



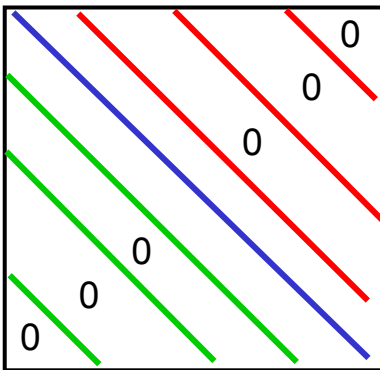
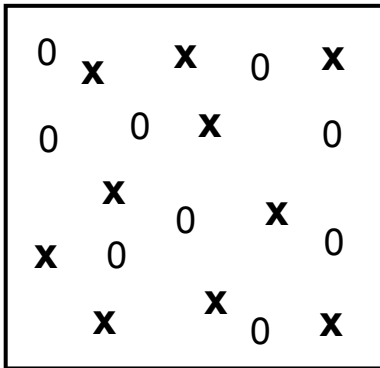
Introduction to Numerical Analysis for Engineers

- Systems of Linear Equations Mathews
 - Cramer's Rule
 - Gaussian Elimination 3.3–3.5
 - Numerical implementation
3.3–3.4
 - Numerical stability
 - Partial Pivoting
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 - Jacobi's method
 - Gauss–Seidel iteration
 - Convergence



Linear Systems of Equations Iterative Methods

Sparse, Full-bandwidth Systems



Rewrite Equations

$$\overline{\overline{\mathbf{A}}}\overline{\overline{\mathbf{x}}} = \overline{\overline{\mathbf{b}}} \Leftrightarrow \sum_{j=1}^n a_{ij}x_j = b_i$$

$$a_{ii} \neq 0 \Rightarrow x_i = \frac{b_i - \sum_{j=1}^{i-1} a_{ij}x_j - \sum_{j=i+1}^n a_{ij}x_j}{a_{ii}}, \quad i = 1, \dots, n$$

Iterative, Recursive Methods

Jacobi's Method

$$x_i^{(k+1)} = \frac{b_i - \sum_{j=1}^{i-1} a_{ij}x_j^{(k)} - \sum_{j=i+1}^n a_{ij}x_j^{(k)}}{a_{ii}}, \quad i = 1, \dots, n$$

Gauss-Seidel's Method

$$x_i^{(k+1)} = \frac{b_i - \sum_{j=1}^{i-1} a_{ij}x_j^{(k+1)} - \sum_{j=i+1}^n a_{ij}x_j^{(k)}}{a_{ii}}, \quad i = 1, \dots, n$$



Linear Systems of Equations

Iterative Methods

Convergence

$$\|\bar{\mathbf{x}}^{(k+1)} - \bar{\mathbf{x}}\| \rightarrow 0 \text{ for } k \rightarrow \infty$$

Iteration – Matrix form

$$\bar{\mathbf{x}}^{(k+1)} = \bar{\mathbf{B}}\bar{\mathbf{x}}^{(k)} + \bar{\mathbf{c}}, \quad k = 0, \dots$$

Decompose Coefficient Matrix

$$\bar{\mathbf{A}} = \bar{\mathbf{D}}(\bar{\mathbf{L}} + \bar{\mathbf{I}} + \bar{\mathbf{U}})$$

with

$$\bar{\mathbf{D}} = \text{diag } a_{ii}$$

$$\bar{\mathbf{L}} = \begin{cases} a_{ij}/a_{ii}, & i > j \\ 0, & i \leq j \end{cases}$$

$$\bar{\mathbf{U}} = \begin{cases} a_{ij}/a_{ii}, & i < j \\ 0, & i \geq j \end{cases}$$

Jacobi's Method

$$\bar{\mathbf{x}}^{(k+1)} = -(\bar{\mathbf{L}} + \bar{\mathbf{U}})\bar{\mathbf{x}}^{(k)} + \bar{\mathbf{D}}^{-1}\bar{\mathbf{b}}$$

