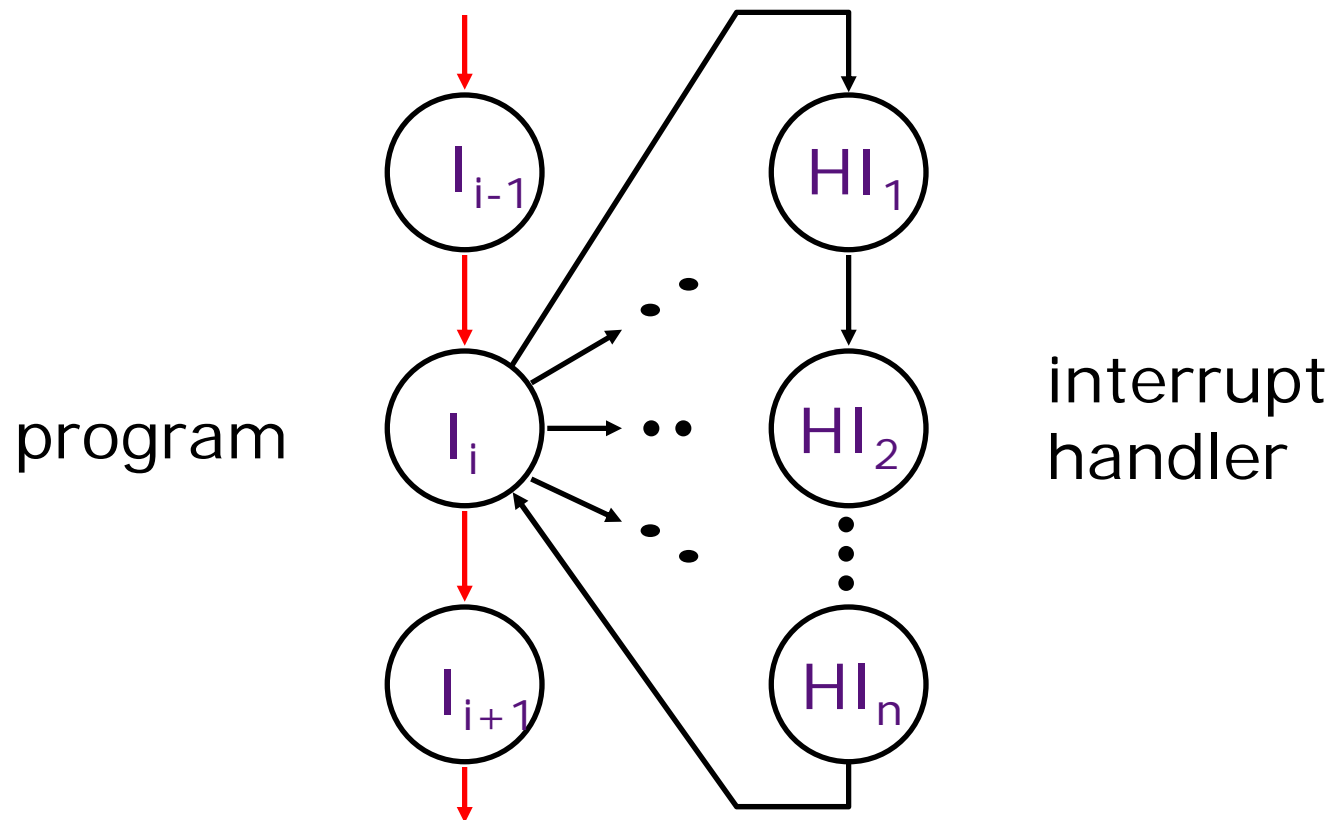
# Topics

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- Interrupts 
- Speeding up the common case:
  - TLB & Cache organization
- Speeding up page table walks
- Modern Usage

# Interrupts: altering the normal flow of control

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An *external or internal event* that needs to be processed by another (system) program. The event is usually unexpected or rare from program's point of view.

# Causes of Interrupts

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Interrupt: an *event* that requests the attention of the processor

- *Asynchronous: an external event*
  - input/output device service-request
  - timer expiration
  - power disruptions, hardware failure
- *Synchronous: an internal event (a.k.a exceptions)*
  - undefined opcode, privileged instruction
  - arithmetic overflow, FPU exception
  - misaligned memory access
  - *virtual memory exceptions*: page faults, TLB misses, protection violations
  - *traps*: system calls, e.g., jumps into kernel

# Asynchronous Interrupts: invoking the interrupt handler

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- An I/O device requests attention by asserting one of the *prioritized interrupt request lines*
- When the processor decides to process the interrupt
  - It stops the current program at instruction  $I_i$ , completing all the instructions up to  $I_{i-1}$  (*precise interrupt*)
  - It saves the PC of instruction  $I_i$  in a special register (EPC)
  - It disables interrupts and transfers control to a designated interrupt handler running in the kernel mode

# Interrupt Handler

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- Saves EPC before enabling interrupts to allow nested interrupts  $\Rightarrow$ 
  - need an instruction to move EPC into GPRs
  - need a way to mask further interrupts at least until EPC can be saved
- Needs to read a *status register* that indicates the cause of the interrupt
- Uses a special indirect jump instruction RFE (*return-from-exception*) which
  - enables interrupts
  - restores the processor to the user mode
  - restores hardware status and control state

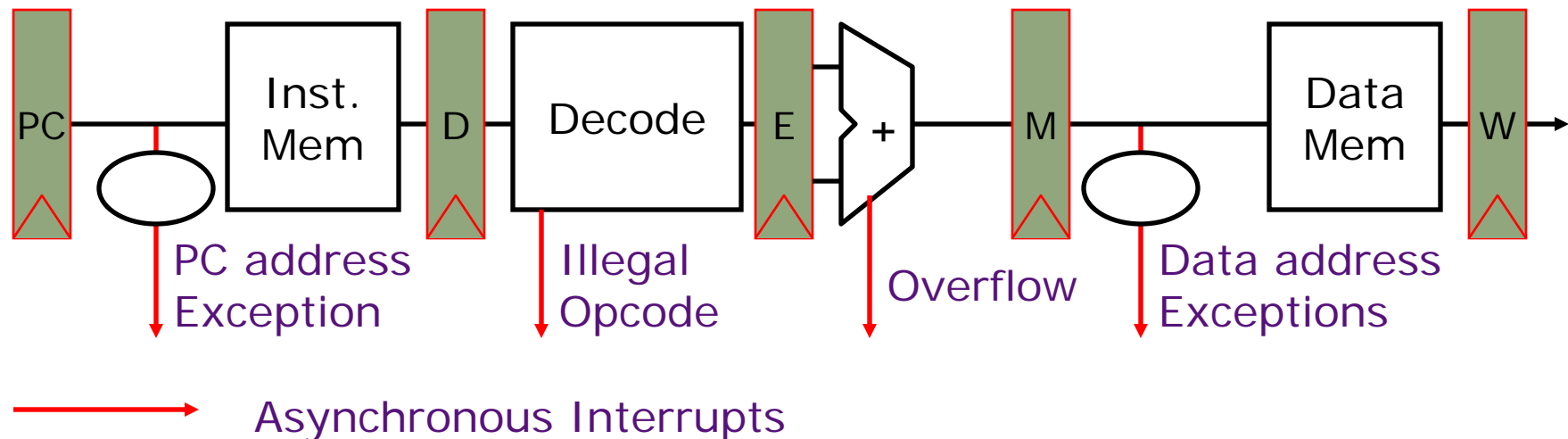
# Synchronous Interrupts

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- A synchronous interrupt (exception) is caused by a *particular instruction*
- In general, the instruction cannot be completed and needs to be *restarted* after the exception has been handled
  - requires undoing the effect of one or more partially executed instructions
- In case of a trap (system call), the instruction is considered to have been completed
  - a special jump instruction involving a change to privileged kernel mode

