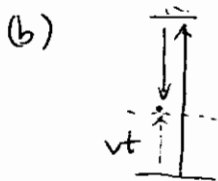


$$\left(\frac{ct}{2}\right)^2 = d^2 + \left(\frac{vt}{2}\right)^2 \Rightarrow \boxed{t = \frac{2d}{c} \frac{1}{\sqrt{1-v^2/c^2}} = \frac{2d}{c} \gamma}$$



$$t = \frac{d'}{c-v} + \frac{d'}{c+v} \quad d' \rightarrow \text{contracted length } d' = \frac{d}{\gamma}$$

$$\boxed{= \frac{2d'}{c} \gamma^2 = \frac{2d}{c} \gamma}$$

2. Use the identity $(1-\beta_1^2)(1-\beta_2^2) = (1+\beta_1\beta_2)^2 \left[1 - \left(\frac{\beta_1+\beta_2}{1+\beta_1\beta_2}\right)^2\right]$

3. In instantaneous rest frame, the rocket's velocity changes from 0 to $g d\tau$ ($d\tau$ - proper time)
 In the earth's reference frame, this velocity change is from v to $\frac{v+g d\tau}{1+\frac{vg d\tau}{c^2}} \approx v + g d\tau (1 - \frac{v^2}{c^2})$
 during a time interval $dt = \frac{d\tau}{\sqrt{1-v^2/c^2}}$

Therefore in the earth's reference frame: $\frac{dv}{dt} = g \left(1 - \frac{v^2}{c^2}\right)^{3/2}, \quad v|_{t=0} = 0$

This produces $v = \frac{gt/c^0}{\sqrt{\left(\frac{gt}{c^0}\right)^2 + 1}} \cdot c \Rightarrow \boxed{t = \frac{c^0}{g} \sinh \frac{g\tau}{c^0}}$

$x = \int_0^t v dt = \frac{c^2}{g} \left(\sqrt{1 + \frac{g^2 t^2}{c^2}} - 1 \right)$ these are results for the first 5- yrs in the rocket's frame

By the time the rocket returns, the earth's year will be year 2355, and the rocket will travel to a distance as far as 173 light years away from the earth.

4. See the discussion on light cone in Jackson/other texts.

(a) if $T \ll d/c$, handicap can be eliminated by switching to a reference frame moving along y direction at a speed $v = c^2 T/d$. If $T \gg d/c$ this is impossible.

(b) the y -coordinate of the runner in the new frame will be Lorentz-contracted by $\sqrt{1-v^2/c^2}$ while the starting time will be the same.

5. The equation of motion is

$$m \frac{d^2 \vec{r}}{dt^2} = e \left(\vec{E} + \frac{\vec{v}}{c} \times \vec{B} \right)$$

This should be derivable from both Lagrangian and Hamiltonian approaches

6.
$$\frac{d}{dt} \left(\frac{m \dot{\vec{r}}}{\sqrt{1 - \frac{\dot{\vec{r}}^2}{c^2}}} \right) = e \left(\vec{E} + \frac{\vec{v}}{c} \times \vec{B} \right)$$

7. b). from $\frac{d\vec{p}}{dt} = e\vec{E} \Rightarrow \vec{p} = e\vec{E}t = \frac{m_0 \dot{\vec{r}}}{\sqrt{1 - \frac{\dot{\vec{r}}^2}{c^2}}}$

$$\Rightarrow \begin{cases} \vec{r} = \frac{c\vec{E}}{eE^2} \left(\sqrt{m_0^2 c^2 + e^2 E^2 t^2} - m_0 c \right) \\ t = \frac{m_0 c}{eE} \sinh \left(\frac{eE}{m_0 c} \tau \right) \end{cases}$$