

Fall 2002 22.611J 6.657J, 8.613J  
PS#6 Answer Key

2. The quick way:

Laplace transform Poisson's equation:

$$\nabla^2 \phi = 4\pi \delta(\vec{x}) \Rightarrow k^2 \tilde{\phi} = 4\pi$$

$$\tilde{\phi} = \frac{4\pi}{k^2}$$

since  $\phi = \frac{1}{|\vec{x}|}$  for a pt. charge,

$\int d^3x e^{-i\vec{k}\cdot\vec{x}} \frac{1}{|\vec{x}|}$  is simply the transform of  $\phi$ ,  
which is  $\tilde{\phi} = \frac{4\pi}{k^2}$

Similarly,

$$\nabla \cdot \vec{E} = 4\pi \delta(\vec{x}) \Rightarrow -i\vec{k} \cdot \vec{E} = 4\pi \Rightarrow \vec{E} = \frac{4\pi i \vec{k}}{k^2}$$

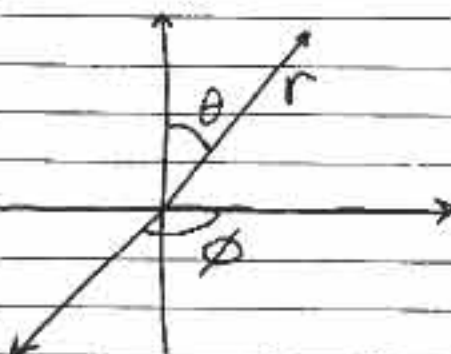
$$\text{But } \vec{E} = -\nabla \phi = -\frac{\partial}{\partial x} \frac{1}{|\vec{x}|}$$

hence,

$$\int d^3x e^{i\vec{k}\cdot\vec{x}} \frac{\partial}{\partial x} \frac{1}{|\vec{x}|} = \int d^3x e^{-i\vec{k}\cdot\vec{x}} \vec{E} = \frac{4\pi i \vec{k}}{k^2}$$

The "manly" direct integral way:

first, switch over to spherical coordinates



pick  $\vec{k} = k\hat{z}$  (we can always rotate our system)

$$dV = r^2 \sin\theta dr d\theta d\phi$$

$$\vec{k} \cdot \vec{x} = kr \cos\theta$$

1. (cont)

$$\int d^3x \frac{e^{-ik \cdot \vec{x}}}{2\pi |\vec{x}|} = \int_0^\infty \int_0^\pi \frac{r^2 \sin\theta e^{-ikr \cos\theta}}{r} dr d\theta 2\pi$$

Doing the  $\theta$  integral:

$$= 2\pi \int_0^\infty \int_0^\pi \frac{r e^{-ikr \cos\theta}}{+ikr} dr$$

$$= 2\pi \int_0^\infty \frac{e^{ikr} + e^{-ikr}}{ik} dr = \frac{2\pi}{ik} \int_0^\infty e^{ikr} - e^{-ikr} dr$$

→ Now, there's a few ways to resolve this integral. But let me try to do this the standard way first to illustrate the problem

$$\int_0^\infty e^{ikr} - e^{-ikr} dr = \int_0^\infty \frac{e^{ikr} + e^{-ikr}}{ik} = \frac{1}{ik} \int_0^\infty \cos(kr)$$

→ so our integral becomes undefined, since  $\cos(kr \rightarrow \infty) = ?$

→ why did this happen? This is because this transform is really an ill-posed

problem; it's well known that a  $\frac{1}{r}$  potential is divergent as  $r \rightarrow \infty$ .

Hence, when we did Coulomb scattering earlier, we truncated the integral to  $2D$  from  $\infty$ . (when we were determining the transport cross sections and characteristic times)

→ A better way to do this problem is to use a shielded potential (i.e. problem 2) and take a limit ...

$$\phi = \lim_{k_0 \rightarrow 0} \frac{1}{|\vec{x}|} e^{-|\vec{x}| k_0} \quad \left( \begin{array}{l} \text{I think this is} \\ \text{the most physical} \\ \text{interpretation} \end{array} \right)$$