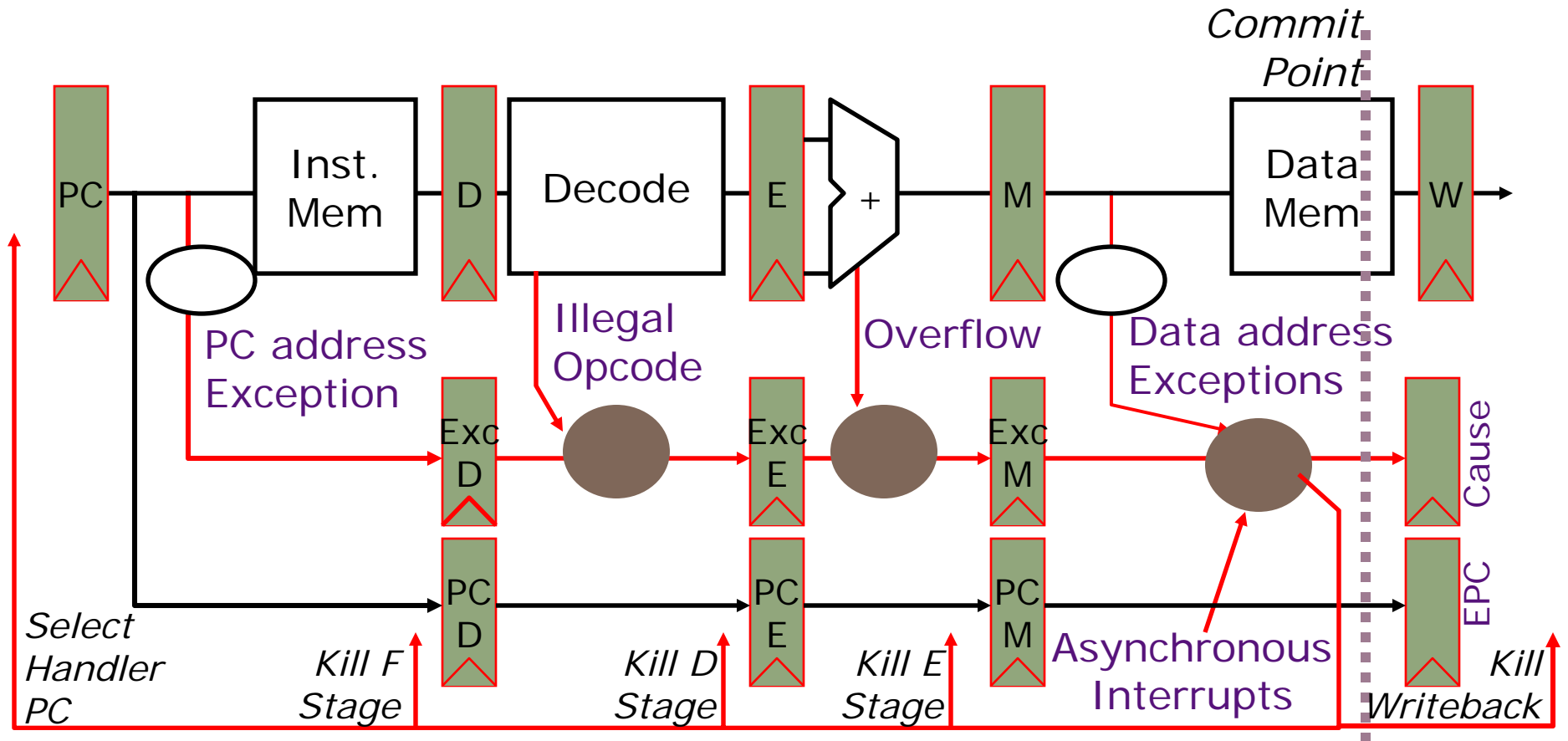


# Exception Handling 5-Stage Pipeline



- How to handle multiple simultaneous exceptions in different pipeline stages?
- How and where to handle external asynchronous interrupts?

# Exception Handling 5-Stage Pipeline



# Exception Handling 5-Stage Pipeline

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- Hold exception flags in pipeline until commit point (M stage)
- Exceptions in earlier pipe stages override later exceptions *for a given instruction*
- Inject external interrupts at commit point (override others)
- If exception at commit: update Cause and EPC registers, kill all stages, inject handler PC into fetch stage

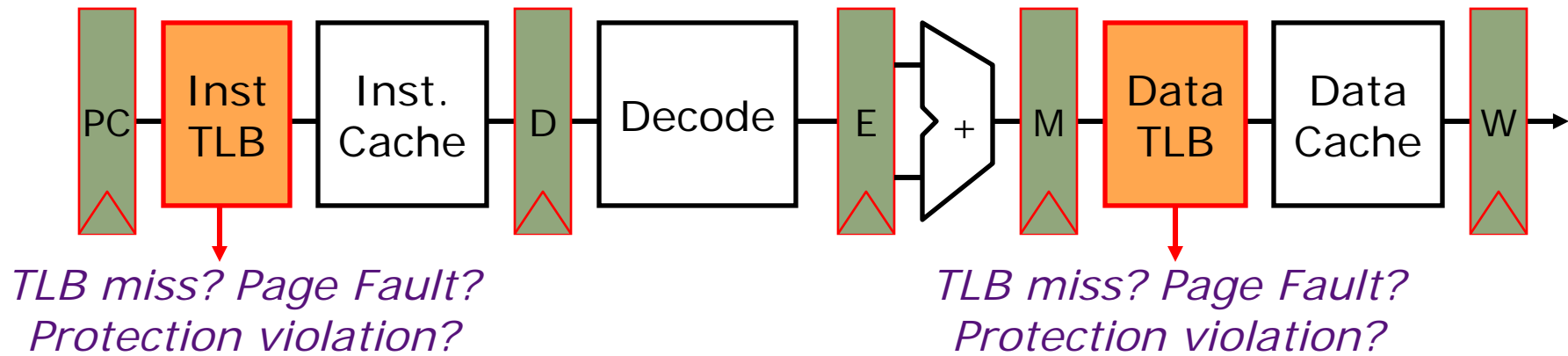
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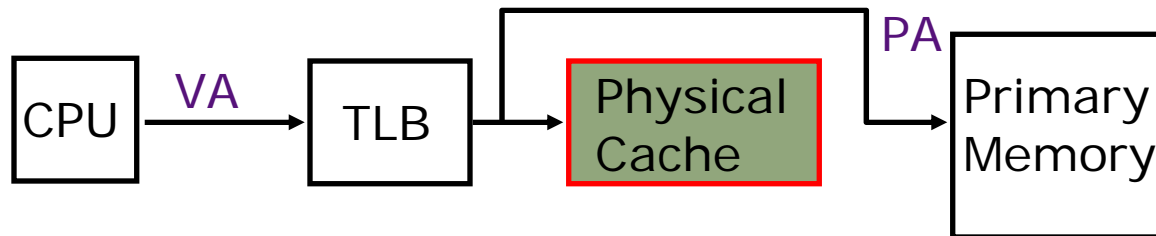


