

PART A -

①

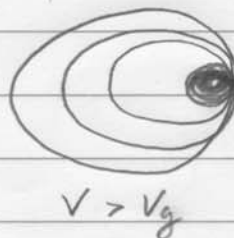
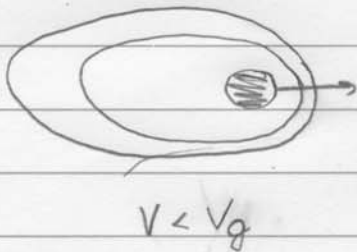
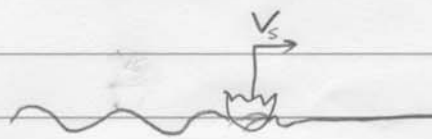
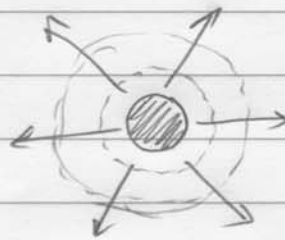
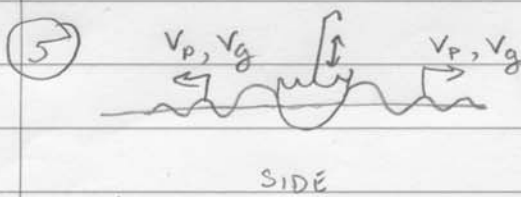
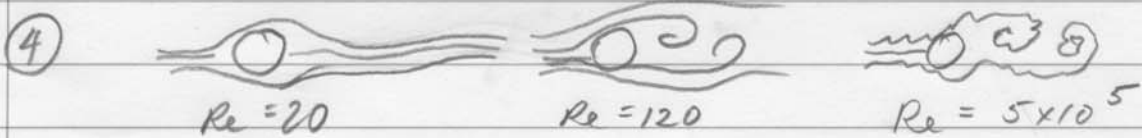
x	0	0	0	0	x
0	x	0	0	0	0
0	0	x	x	0	0
0	0	x	x	0	0
0	0	0	0	0	0
x	0	0	0	0	x

③

-x	0	0	0	0	-x
0	-x	0	0	0	-x
0	0	+x	+x	+x	0
0	0	+x	-x	0	0
0	0	+x	0	-x	0
-x	-x	0	0	0	-x

② $\underline{\omega_s} = 16.75 \text{ rad/s}$, $(f_s = 2.67 \text{ Hz})$

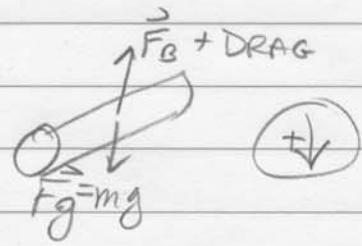
$\omega_s = \omega_n = \sqrt{\frac{k}{M+m_a}}$ lock in -



↑
there is always some form of bow wave...

PART B-

(17) a) Terminal Velocity



$$F_{\text{DRAG}} = \frac{1}{2} \rho U^2 C_D A$$

$$F_B = \rho g V$$

$$F_g = 1.5 \rho_w g V$$

$$A = dL$$

$$V = \frac{\pi d^2}{4} L$$

@ Terminal Vel $\Sigma F = ma = 0$

$$\Sigma F = \vec{F}_g - \vec{F}_B - \vec{F}_D = 0$$

$$\vec{F}_D = \vec{F}_g - \vec{F}_B = \frac{1}{2} \rho_w g V = 157 \text{ N}$$

$$U^2 \left(\frac{1}{2} \rho C_D d \cdot V \right) = \frac{1}{2} \rho_w g \frac{\pi d^2}{4} V$$

$$U = \sqrt{\frac{\pi g d}{4 C_D}} = \sqrt{1.57 / C_D}$$

laminar $C_D = 1.2$ $U = 1.14 \text{ m/s}$ $Re = 228,000$

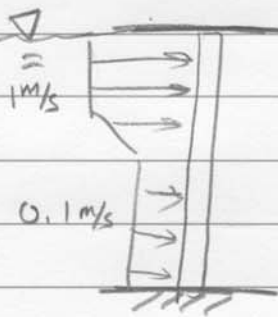
turb $C_D = 0.6$ $U = 1.62 \text{ m/s}$ $Re = 324,000$

wow! v. close could be either so it ultimately depends on cylinder roughness - either answer gets credit-

b) @ $U = 1.14 \text{ m/s}$ $f = 1.14 \text{ Hz}$; $f = \frac{U}{d} = \frac{0.2}{0.2} U$
 $U = 1.62 \text{ m/s}$ $f = 1.62 \text{ Hz}$;