Iteration Matrix form

$$\bar{\mathbf{B}} = -(\bar{\mathbf{L}} + \bar{\mathbf{U}})$$

$$\bar{\mathbf{c}} = \bar{\mathbf{D}}^{-1}\bar{\mathbf{b}}$$

Convergence Analysis

$$\bar{\mathbf{x}}^{(k+1)} = \bar{\mathbf{B}}\bar{\mathbf{x}}^{(k)} + \bar{\mathbf{c}}$$

$$\bar{\mathbf{x}} = \bar{\mathbf{B}}\bar{\mathbf{x}} + \bar{\mathbf{c}}$$

$$\begin{aligned} \bar{\mathbf{x}}^{(k+1)} - \bar{\mathbf{x}} &= \bar{\mathbf{B}}(\bar{\mathbf{x}}^{(k)} - \bar{\mathbf{x}}) \\ &= \bar{\mathbf{B}} \cdot \bar{\mathbf{B}}(\bar{\mathbf{x}}^{(k-1)} - \bar{\mathbf{x}}) \\ &\quad \cdot \\ &= \bar{\mathbf{B}}^{k+1}(\bar{\mathbf{x}}^{(0)} - \bar{\mathbf{x}}) \end{aligned}$$

$$\|\bar{\mathbf{x}}^{(k+1)} - \bar{\mathbf{x}}\| \leq \|\bar{\mathbf{B}}^{k+1}\| \|\bar{\mathbf{x}}^{(0)} - \bar{\mathbf{x}}\| \leq \|\bar{\mathbf{B}}\|^{k+1} \|\bar{\mathbf{x}}^{(0)} - \bar{\mathbf{x}}\|$$

Sufficient Convergence Condition

$$\|\bar{\mathbf{B}}\| < 1$$



Linear Systems of Equations

Iterative Methods

Sufficient Convergence Condition

$$\|\overline{\overline{\mathbf{B}}}\| < 1$$

Jacobi's Method

$$b_{ij} = -\frac{a_{ij}}{a_{ii}}, \quad i \neq j$$

$$\|\overline{\overline{\mathbf{B}}}\|_{\infty} = \max_i \sum_{j=1, j \neq i}^n \frac{|a_{ij}|}{|a_{ii}|}$$

Sufficient Convergence Condition

$$\sum_{j=1, j \neq i}^n |a_{ij}| < |a_{ii}|$$

Diagonal Dominance

Stop Criterion for Iteration

$$\begin{aligned} \overline{\mathbf{x}}^{(k)} - \overline{\mathbf{x}} &= \overline{\overline{\mathbf{B}}} (\overline{\mathbf{x}}^{(k-1)} - \overline{\mathbf{x}}) && \overline{\overline{\mathbf{B}}} \overline{\mathbf{x}}^{(k)} \\ &= -\overline{\overline{\mathbf{B}}} (\overline{\mathbf{x}}^{(k)} - \overline{\mathbf{x}}^{(k-1)}) + \overline{\overline{\mathbf{B}}} (\overline{\mathbf{x}}^{(k)} - \overline{\mathbf{x}}) \end{aligned}$$

$$\|\overline{\mathbf{x}}^{(k)} - \overline{\mathbf{x}}\| \leq \|\overline{\overline{\mathbf{B}}}\| \|\overline{\mathbf{x}}^{(k)} - \overline{\mathbf{x}}^{(k-1)}\| + \|\overline{\overline{\mathbf{B}}}\| \|\overline{\mathbf{x}}^{(k)} - \overline{\mathbf{x}}\|$$

$$\|\overline{\mathbf{x}}^{(k)} - \overline{\mathbf{x}}\| \leq \frac{\|\overline{\overline{\mathbf{B}}}\|}{1 - \|\overline{\overline{\mathbf{B}}}\|} \|\overline{\mathbf{x}}^{(k)} - \overline{\mathbf{x}}^{(k-1)}\|$$

$$\|\overline{\overline{\mathbf{B}}}\| < 1/2 \Rightarrow \|\overline{\mathbf{x}}^{(k)} - \overline{\mathbf{x}}\| \leq \|\overline{\mathbf{x}}^{(k)} - \overline{\mathbf{x}}^{(k-1)}\|$$