# Address Translation in CPU Pipeline

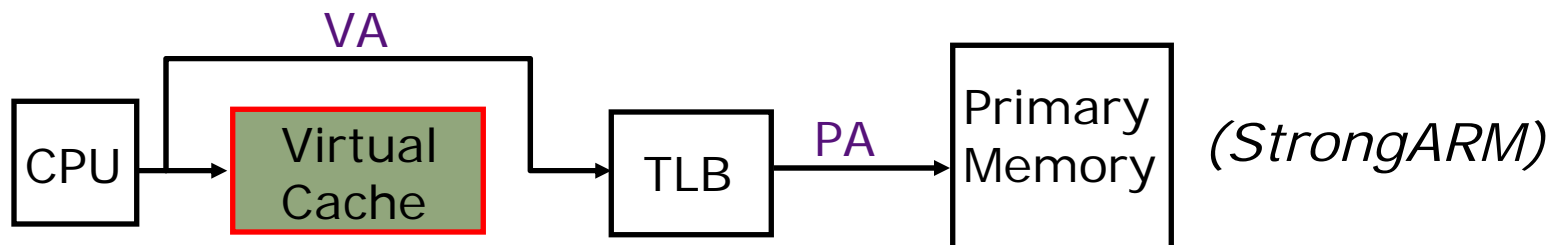


- Software handlers need a *restartable* exception on page fault or protection violation
- Handling a TLB miss needs a *hardware or software* mechanism to refill TLB
- Need mechanisms to cope with the additional latency of a TLB:
  - slow down the clock
  - pipeline the TLB and cache access
  - virtual address caches
  - parallel TLB/cache access

# Virtual Address Caches

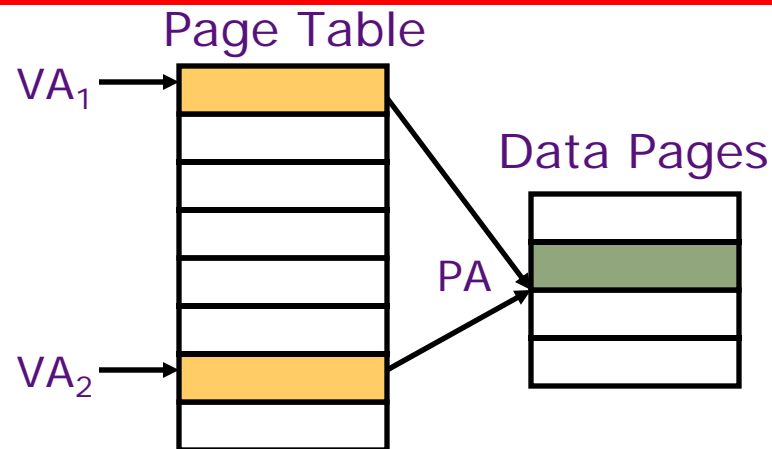


*Alternative: place the cache before the TLB*



- one-step process in case of a hit (+)
- cache needs to be flushed on a context switch unless address space identifiers (ASIDs) included in tags (-)
- *aliasing problems* due to the sharing of pages (-)

# Aliasing in Virtual-Address Caches



Two virtual pages share one physical page

Tag	Data
VA <sub>1</sub>	1st Copy of Data at PA
VA <sub>2</sub>	2nd Copy of Data at PA

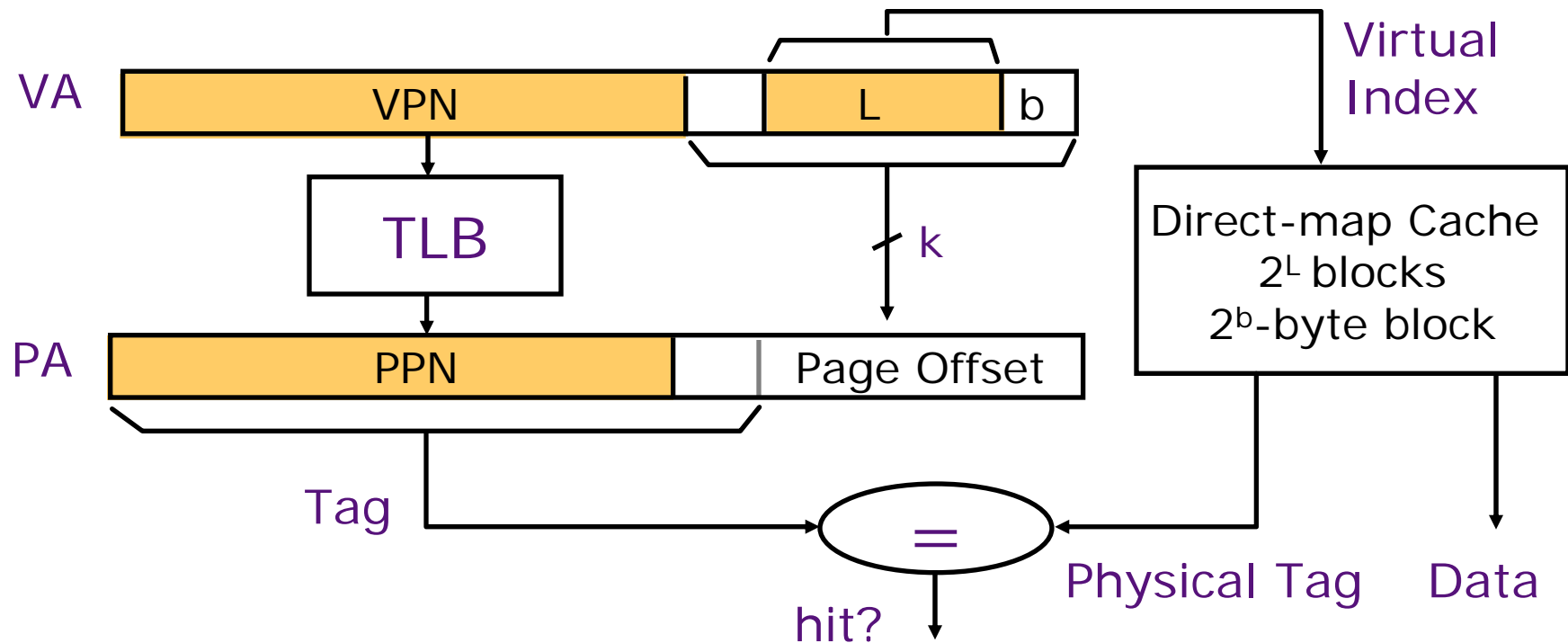
Virtual cache can have two copies of same physical data. Writes to one copy not visible to reads of other!

General Solution: *Disallow aliases to coexist in cache*

Software (i.e., OS) solution for direct-mapped cache

VAs of shared pages must agree in cache index bits; this ensures all VAs accessing same PA will conflict in direct-mapped cache (early SPARCs)

