

I Systems Microbiology (13 Lectures)

'The cell as a well-stirred biochemical reactor'

- L1 Introduction
- L2 Chemical kinetics, Equilibrium binding, cooperativity
- L3 Lambda phage
- L4 Stability analysis
- L5-6 Genetic switches
- L7-9 *E. coli* chemotaxis
- L10-11 Genetic oscillators
- L12-13 Stochastic chemical kinetics

II Systems Cell Biology (9 Lectures)

'The cell as a compartmentalized system with concentration gradients'

- L15 Diffusion, Fick's equations, boundary and initial conditions
- L16-17 Local excitation, global inhibition theory
- L18-19 Models for eukaryotic gradient sensing
- L20-21 Center finding algorithms
- L22-23 Modeling cytoskeleton dynamics

III Systems Developmental Biology (2 Lectures)

'The cell in a social context communicating with neighboring cells'

- L23 Quorum sensing
- L25 Drosophila development

Main take home messages from this course:

- 1. translate the biology into a quantitative model:**
given the biology set up the coupled differential equations that capture the essence of the biological phenomena
(not trivial since 4 papers came up with a different model given the same biological phenomenon, which assumptions to make is critical)
- 2. analysis of the system of differential equations**
stability analysis (both in space and time)
- 3. interpretation of the mathematical analysis, what are the biological conclusions ?**
e.g. if the imaginary part of the eigenvalue is non zero, what does this mean for the underlying biology?
- 4. develop a taste for the potential of these systems approaches for biological problems that you may encounter in the future**

Developmental Systems Biology

‘Building an organism
starting from a single cell’

Introducing: *Drosophila melanogaster*
(or the fruitfly)

Great book: ‘The making of the fly’ by
Peter Lawrence

major advantage of
Drosophila:

each stripe in the
embryo corresponds
to certain body parts
in adult fly

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MOVIE !

<http://flymove.uni-muenster.de>

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Pioneering experiments by Klaus Sander (1958) on leaf-hoppers

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ligation and transplantation
experiments indicate the presence
of morphogens created/destroyed at
the poles of the embryo

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First morphogen:
bicoid (true maternal)

transplantation of bicoid
can rescue cells

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head fold shift to
right for increasing
number of gene copies
in mother

interpreting the bicoid gradient (created by maternal effects) by zygotic effect (gene expression by embryo itself)

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**hunchback reads
the bicoid gradient**

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recent experimental paper explores relation
between bicoid and hunchback quantitatively:

Houchmandzadeh et al. Nature 415, 798 (2002).

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**How can you make a steep step in hunchback
exactly in the middle of the embryo from
a noisy bicoid gradient ?**

Nobody knows ...

Second example:

Robustness of Drosophila patterning
Eldar et al., Nature **419**, 304 (2002)

remember robustness of chemotaxis (L9-10):

Image removed due to copyright considerations.

explore robustness in *Drosophila* patterning

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main molecules of interest:

Scw: BMP (bone morphogenic protein) ligand

Sog: a BMP inhibitor

Tld: protease (cleaves Sog)

simple reaction-diffusion model:

$$\frac{\partial[Sog]}{\partial t} = D_s \frac{\partial^2[Sog]}{\partial x^2} - k_b[Sog][Scw] + k_{-b}[Sog - Scw] - \alpha[Tld][Sog]$$

$$\frac{\partial[Scw]}{\partial t} = D_{BMP} \frac{\partial^2[Scw]}{\partial x^2} - k_b[Sog][Scw] + k_{-b}[Sog - Scw] + \lambda[Tld][Sog - Scw]$$

$$\frac{\partial[Sog - Scw]}{\partial t} = D_c \frac{\partial^2[Sog - Scw]}{\partial x^2} + k_b[Sog][Scw] - k_{-b}[Sog - Scw] - \lambda[Tld][Sog - Scw]$$

what does this mean ?

robustness analysis

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$$\frac{\partial[Sog]}{\partial t} = D_s \frac{\partial^2[Sog]}{\partial x^2} - k_b[Sog][Scw] + k_{-b}[Sog - Scw] - \alpha[Tld][Sog]$$

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$$\frac{\partial[Sog - Scw]}{\partial t} = D_c \frac{\partial^2[Sog - Scw]}{\partial x^2} + k_b[Sog][Scw] - k_{-b}[Sog - Scw] - \lambda[Tld][Sog - Scw]$$

why robust, ideal model: $D_{BMP}=0$, $\alpha=0$, $k_{-b}=0$

$$0 = D_s \frac{\partial^2[Sog]}{\partial x^2} - k_b[Sog][Scw]$$

$$0 = 0 - k_b[Sog][Scw] + \lambda[Tld][Sog - Scw] \longrightarrow \frac{\partial^2}{\partial x^2} \frac{1}{[Scw]} = \frac{k_b}{D_s}$$

$$0 = D_c \frac{\partial^2[Sog - Scw]}{\partial x^2} + k_b[Sog][Scw] - \lambda[Tld][Sog - Scw]$$