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```
n=99;
L=1.0;
h=L/(n+1);
k=2*pi;
kh=k*h
x=[h:h:L-h]';
a=zeros(n,n);
f=zeros(n,1);
o=1 ← Off-diagonal values

a(1,1) =kh^2 - 2;
a(1,2)=o;

for i=2:n-1
    a(i,i)=a(1,1);
    a(i,i-1) = o;
    a(i,i+1) = o;
end
a(n,n)=a(1,1);
a(n,n-1)=o;

nf=round((n+1)/3);
nw=round((n+1)/6);
nw=min(min(nw,nf-1),n-nf);
figure(1)
hold off

nw1=nf-nw;
nw2=nf+nw;
f(nw1:nw2) = h^2*hanning(nw2-nw1+1);
subplot(2,1,1); plot(x,f,'r');
% exact solution
y=inv(a)*f;
subplot(2,1,2); plot(x,y,'b');
```

```
% Iterative solution using Jacobi and Gauss-Seidel
b=-a;
c=zeros(n,1);
for i=1:n
    b(i,i)=0;
    for j=1:n
        b(i,j)=b(i,j)/a(i,i);
        c(i)=f(i)/a(i,i);
    end
end

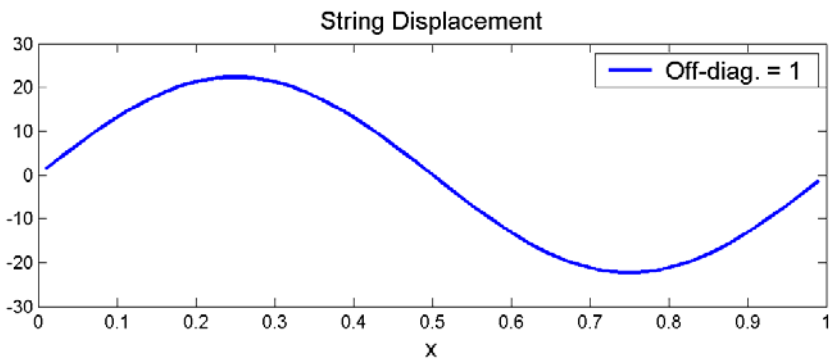
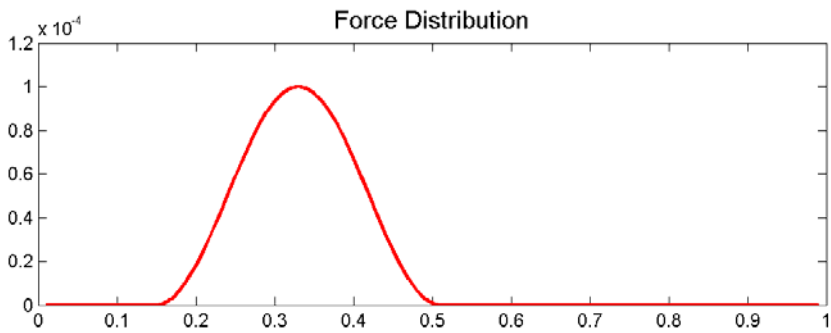
nj=100;
xj=f;
xgs=f;

