

Massachusetts Institute of Technology
Department of Physics

Physics 8.01L

SAMPLE FINAL EXAM

SOLUTIONS

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Problem 1

a) $V = \frac{NkT}{P}$, $V_{NEW} = \frac{Nk\frac{T}{3}}{\frac{P}{10}} = \frac{10}{3} \frac{NkT}{P}$, $\Rightarrow V$ goes up

b) (i) $F = mg = 8(10) = \boxed{80N}$

(ii) $F_{Buoy} = (1000)(.002)(10) = 20N$,

$\therefore F = 80 - 20 = \boxed{60N}$

c) Velocity goes down, pressure goes up.

Problem 2

a) Equilibrium, so $F_{Buoyant} - w = 0 \Rightarrow F_B = w$.

$F_B = V_f \rho_f g = (\pi r^2 d) \rho g = w$, $d = \frac{w}{\pi r^2 \rho g}$

b) $F_{TOT} = Ma = F_B - w$, $F_B = \pi r^2 \left(\frac{d}{2}\right) \rho g = d \left(\frac{\pi r^2 \rho g}{2}\right)$

From (a), $d = \frac{w}{\pi r^2 \rho g} \Rightarrow F_B = \frac{w}{\pi r^2 \rho g} \left(\frac{\pi r^2 \rho g}{2}\right) = \frac{w}{2}$

Half as deep \Rightarrow half as large buoyancy force.

$F_{TOT} = Ma = \frac{w}{2} - w = -\frac{w}{2}$, $a = \frac{-w}{2m}$, but $w = Mg$.

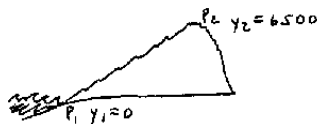
$\Rightarrow a = \frac{-g}{2}$, accelerating downward at $\frac{g}{2}$.

Problem 3

a) $P + \rho g y = \text{constant}$, $P_1 + \rho g(0) = P_2 + \rho g(6500)$

$P_2 = P_1 - \rho g(y_2) = 1.013 \times 10^5 - (0.95)(9.8)(6500)$,

$P_2 = 4.08 \times 10^4 N/m^2 = 0.40 \text{ atm}$

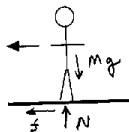


b) $N = \text{const}$, $V = \text{const}$, $PV = NkT$

$\Rightarrow \frac{P_1}{T_1} = \frac{P_2}{T_2}$, $T_1 = 293$, $P_1 = 1.5 \times 10^7$, $T_2 = 253$, $P_2 = \frac{P_1 T_2}{T_1} = 1.30 \times 10^7 N/m^2$

Problem 4

ii) f exerts torque around center of mass, so you fall over.

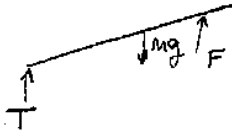


iii) Now N exerts torque which can balance torque due to friction.



Problem 5

a)



b) Take torques around toes: $MgL \cos(\theta) - F(\frac{4L}{3}) \cos(\theta) = 0$, $F = \frac{3}{4}Mg$

c) $T + F = Mg$, $T = \frac{1}{4}Mg$.

Problem 6

a) $3Mg + Mg = 4Mg$.

b) Take torques about left end: $4MgD - LMg = 0$, $D = \frac{L}{4}$.

Check torque around weight: $0 = D(3Mg) - Mg(L - D)$, $D(4Mg) = MgL$, $D = \frac{L}{4}$.

Problem 7

a)



b) $\sum F_x = N_2 + N_1 \sin(\theta) - f_1 \cos(\theta) = 0$
 $\sum F_y = f_2 - Mg + N_1 \cos(\theta) + f_1 \sin(\theta) = 0$

c) $\sum \tau = Mg(\frac{L}{2} \cos(\theta)) - N_1 L = 0$.