PART B

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assume $S = 0.2 = \frac{fd}{u}$

Top
 $f = \frac{0.2 \cdot 1.0}{0.5}$

bottom
 $f_{bot} = 0.1 * f_{top}$

$f_{top} = 0.4 \text{ Hz}$

$f_{bot} = 0.04 \text{ Hz}$

b) frequency of drag is 2. freq of vortex shedding

freq. of lift is = freq of vortex shedding

therefore it directly correlates w/ flow velocity.

c) the structure will tend to vibrate more at top exciting forced motion

@ bottom. In both cases frequency is low so it's not going to be too violent.

Shear will complicate shedding & make flow more 3 dimensional

d) Flexible cylinder

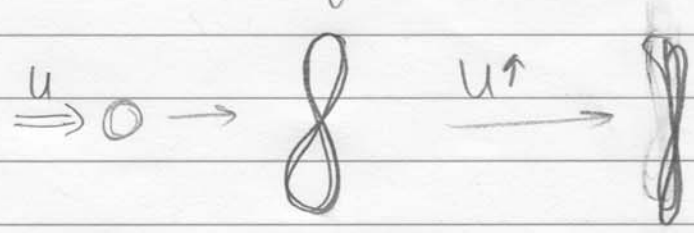


figure "8" motion

high vel, tension ↑ and inline vibs ↓

PART B-

(2) Initial Acceleration

$$\Sigma F = M \ddot{x}_3 \Big|_{t=0} = \vec{F}_g - \vec{F}_g \quad \text{only forces at work!}$$

$$M = m + m_a \quad m = \rho V = 2\rho \pi a^3$$

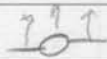
$$\begin{aligned} V &= V_{\text{sphere}} + 2V_{\text{cylinders}} \\ &= \frac{4}{3}\pi(2a)^3 + 2 \cdot \pi\left(\frac{a}{2}\right)^2(4a) \\ &= \frac{32}{3}\pi a^3 + 2\pi a^3 = \boxed{\frac{38}{3}\pi a^3 = V} \end{aligned}$$

(i) vertical



$$\begin{aligned} m_a &\approx m_{\text{sphere}} + \text{negligible} \\ &\quad \text{only} \quad \text{compared to sphere} \\ &= \frac{1}{2}\rho_w V_s = \frac{16}{3}\rho_w \pi a^3 \end{aligned}$$

(ii) horizontal



$$\begin{aligned} m_a &= \frac{1}{2}\rho_w V_s + 2\pi\left(\frac{a}{2}\right)^2(4a)\rho_w \\ &= \frac{22}{3}\pi\rho_w a^3 \end{aligned}$$

(1+)

$$\begin{aligned} (m+m_a)\ddot{x}_3 &= mg - \rho_w g V \\ &= 2\rho_w g V - \rho_w g V \\ \ddot{x}_3 &= \frac{\rho_w g V}{m+m_a} \\ &= \frac{\rho_w g \frac{38}{3}\pi a^3}{\frac{76}{3}\rho_w \pi a^3 + \frac{16}{3}\rho_w \pi a^3} \end{aligned}$$

$$\begin{aligned} (m+m_a)\ddot{x}_3 &= mg - \rho_w g V = \rho_w g V \\ \ddot{x}_3 &= \frac{\rho_w g \left(\frac{38}{3}\pi a^3\right)}{\left(\frac{76}{3} + \frac{22}{3}\right)\rho_w \pi a^3} \\ &= \frac{38}{98}g \end{aligned}$$

accel is + down

$$\ddot{x}_3 = \frac{38g}{92} = \frac{19}{46}g \text{ m/s}^2$$

$$\ddot{x}_3 = \frac{19}{49}g \text{ m/s}^2 \text{ (down)}$$

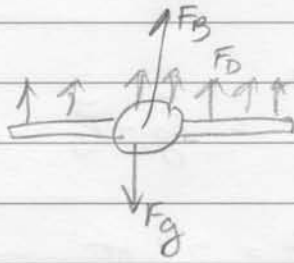
lower added mass so slightly larger initial acceleration

slightly lower due to higher added mass

$$\ddot{x}_3 = 4.13 \text{ m/s}^2 \text{ (}\downarrow\text{)}$$

$$\ddot{x}_3 = 3.88 \text{ m/s}^2 \text{ (}\downarrow\text{)}$$

(b)