# Concurrent Access to TLB & Cache



Index L is available without consulting the TLB

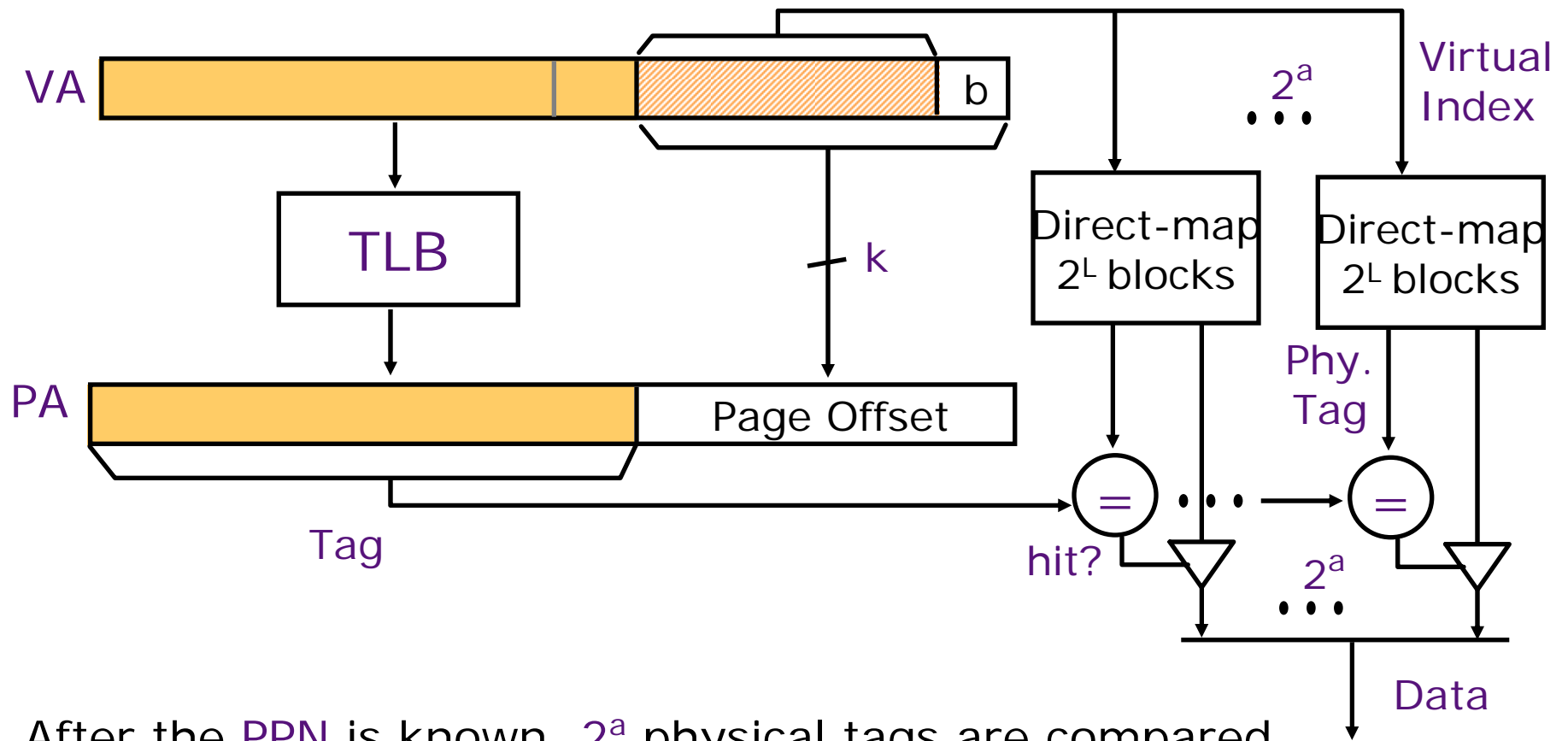
⇒ *cache and TLB accesses can begin simultaneously*

Tag comparison is made after both accesses are completed

Cases:  $L + b = k$      $L + b < k$      $L + b > k$



# Virtual-Index Physical-Tag Caches: Associative Organization

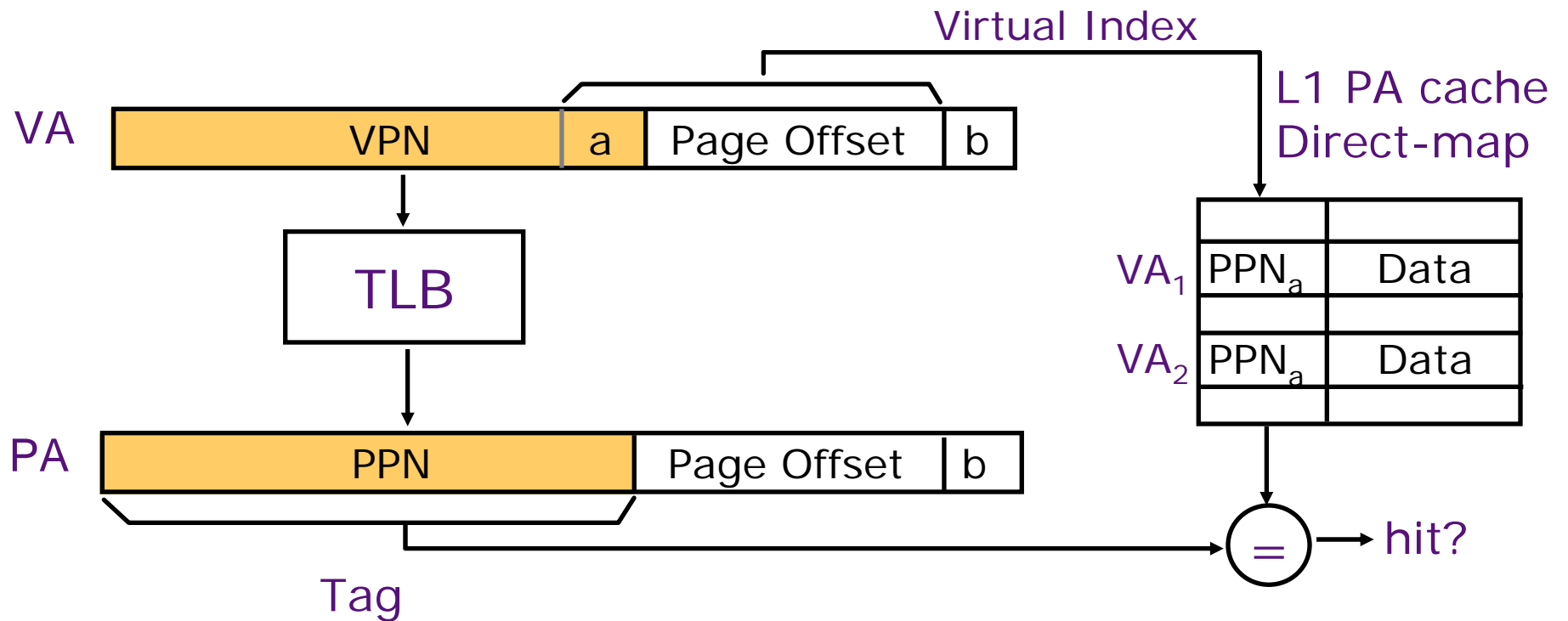


After the PPN is known,  $2^a$  physical tags are compared

*Is this scheme realistic?*

# Concurrent Access to TLB & Large L1

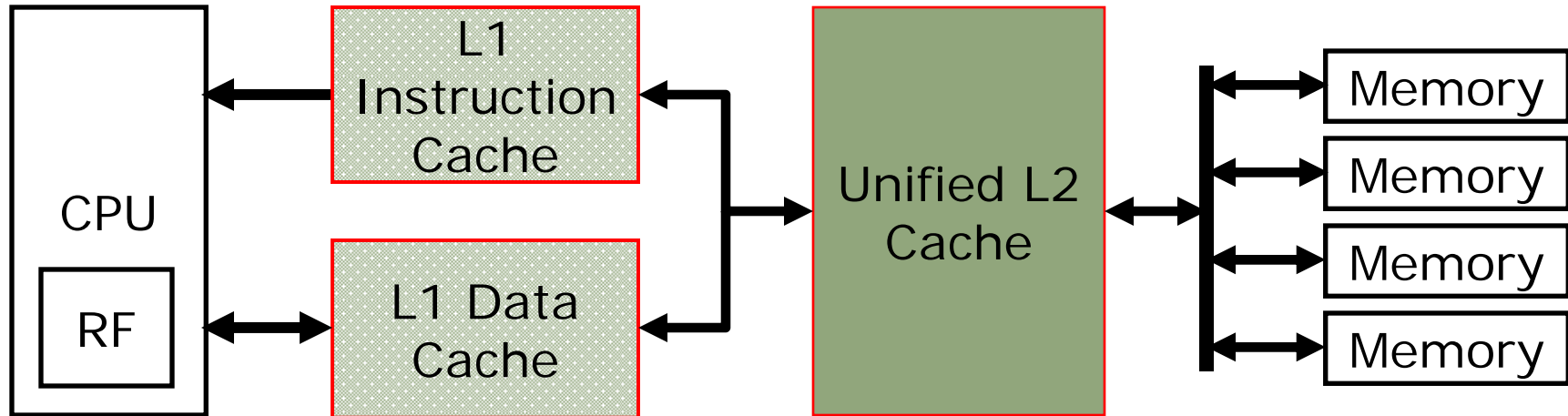
The problem with  $L1 > \text{Page size}$