Then, we've

$$\lim_{k_0 \rightarrow 0} \int_0^{\infty} \frac{(e^{ikr} - e^{-ikr})}{ik} e^{-k_0 r} dr$$

$$= \lim_{k_0 \rightarrow 0} 2\pi \int_0^{\infty} \frac{e^{ikr - k_0 r} - e^{-ikr - k_0 r}}{ik} dr$$

$$= \lim_{k_0 \rightarrow 0} \frac{2\pi}{ik} \left[ \frac{e^{i(k-k_0)r} - e^{-(i(k+k_0))r}}{i(k-k_0)} \right]$$

$$= \lim_{k_0 \rightarrow 0} \frac{2\pi}{ik} \left[ \frac{e^{i(k-k_0)r} - e^{-i(k+k_0)r}}{i(k-k_0)} - \frac{2}{i(k-k_0)} \right]$$

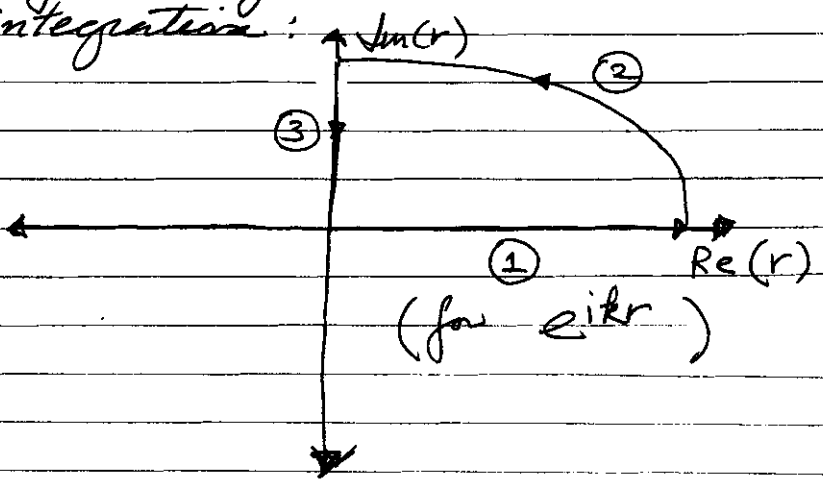
since  $e^{-k_0 r} \rightarrow 0$  for any finite  $k$ .

$$= \lim_{k_0 \rightarrow 0} \frac{2\pi \cdot (-2)}{ik(i(k-k_0))} =$$

$$\frac{4\pi}{k^2} = \int d^3x \frac{e^{-i\vec{k}\cdot\vec{x}}}{|\vec{x}|}$$

→ Another possible way of doing this is through contour integration:

$$\int_0^{\infty} (e^{ikr} - e^{-ikr}) dr \Rightarrow$$



So, for

$$\int_0^{\infty} e^{ikr} dr \text{ we've}$$

$$\int_1 + \int_2 + \int_3 = 0$$

Now, if  $\int_2$  equal zero (which is not completely obvious since Jordan's Lemma is for the full semi-circle)

then,  $\int_{\textcircled{1}} = -\int_{\textcircled{2}}$ ,  $\int_{\textcircled{3}}$

$$\int_0^{\infty} e^{ikr} dr = -\int_{i\infty}^0 e^{ikr} dr = + \int_0^{i\infty} \frac{e^{ikr}}{ik}$$

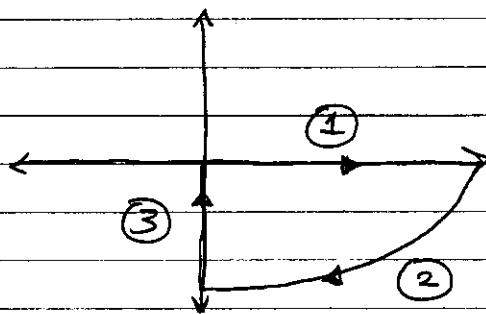
$$= + \frac{e^{ikr}}{ik} \Big|_0^{i\infty} = -\frac{1}{ik}$$

Similarly, for  $\int e^{-ikr} dr$

$$\int_{\textcircled{1}} = -\int_{\textcircled{2}} \text{ as before}$$

$$\int_0^{\infty} e^{-ikr} dr = -\int_0^{-i\infty} e^{-ikr} dr$$

$$= + \int_{-i\infty}^0 \frac{e^{-ikr}}{-ik} = + \left[ \frac{1}{-ik} + \frac{e^{-ikr}}{-ik} \Big|_{-i\infty}^0 \right] = -\frac{1}{ik}$$



hence,

$$\int_0^{\infty} (e^{ikr} - e^{-ikr}) dr \rightarrow \frac{-2}{ik}$$

which is what we needed to get the  $\frac{4\pi}{k^2}$  answer.