figure(2)
nc=6
col=['r' 'g' 'b' 'c' 'm' 'y']
hold off
for j=1:nj
    xj=b*xj+c;
    xgs(1)=b(1,2:n)*xgs(2:n) + c(1);
    for i=2:n-1
        xgs(i)=b(i,1:i-1)*xgs(1:i-1) + b(i,i+1:n)*xgs(i+1:n) +c(i);
    end
    xgs(n)= b(n,1:n-1)*xgs(1:n-1) +c(n);
    cc=col(mod(j-1,nc)+1);
    subplot(2,1,1); plot(x,xj,cc); hold on;
    subplot(2,1,2); plot(x,xgs,cc); hold on;
end
end
```

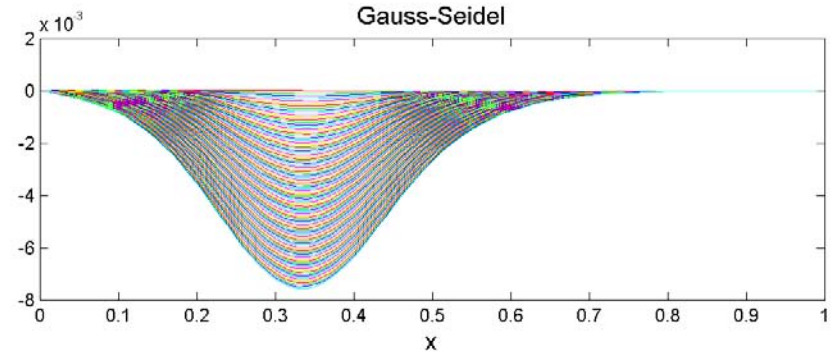
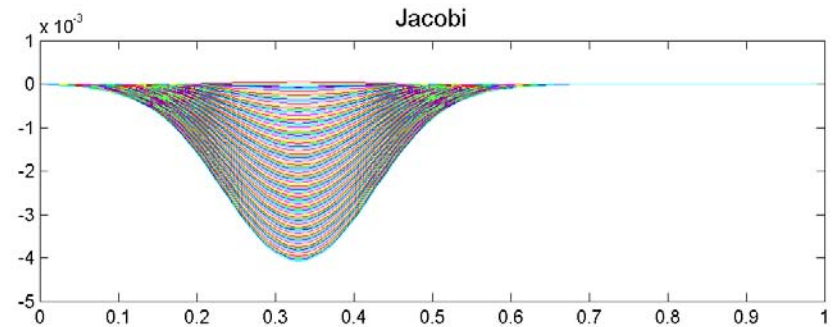


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Exact Solution



Iterative Solutions

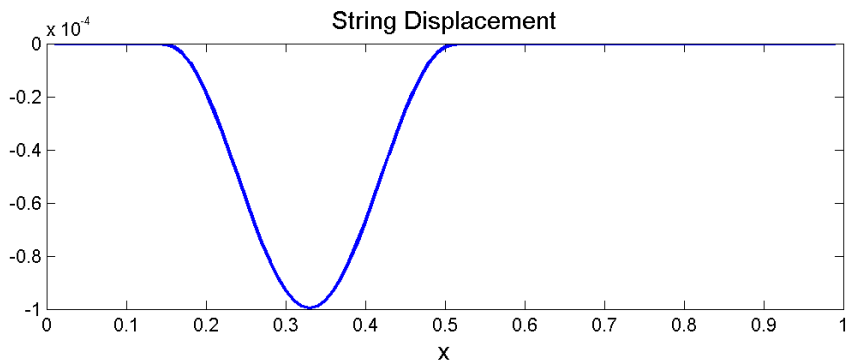
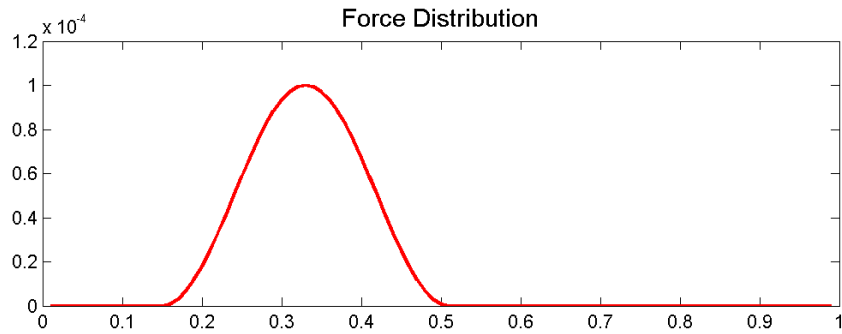




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$\alpha = 0.5$

Exact Solution



Iterative Solutions