*Can VA<sub>1</sub> and VA<sub>2</sub> both map to PA ?*

## A solution via Second Level Cache

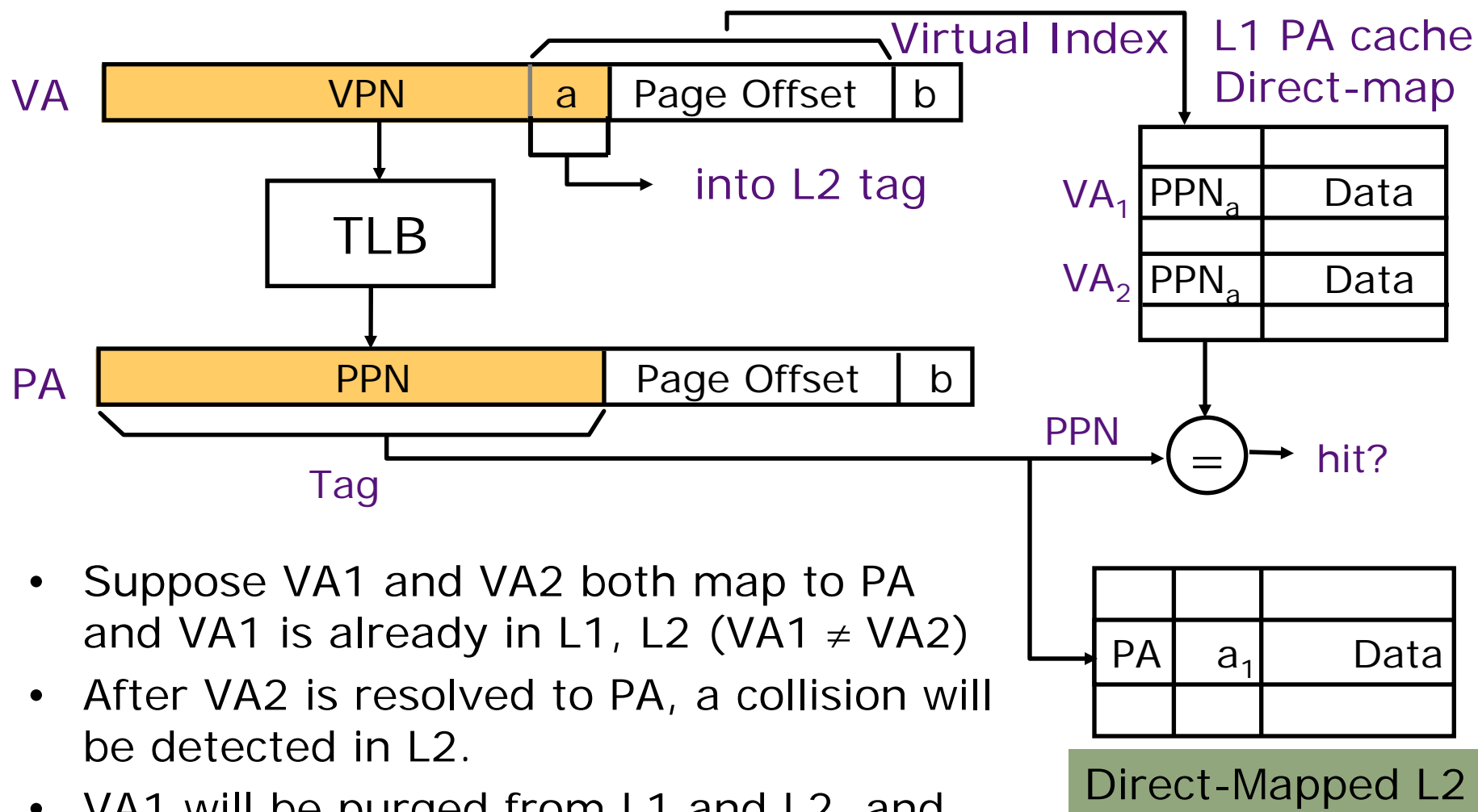
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Usually a common L2 cache backs up both Instruction and Data L1 caches

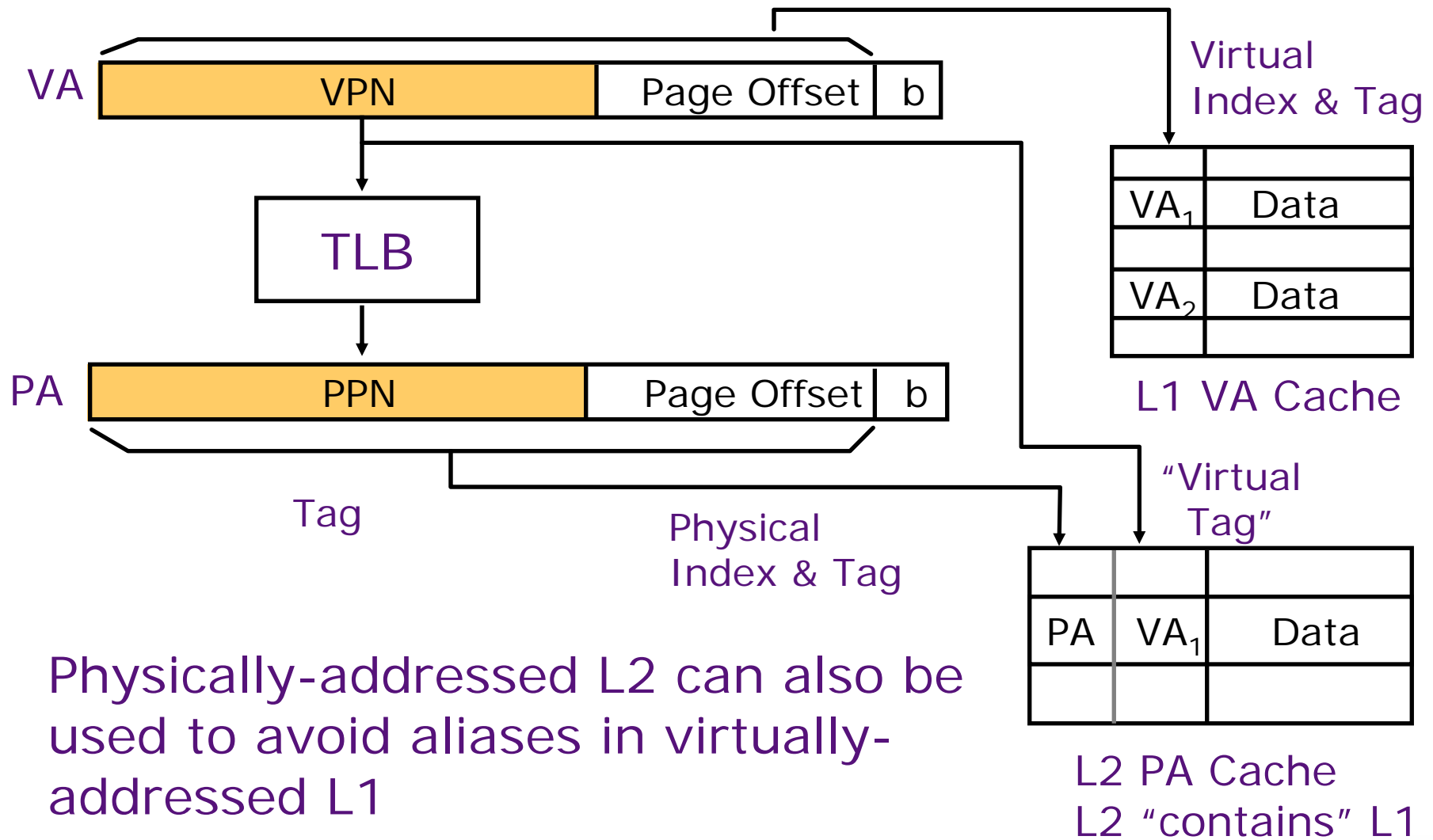
L2 is “inclusive” of both Instruction and Data caches

# Anti-Aliasing Using L2: MIPS R10000



- Suppose VA<sub>1</sub> and VA<sub>2</sub> both map to PA and VA<sub>1</sub> is already in L1, L2 (VA<sub>1</sub> ≠ VA<sub>2</sub>)
- After VA<sub>2</sub> is resolved to PA, a collision will be detected in L2.
- VA<sub>1</sub> will be purged from L1 and L2, and VA<sub>2</sub> will be loaded ⇒ *no aliasing* !