Terminal Vel $\Sigma F = 0 = m\ddot{x}_3 \Rightarrow \ddot{x}_3 = 0$ no added mass per se.

$$mg - \rho g V - \frac{1}{2} \rho U^2 C_D A = 0$$

$$\rho g V = \frac{1}{2} \rho U^2 (C_D A) \quad U^2 = \frac{\rho g V}{\frac{1}{2} \rho C_D A} = \frac{2gV}{C_D A}$$

$$C_D A = A_{\text{sphere}} C_{D_{\text{sphere}}} + 2A_{\text{cyl}} C_{D_{\text{cyl}}}$$

$$= 4\pi a^2 \cdot C_{D_s} + 2a(4a) C_{D_c}$$

$$U = \sqrt{\frac{2g \cdot \frac{38}{3} \pi a^3}{24a^2 (\pi C_{D_s} + 2C_{D_c})}} = \sqrt{\frac{19g\pi a}{3(\pi C_{D_s} + 2C_{D_c})}}$$

if a small ($a \rightarrow 0$) $U \rightarrow 0$

$$a \text{ large then } U \approx \sqrt{\frac{19g\pi a}{3(\pi C_{D_s} + 2C_{D_c})}}$$

(C_{D_s} chosen based on $Re \#$)



(c) $M_1 = ? - \epsilon_{ijk} u_i u_k m_{ji}$
 $M_2 = ?$

$M_3 = 0$ by symmetry

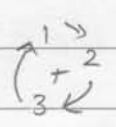
$u = (0, -u_2, u_3, 0, 0, 0)$

no accelerations
on angular
velocities!

$M_1 = - \epsilon_{123}^{(+1)} u_2 u_3 m_{33} - \epsilon_{132}^{(-1)} u_3 u_2 m_{22}$
 $j=1$

Munk moment only -

$(k=2,3)$
 $i=2,3$
 $l=1-3$



$m_{11}, m_{22}, m_{33} \neq 0$
 $m_{55}, m_{66} \neq 0$
 Rest are zero!

$m_{ji} = \begin{matrix} 12 & 13 \\ 22 & 23 \\ 32 & 33 \end{matrix}$

$m_1 = - (u_2 u_3) [m_{22} - m_{33}] = 0$

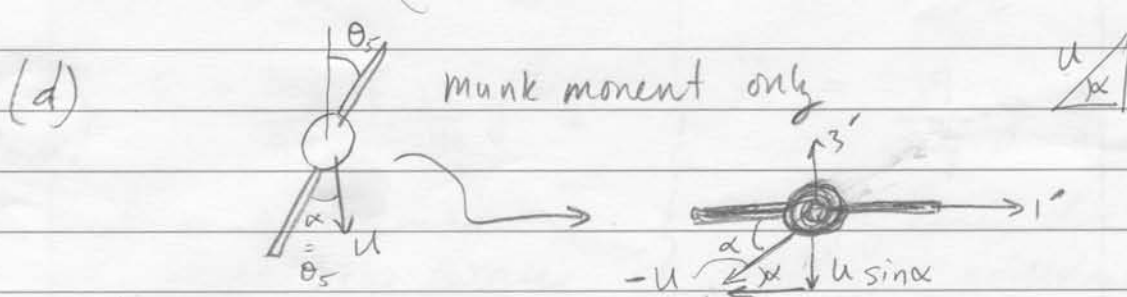
$j=2 \Rightarrow m_2 = 0$

$-\epsilon_{2kl}$
 $j=2$

$\because m_{22} = m_{33}$ by symmetry!

$k=3$ only
 $l=1$ then
 $i=1$ only
 but $u_1 = 0 \Rightarrow$

for $j=3$ then
 $k=2$ only
 $l=1$ only
 $i=1$ only $u_1 = 0 \Rightarrow m_3 = 0$



$u = (-u \cos \alpha, 0, u \sin \alpha, 0, 0, 0)$

$m_{33} = M_{\text{rot}}$ from pta
 $m_{11} = M_{\text{var}}$ from pta.

Want $M_2 = -\epsilon_{213} u_1 u_3 m_{33} - \epsilon_{231} u_3 u_1 m_{11} = u_1 u_3 [m_{33} - m_{11}] \neq 0$
 $j=2$ $k=1,3$ $i=1,3$ $l=1,3$ for nonzero m_{ij}