→ Finally, a way that is related to the first method is to simply plug in a  $e^{-sr}$ :

$$\int_0^{\infty} (e^{ikr} - e^{-ikr}) \cdot \lim_{s \rightarrow 0} e^{-sr} dr, \text{ which is the same as using a shielded potential and taking the limit; however, starting w/ a shielded potential gives a more physical picture.}$$

$$= 1 \text{ at limit}$$

$$\Rightarrow \lim_{s \rightarrow 0} \int_0^{\infty} (e^{ikr} - e^{-ikr}) e^{-sr} dr$$

1) the hard way for

$$\int d^3x e^{-i\vec{k}\cdot\vec{x}} \left( \hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \frac{1}{|\vec{x}|}$$

using integration by parts,

$$\int dx e^{-i\vec{k}\cdot\vec{x}} \hat{i} \frac{\partial}{\partial x} \frac{1}{|\vec{x}|} \quad \text{for the } x\text{-component.}$$

Note:  
 $\hat{i}$  is the unit x vector  
 $\hat{i}$  is  $\sqrt{1}$

$$\text{IBP: } \int u dv = uv - \int v du$$

$$\text{let } \frac{dv}{dx} = \frac{\partial}{\partial x} \frac{1}{|\vec{x}|}, \quad v = \frac{1}{|\vec{x}|}$$

$$\frac{du}{dx} = -ik_x e^{-i\vec{k}\cdot\vec{x}} \quad u = e^{-i\vec{k}\cdot\vec{x}}$$

then,

$$\Rightarrow \int dx e^{-i\vec{k}\cdot\vec{x}} \hat{i} \frac{\partial}{\partial x} \frac{1}{|\vec{x}|} = \hat{i} \int_{-\infty}^{\infty} \frac{e^{-i\vec{k}\cdot\vec{x}}}{|\vec{x}|} + \hat{j} \int_{-\infty}^{\infty} \frac{ik_x e^{-i\vec{k}\cdot\vec{x}}}{|\vec{x}|} dx$$

Doing the same w/ the y & z components,  
 we get:

$$\int d^3x e^{-i\vec{k}\cdot\vec{x}} \vec{\nabla} \frac{1}{|\vec{x}|} = (\hat{i}k_x + \hat{j}k_y + \hat{k}k_z) \int_{-\infty}^{\infty} \frac{e^{-i\vec{k}\cdot\vec{x}}}{|\vec{x}|} dx$$

$$\text{from above, } \int_{-\infty}^{\infty} \frac{e^{-i\vec{k}\cdot\vec{x}}}{|\vec{x}|} dx = \frac{4\pi}{k^2}$$

$$\boxed{\int d^3x e^{-i\vec{k}\cdot\vec{x}} \frac{\partial}{\partial x} \frac{1}{|\vec{x}|} = i\vec{k} \frac{4\pi}{k^2}}$$

2) First, we see that  $f(\bar{x})$  is the inverse ~~to~~ fourier transform of  $\frac{4\pi}{k^2+k_0^2}$

Now, from part one, we see that this is very similar to Poisson's equation. Hence, try

$$\tilde{\phi} = \frac{4\pi}{k^2+k_0^2}$$

$$(k^2+k_0^2)\tilde{\phi} = 4\pi$$

Inverting,

$$(\nabla^2 + k_0^2)\phi = 4\pi\delta(\bar{x})$$

$$\nabla^2\phi + k_0^2\phi = 4\pi\delta(\bar{x})$$

which is the equation for Debye shielding! (i.e. the potential of a shielded charge)

$$\text{w/ } \lambda_D^2 = \frac{1}{k_0^2}$$

$$f(\bar{x}) = \phi = \phi_0 e^{\left(\frac{-|\bar{x}|k_0}{1}\right)} = \frac{e^{(-|\bar{x}|k_0)}}{|\bar{x}|}$$


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### 3) Maxwellian Distribution from Entropy Maximization:

From "Mathematical Methods for Physicists," Arfken & Weber 4th ed.