# Virtually-Addressed L1: Anti-Aliasing using L2





**Five-minute break to stretch your legs**

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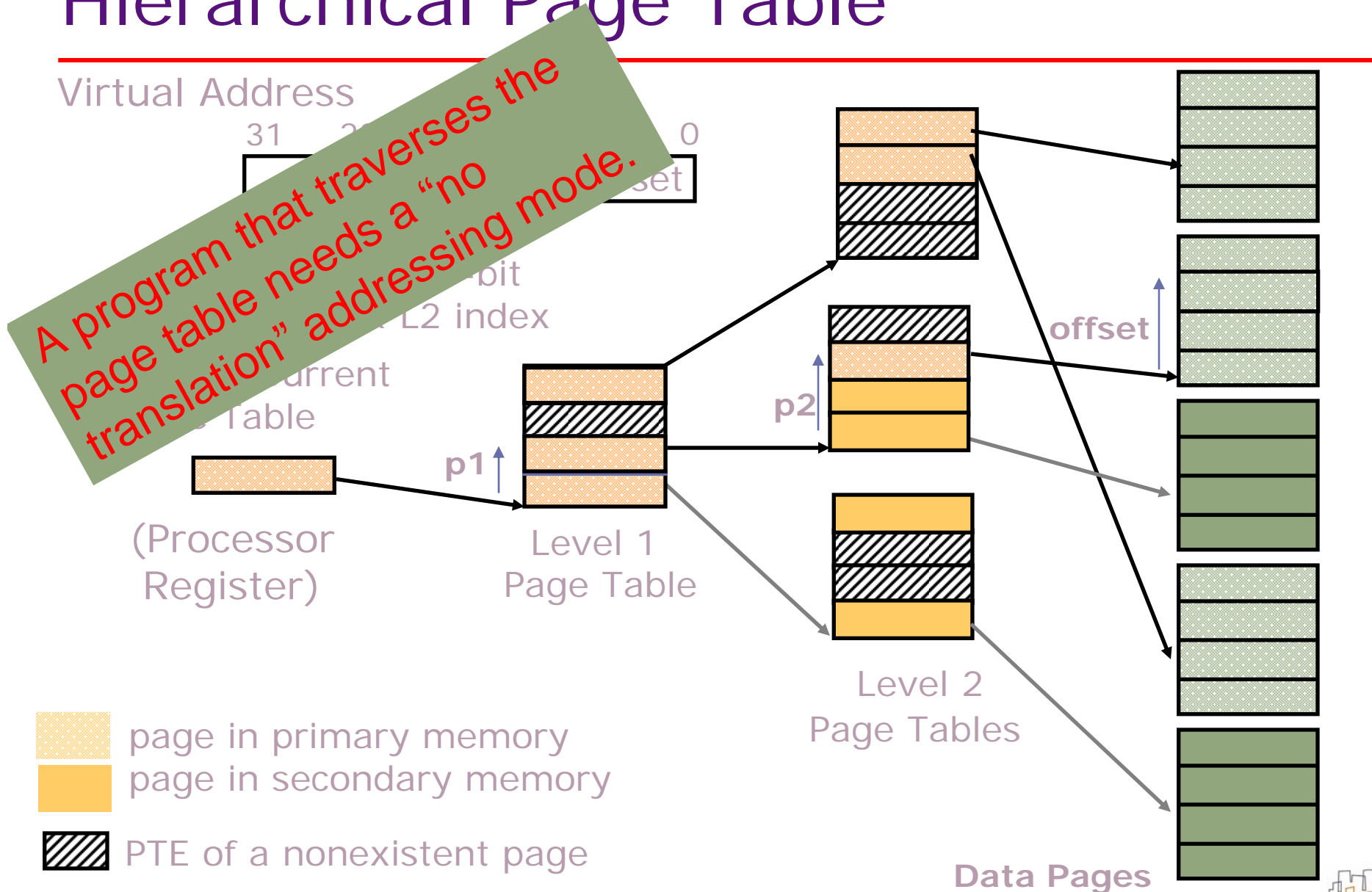
# Page Fault Handler

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- When the referenced page is not in DRAM:
  - The missing page is located (or created)
  - It is brought in from disk, and page table is updated
    - Another job may be run on the CPU while the first job waits for the requested page to be read from disk*
  - If no free pages are left, a page is swapped out
    - Pseudo-LRU replacement policy*
- Since it takes a long time to transfer a page (msecs), page faults are handled completely in software by the OS
  - Untranslated addressing mode is essential to allow kernel to access page tables

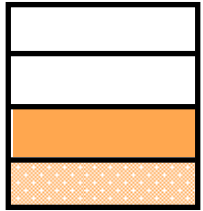


# Hierarchical Page Table

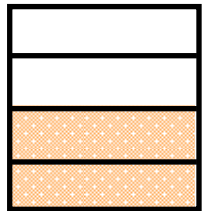


# Swapping a Page of a Page Table

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A PTE in primary memory contains  
primary or secondary memory addresses



A PTE in secondary memory contains  
*only* secondary memory addresses

⇒ a page of a PT can be swapped out only  
if none its PTE's point to pages in the  
primary memory

Why? \_\_\_\_\_

# Atlas Revisited

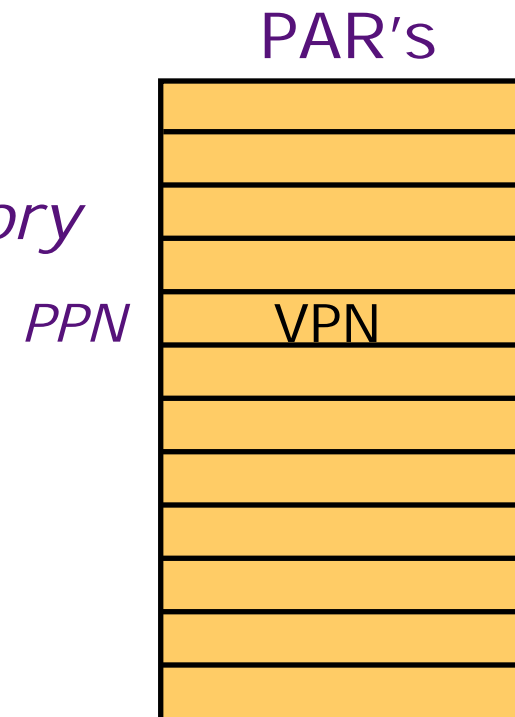
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- One PAR for each physical page