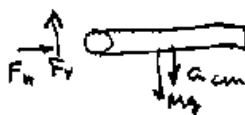
d) $\sum \tau = N_2 L \sin(\theta) + f_2 L \cos(\theta) - Mg \frac{L}{2} \cos(\theta) = 0$.

Problem 8

a) $\tau = I\alpha$, take torques about hinge.

$(Mg)(\frac{L}{2})(\sin(90^\circ)) = (\frac{ML^2}{3})(\alpha) \Rightarrow \alpha = \frac{\frac{gL}{2}}{\frac{L^2}{3}} = \frac{3g}{2L}$, $\alpha = \frac{3g}{2L}$

b)



$$F = Ma_{cm}, \quad a_{cm} = \alpha\left(\frac{L}{2}\right), \text{ downward.}$$

$$\text{All forces and acceleration are vertical} \Rightarrow \boxed{F_H = 0}.$$

$$F_V - Mg = -Ma = -M\alpha\left(\frac{L}{2}\right) = -M\left(\frac{3g}{2L}\right)\left(\frac{L}{2}\right) = \frac{-3Mg}{4}$$

$$F_V = Mg - \frac{3Mg}{4} \Rightarrow \boxed{F_V = \frac{Mg}{4}}, \quad \boxed{F_{TOT} = \frac{Mg}{4}, \text{ up.}}$$

c) Used fixed pivot:



$$KE_I = 0, \quad PE_I = MgL, \quad KE_F = \frac{1}{2}I_{end}\omega^2, \quad PE_F = Mg\left(\frac{L}{2}\right), \quad \text{Work} = 0.$$

$$\frac{1}{2}\left(\frac{ML^2}{3}\right)\omega^2 + Mg\frac{L}{2} = MgL, \quad \frac{ML^2\omega^2}{6} = \frac{MgL}{2}, \quad \boxed{\omega^2 = \frac{3g}{L} \text{ or } \omega = \sqrt{\frac{3g}{L}}}.$$

Used center of mass:

$$KE_I = 0, \quad KE_F = \frac{1}{2}Mv_{CM}^2 + \frac{1}{2}I_{CM}\omega^2, \quad v_{CM} = \omega\left(\frac{L}{2}\right)$$

$$KE_F = \frac{1}{2}M\left(\frac{L}{2}\right)^2\omega^2 + \frac{1}{2}\left(\frac{ML^2}{12}\right)\omega^2 = ML^2\omega^2\left(\frac{1}{8} + \frac{1}{24}\right) = ML^2\omega^2\left(\frac{3}{24} + \frac{1}{24}\right) = ML^2\omega^2\left(\frac{1}{6}\right) \Rightarrow \text{Same answer.}$$

Problem 9

a) L is conserved: $mvR = (I_0 + mR^2)\omega_f$

$$\boxed{\omega_f = \frac{mvR}{I_0 + mR^2}}$$

b) $KE_I = \frac{1}{2}mv^2$, $KE_F = \frac{1}{2}(I_0 + mR^2)\left(\frac{mvR}{I_0 + mR^2}\right)^2 = \frac{1}{2}\left(\frac{m^2v^2R^2}{I_0 + mR^2}\right)$

$$\boxed{\frac{KE_F}{KE_I} = \frac{mR^2}{I_0 + mR^2}}$$

Problem 10

a) Left

b) Yes, gravity.

c) Out of the page; Counter-clockwise.

d) Yes, pivot force.

e) Out of the page; Counter-clockwise.

f) Out of the page.

Problem 11

Take clockwise to be positive. Angular momentum is conserved: $I\omega_I - mv_I d = I\omega_f + mv_f d$

$$0.30(\omega) - 0.15(50)(0.8) = 0.3(0.35\omega) + 0.15(40)(0.8)$$

$$0.20\omega = 6 + 4.8 \Rightarrow \boxed{\omega = 54 \text{ rad/s}}. \quad \text{Period} = 0.12 \text{ sec.}$$