If we've a function  $J$ , such that

$$J = \int f(y_i, \frac{\partial y_i}{\partial x_j}, x_j) dx_j,$$

where  $x_j$ 's are the independent variables, and  $y_i$ 's the dependent variables, and we wish to find  $\delta J = 0$  w/ the following constraints,

$$\int \psi_k(y_i, \partial y_i / \partial x_j, x_j) dx_j = \text{constant},$$

we've to solve the Euler-Lagrange equations:

$$\frac{\partial g}{\partial y_i} - \sum_j \frac{\partial}{\partial x_j} \frac{\partial g}{\partial (\partial y_i / \partial x_j)} = 0 \quad \text{(A)}$$

where  $g(y_i, \frac{\partial y_i}{\partial x_j}, x_j) = f + \sum_k \lambda_k \psi_k$   
and  $\lambda_k$  are constants.

In our case, we've

$$g = -f \ln f + \alpha f + \beta \frac{1}{2} m v^2 f \quad \text{(B)}$$

where our  $f$  correspond to  $y_i$  above, and  $v_x, v_y, v_z \leftrightarrow x_j$ . We've no dependence on  $\frac{\partial y_i}{\partial x_j}$  for  $g$ .

hence,

Plugging  $(B) \rightarrow (A)$  we've

$$\frac{\partial}{\partial f} (-f \ln f + \alpha f + \beta \frac{1}{2} m v^2 f) = 0$$

$$-(\ln f + 1) + \alpha + \beta \frac{1}{2} m v^2 = 0$$

$$\ln f + 1 = \alpha + \beta \frac{1}{2} m v^2$$

$$\ln f = -1 + \alpha + \beta \frac{1}{2} m v^2$$

$$f = e^{\alpha-1} e^{\beta \frac{1}{2} m v^2}$$

which looks very much like the Maxwell distribution!

→ Now, use constraints to determine  $\alpha$  and  $\beta$

$$N = \int d^3v e^{\alpha-1} e^{\beta \frac{1}{2} m v^2}$$

$$= e^{\alpha-1} 4\pi \int_0^{\infty} v^2 e^{\beta \frac{1}{2} m v^2} dv \quad (\text{spherical coordinates})$$

$$= e^{\alpha-1} 4\pi \left( \frac{\Gamma(\frac{3}{2})}{2 \left(-\frac{m\beta}{2}\right)^{3/2}} \right)$$

$$= e^{\alpha-1} 4\pi \frac{\sqrt{\pi}}{2} \left(\frac{1}{2}\right) \left(-\frac{2}{m\beta}\right)^{3/2}$$

$$N = e^{\alpha-1} \left(-\frac{2\pi}{m\beta}\right)^{3/2}$$



Now, for E:

$$E = \int d^3v \frac{1}{2} m v^2 f = \int d^3v \frac{m v^2}{2} (e^{\alpha-1} e^{\frac{\beta m}{2} v^2})$$

$$= 4\pi e^{\alpha-1} \frac{m}{2} \int_0^\infty v^4 e^{\frac{\beta m}{2} v^2} dv$$

$$= 2\pi e^{\alpha-1} m \left( \frac{\Gamma(5/2)}{2 \left(-\frac{m\beta}{2}\right)^{5/2}} \right)$$

$$= \pi e^{\alpha-1} m \left( \frac{3(\pi)^{1/2}}{4} \left(-\frac{2}{m\beta}\right)^{5/2} \right)$$

$$E = \frac{3}{4} \pi^{3/2} e^{\alpha-1} m \left(-\frac{2}{m\beta}\right)^{5/2}$$

Now, we've two eqn's for  $\alpha$  &  $\beta$ .

Divide

$$\frac{N}{E} = \frac{\pi^{3/2}}{\frac{3}{4} \pi^{3/2} m} \left(-\frac{m\beta}{2}\right) = -\frac{2\beta}{3\pi^{3/2}}$$

$$\boxed{\beta = -\frac{3N}{2E}}$$

$$N = e^{\alpha-1} \left(-\frac{2\pi}{m\beta}\right)^{3/2}$$

$$N = e^{\alpha-1} \left(\frac{+2\pi 2E}{m 3N}\right)^{3/2}$$

$$N^{5/2} = e^{\alpha-1} \left(\frac{\pi 4E}{3m}\right)^{3/2}$$

$$\left(\frac{3m}{\pi 4E}\right)^{3/2} N^{5/2} = e^{\alpha-1}$$

OR,

$$\ln \left[ \left(\frac{3m}{4E\pi}\right)^{3/2} N^{5/2} \right] + 1 = \alpha$$

hence,

$$f = \left(\frac{3m}{4E\pi}\right)^{3/2} N^{5/2} e^{-\frac{3N}{2E} \cdot \frac{1}{2} m v^2}$$

defining  $E = \frac{3}{2} N T$

$$f = \left(\frac{m}{2T\pi}\right)^{3/2} N e^{-\frac{m v^2}{2T}}$$

which is the Maxwellian distribution.