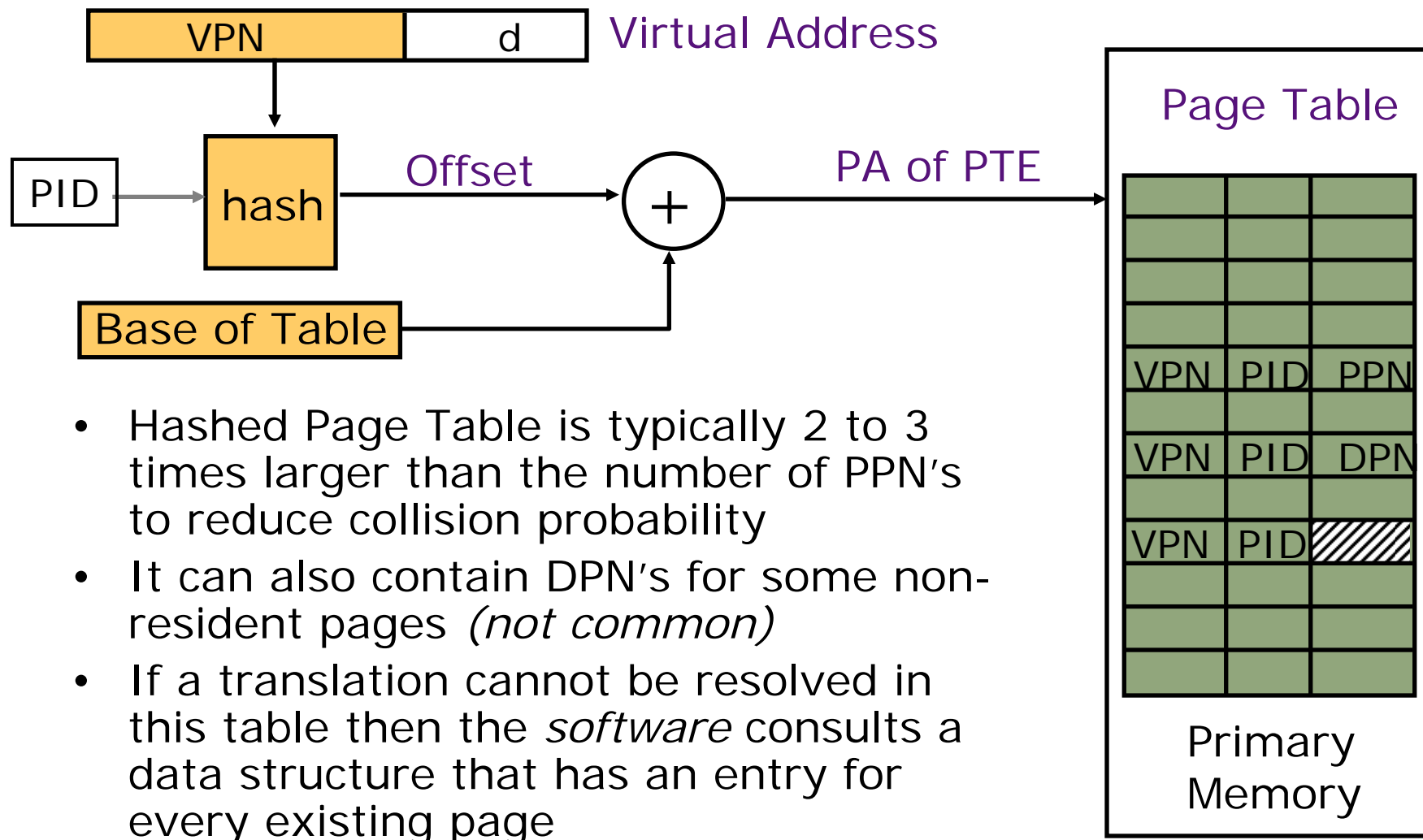
- PAR's contain the VPN's of the pages *resident in primary memory*