→ FYI; normally  $f$  is derived through Boltzmann's H theorem, which is related to the collision operator.

4) The Vlasov equation is:

$$\frac{df}{dt} = 0,$$

$$\Rightarrow \frac{\partial f}{\partial t} + \vec{a} \cdot \vec{\nabla}_v f + \vec{v} \cdot \vec{\nabla} f = 0$$

$$\vec{a} = \frac{q}{m} (\vec{E} + \vec{v} \times \vec{B})$$

Letting  $q \rightarrow \frac{q}{N}$ ,  $m \rightarrow \frac{m}{N}$  &  $n \rightarrow Nn$

$$\frac{N \partial f}{\partial t} + \frac{N q}{N m} (\vec{E} + \vec{v} \times \vec{B}) \cdot \vec{\nabla}_v N f + \vec{v} \cdot \vec{\nabla} N f = 0$$

$\rightarrow$  all the  $N$ 's divide out  $\rightarrow$  hence, Vlasov remains invariant under transformation

$\rightarrow$  Furthermore, the parameter  $\frac{1}{n \lambda_D^3}$  does not!

$$\Rightarrow \frac{1}{n \lambda_D^3} \propto \frac{1}{n \left(\frac{1}{n q^2}\right)^{3/2}} \propto n^{1/2} q^2$$

$$\text{letting } n^{1/2} \rightarrow (Nn)^{1/2}, \quad q^2 \rightarrow \left(\frac{q}{N}\right)^2$$

$$\frac{1}{n \lambda_D^3} \Rightarrow \frac{(Nn)^{1/2} \frac{q^2}{N^2}}{N^{3/2}} = \frac{n^{1/2} q^2}{N^{3/2}} \Rightarrow 0 \text{ when } N \rightarrow \infty$$

Hence,  $\frac{1}{n \lambda_D^3}$  is not invariant.

How does this discreteness parameter relate to the Vlasov equation?

In general,  $\frac{df}{dt} = C$ , where  $C$  is a collision operator.

$$C = C\left(\frac{1}{n \lambda_D^3}\right), \text{ which means that as } N \rightarrow 0, C \Rightarrow C = 0.$$

$\rightarrow$  Hence, in the limit of 0 discreteness, the Vlasov equation,  $\frac{df}{dt} = 0$ , is exact!

$\rightarrow$  In ~~other~~ other words, no particles/discreteness, no collisions!

### 5) Final Value theorem Proof:

We know

$$\begin{aligned} \mathcal{L}(g'(t)) &= -i\omega \mathcal{L}(g(t)) - g(t=0) \\ &= -i\omega g_\omega - g(t=0) \end{aligned}$$

By definition,

$$\mathcal{L}(g'(t)) = \int_0^\infty dt e^{i\omega t} g'(t)$$

Setting  $\omega \rightarrow 0$ ,

$$\begin{aligned} \mathcal{L}(g'(t)) &= \int_0^\infty dt \frac{dg(t)}{dt} \\ &= \int_0^\infty g(t) \\ &= \lim_{t \rightarrow \infty} g(t) - g(t=0) \end{aligned}$$

hence,

$$\lim_{\omega \rightarrow 0} (-i\omega g_\omega) - g(t=0) = \lim_{t \rightarrow \infty} g(t) - g(t=0)$$

$$\lim_{\omega \rightarrow 0} (-i\omega g_\omega) = \lim_{t \rightarrow \infty} g(t)$$

- Stable in this case means NO Poles above  $\text{Im}(\omega) = 0$ , and  $\omega_r \rightarrow 0$  as  $t \rightarrow \infty$
- the system ~~does~~ goes to 0 at  $t \rightarrow \infty$ .
- for systems that oscillate indefinitely,

$$\lim_{t \rightarrow \infty} g(t) = \lim_{\omega_r \rightarrow \text{constant}} (-i\omega g_\omega)$$

(Note that  $\omega_r$  still has to be below negative)