- *Advantage:* The size is proportional to the size of the primary memory

- *What is the disadvantage ?*

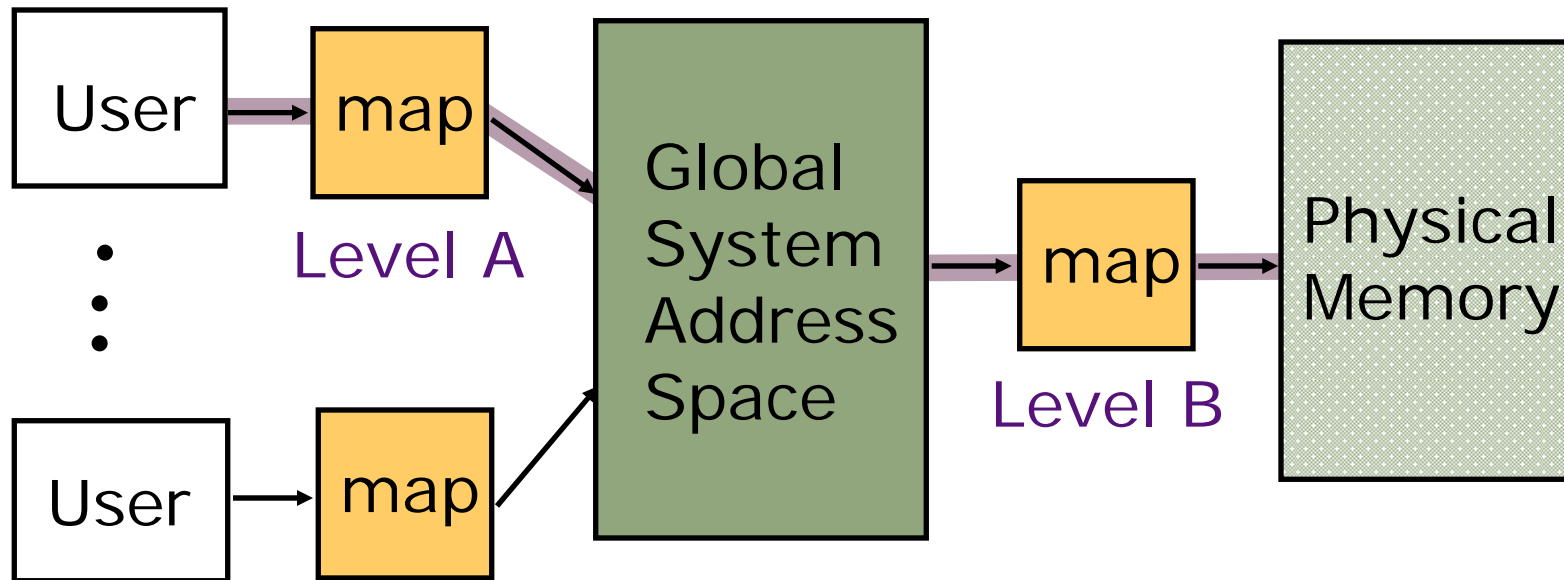


# Hashed Page Table: Approximating Associative Addressing



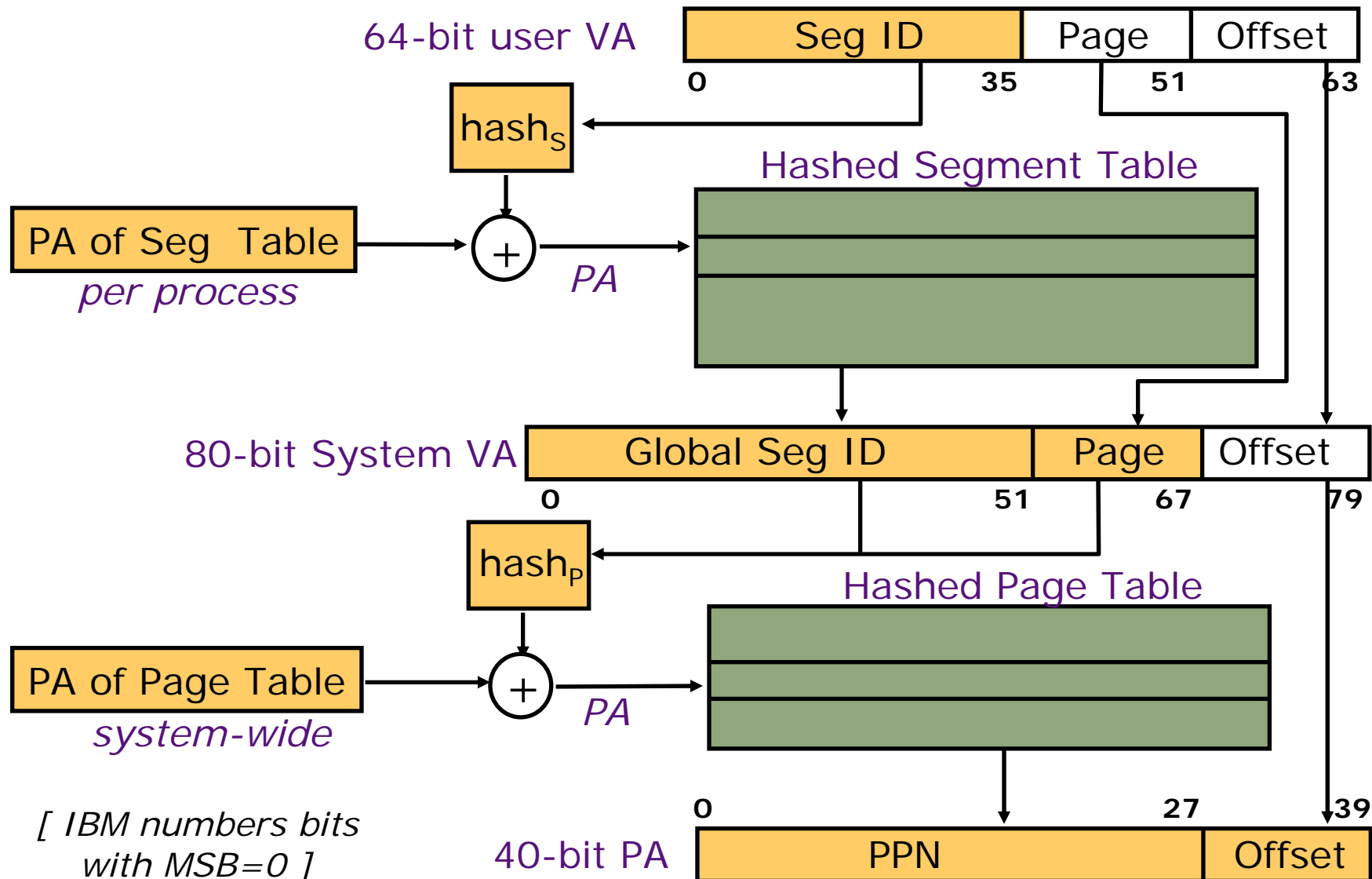
- Hashed Page Table is typically 2 to 3 times larger than the number of PPN's to reduce collision probability
- It can also contain DPN's for some non-resident pages (*not common*)
- If a translation cannot be resolved in this table then the *software* consults a data structure that has an entry for every existing page

# Global System Address Space



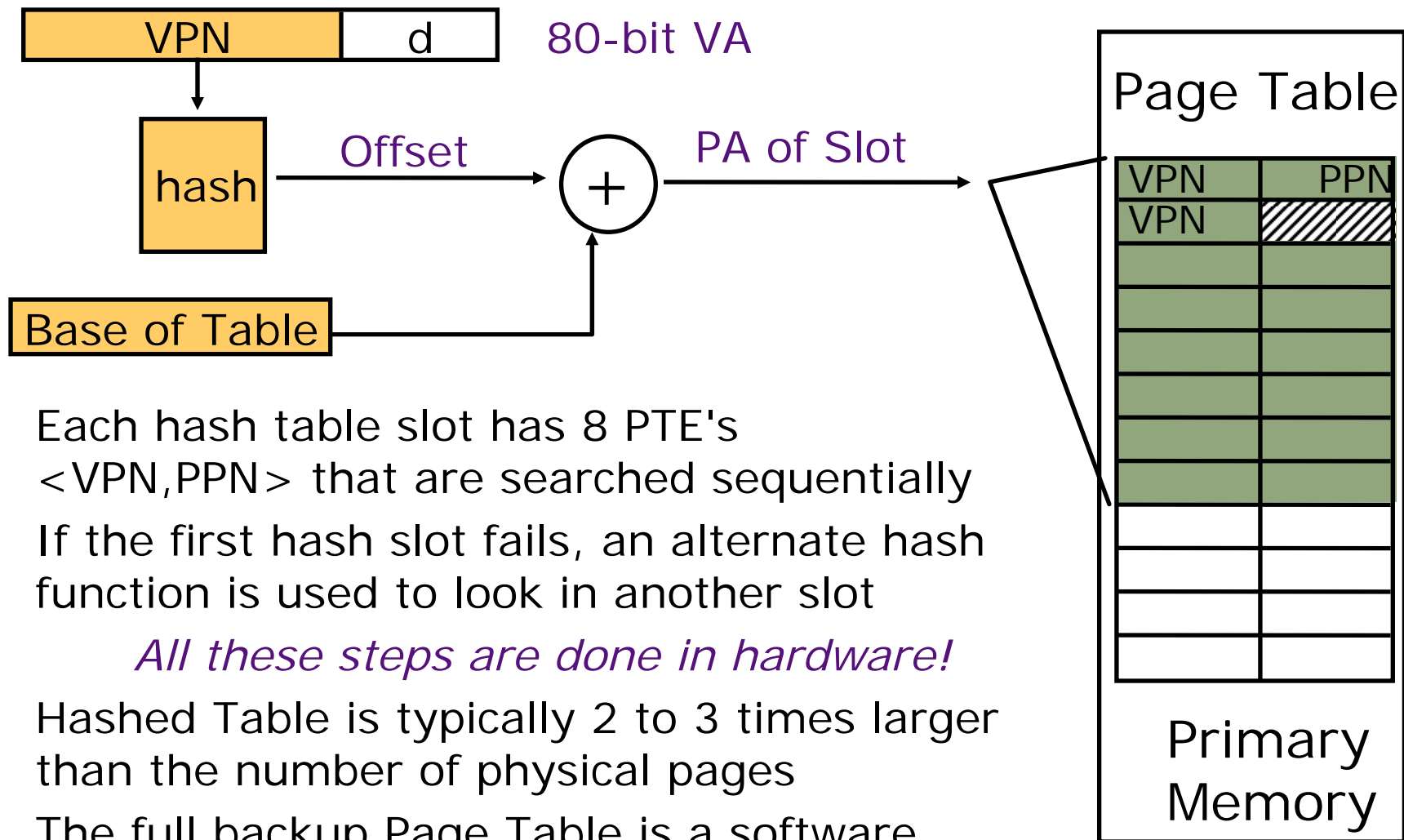
- Level A maps users' address spaces into the global space providing privacy, protection, sharing etc.
- Level B provides demand-paging for the large global system address space
- Level A and Level B translations may be kept in separate TLB's

# Hashed Page Table Walk: PowerPC Two-level, Segmented Addressing



[ IBM numbers bits  
with MSB=0 ]

# Power PC: Hashed Page Table



- Each hash table slot has 8 PTE's  $\langle \text{VPN}, \text{PPN} \rangle$  that are searched sequentially
- If the first hash slot fails, an alternate hash function is used to look in another slot
- *All these steps are done in hardware!*
- Hashed Table is typically 2 to 3 times larger than the number of physical pages
- The full backup Page Table is a software data structure

# Virtual Memory Use Today - 1

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- Desktops/servers have full demand-paged virtual memory
  - Portability between machines with different memory sizes
  - Protection between multiple users or multiple tasks
  - Share small physical memory among active tasks
  - Simplifies implementation of some OS features
- Vector supercomputers have translation and protection but not demand-paging  
(Crays: base&bound, Japanese: pages)
  - Don't waste expensive CPU time thrashing to disk (make jobs fit in memory)
  - Mostly run in batch mode (run set of jobs that fits in memory)
  - Difficult to implement restartable vector instructions



# Virtual Memory Use Today - 2

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- Most embedded processors and DSPs provide physical addressing only
  - Can't afford area/speed/power budget for virtual memory support
  - Often there is no secondary storage to swap to!
  - Programs custom written for particular memory configuration in product
  - Difficult to implement restartable instructions for exposed architectures

*Given the software demands of modern embedded devices (e.g., cell phones, PDAs) all this may change in the near future!*



*Thank you !*